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# Identification of spatial and temporal contributions of rainfalls to flash floods using neural network modelling: case study on the Lez Basin (Southern France)

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HESSD

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



## Abstract

Flash floods pose significant hazards in urbanised zones and have important human and financial implications in both the present and future due to the likelihood that global climate change will exacerbate their consequences. It is thus of crucial importance to better model these phenomena especially when they occur in heterogeneous and karst basins where they are difficult to describe physically. Toward this goal, this paper applies a recent methodology (KnoX methodology) dedicated to extracting knowledge from a neural network model to better determine the contributions and time responses of several well-identified geographic zones of an aquifer. To assess the interest of this methodology, a case study was conducted in Southern France: the Lez hydrosystem whose river crosses the conurbation of Montpellier (400 000 inhabitants). Rainfall contributions and time transfers were estimated and analysed in four geologically-delimited zones to estimate the sensitivity of flash floods to water coming from the surface or karst. The Causse de Viol-le-Fort is shown to be the main contributor to flash floods and the delay between surface and underground flooding is estimated to be three hours. This study will thus help operational flood warning services to better characterise critical rainfall and develop measurements to design efficient flood forecasting models. This generic method can be applied to any basin with sufficient rainfall–runoff measurements.

## 1 Introduction

Flash floods are rapid (they rise in a few hours) and intense floods that occur within small basins. Our current lack of understanding of these floods constitutes a great societal challenge because of their socioeconomic and environmental impacts (Gaume and Bouvier, 2004; Llasat et al., 2010). Over the past 20 years, flash flooding in south-eastern France has caused more than 100 fatalities and several billion euros in property damage. In karst basins, the event of June 2010, in the Var (Southern France)

**HESSD**

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



caused 27 casualties and more than one billion euros of damages. Early warning is also a priority (Borga et al., 2011; Price et al., 2011) that could be improved by using forecast models. In recent decades, considerable efforts have been devoted to improving our understanding and forecasting of flash flooding (Gaume et al., 2009; Marchi et al., 2010). In the literature three aspects were investigated: (i) the rain event (or other cause of rising water), (ii) runoff genesis, and (iii) surface and underground geomorphologic and geologic settings that channel the water transfer toward the outlet.

Mediterranean rain events often occur at the meso-scale (Rivrain, 1997) and generate intense localised rainfall. For this reason, Le Lay and Saulnier (2007), Cosandey and Robinson (2000) and Tramblay et al. (2010) show that flash flood generation is controlled by spatial and temporal variability of rainfall and initial soil moisture conditions. Moreover, sensitivity to rainfall heterogeneity is elevated in small watersheds, which are locations of flash flooding (Krajewski et al., 1991; Corradini and Singh, 1985; Raynaud et al., 2015). The hydrodynamic behaviour of hydrosystems subject to intense rain events depends on soil moisture as well as geology, tectonics, and land use (Ancitil et al., 2008; Nikolopoulos et al., 2011). Moisture content estimation at the watershed scale has proven beneficial for discharge prediction (Kitanidis and Bras, 1980; Parajka et al., 2006; Wooldridge et al., 2003). Nevertheless, soil moisture measurements are highly dependent on field measurement techniques; they provide relative spatial and temporal distributions (Katul et al., 2007; Lauzon et al., 2004) rather than absolute values.

In karst systems, underground water obviously plays a significant role in flooding (Bailly-Comte et al., 2009, 2012; Fleury et al., 2013). Nevertheless, karst systems are intrinsically heterogeneous and their hydrodynamic behaviour generally differs from one system to another (Bakalowicz, 2005). However even if the contribution of karst groundwater to flash flooding is assumed to be negligible because of its longer response time (Borga et al., 2007; Norbiato et al., 2008), other studies emphasize the considerable contribution of groundwater to flash flooding (Bailly-Comte et al., 2012). Faced with the question of the role of karst groundwater in flash flooding, this study

**Spatial and temporal contributions of rainfalls**

T. Darras et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

investigates a method for estimating spatialized contributions from different parts of a heterogeneous aquifer.

Because of the lack of knowledge regarding the various hydrodynamic behaviours involved in karst systems, a generic blackbox method seems to be adequate. For this reason, neural network modelling seems to be a relevant method (Kong-A-Siou et al., 2011; Kong-A-Siou et al., 2014; Kurtulus and Razack, 2007). For this purpose, in recent decades, the multilayer perceptron has been increasingly used in the field of hydrology (Maier and Dandy, 2000; Toth, 2011). These models have been effective in identifying the rainfall–runoff relationship (Hsu et al., 1995). Their ability to forecast flash floods (Toukourou et al., 2011; Artigue et al., 2012) and model karst system behaviour have also been demonstrated (Kong-A-Siou et al., 2011). To model hydrosystem behaviour efficiently, neural networks need relevant datasets as input and output variables, and rigorous application of regularisation methods (Abrahart and See, 2007; Bowden et al., 2005; Fernando et al., 2009). Rainfall data are obvious inputs; in addition (Anctil et al., 2008) demonstrated that soil-moisture content observations improve prediction performance. Even so, selection of relevant variables to represent moisture content is a difficult task (Darras et al., 2014a). Data quantity and quality are the major limiting factors in the application of neural networks to hydrological modelling (Pereira Filho and dos Santos, 2006). Because of noisy data, neural networks used to model natural phenomena are sensitive to overtraining; the use of regularization methods to deal with the bias-variance trade-off is thus mandatory (cf. Sect. 3.1.2). Kong-A-Siou et al. (2014) compared neural network models and VENSIM software to simulate flooding or drought; they concluded that neural modelling performed better for extreme events whereas VENSIM worked better for intermediate, more complex events. This statistical approach has been used to propose some interesting hydrological models. Artigue (2012) has proposed a combination of linear and non-linear modelling in the same model. Corzo and Solomatine (2007) have proposed a combination of specialised neural network to represent isolated processes involved in flood genesis. These methods provided efficient forecasts on rapid hydrodynamic watersheds. Moreover, recent advances have

## HESSD

12, 3681–3718, 2015

### Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



# HESSD

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



proven that the use of these statistical tools can improve the currently-available knowledge of a system. Based on these recent scientific findings, the Knowledge eXtraction (KnoX) methodology was developed to describe contributions and time transfers of spatialized rainfall in any basin. This paper thus proposes to apply this methodology to better apprehend both surface and groundwater processes at the origin of flash flooding in a karst basin. To this end, we focus on the Lez karst hydrosystem which feeds the Lez River that flows through the conurbation of Montpellier (Southern France) with a population of 400 000. Because of its meteorological and geomorphological setting, the Lez River at the Lavalette station, located at the entrance to the city of Montpellier is the site of flash flooding. In addition, as a karst system, the geomorphological structure of the Lez aquifer is strongly heterogeneous, leading to anisotropic water circulation and highly nonlinear hydrodynamic behaviour.

The scientific challenge of this study is thus to apply neural networks to better quantify processes operating in flash flooding. For this purpose, after introduction, Sect. 2 presents a discussion of neural network modelling and the KnoX method. Section 3 is a description of the study area. Section 4 presents the application of the KnoX method to the study area and estimate of contributions and time transfers of spatialized rainfalls to discharge at Lavalette. Section 5 discusses the results and exposes operational and scientific implications. In the conclusion section we discuss innovative perspectives of this generic methodology.

## 2 Artificial neural network modelling for better characterize processes

### 2.1 Neural network design

#### 2.1.1 General presentation

Artificial neural networks are statistical black box models that use input-output measurements to identify nonlinear functions of a system. Basics about neural modelling

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



can be found in (Dreyfus, 2005), only specific information, mandatory for a comprehensive presentation of this study will be provided hereafter. The chosen model is the multilayer perceptron because of its properties of universal approximation and parsimony (Barron, 1993). The universal approximation is the capability to approximate any differentiable and continuous function with an arbitrary degree of accuracy (Hornik et al., 1989). In our study, the multilayer perceptron is a feed-forward model, a finite impulse response model based on (Nerrand et al., 1993). Designing a multilayer perceptron consists mainly of selecting input variables and the number of hidden neurons. This determines the number of parameters mechanically; model complexity increases with the number of parameters.

As statistical models, neural networks are designed in relation to a database. This database is usually divided into three sets: a training set, a stop set, and a test set. The training set is used to calculate parameters through a training procedure that minimizes the mean quadratic error calculated on output neurons. The training is stopped by the stop set (cf. Sect. 2.1.2), and model quality is estimated by the third part of the database: the test set, which is separate from the training and stopping sets. The model's ability to be efficient on the test set is called generalisation. However, the training error is not an efficient estimator of the generalisation error: the efficiency of the training algorithm makes the model specific to the training set. This specialisation of the neural network on the training set is called overtraining. Overtraining is exacerbated by large errors and uncertainties in field measurements; the model learns the specific realization of noise in the training set. This major issue of neural network modelling is called bias-variance trade-off (Geman et al., 1992); Kong-A-Siou et al. (2012) studied it in relation to karst aquifers. To deal with this issue and improve the generalization performance, regularisation methods must be employed (Kong A Siou et al., 2011; Schoups et al., 2008). Three regularisation methods were used in this study.

## 2.1.2 Regularisation methods

In the context of this study, the goal of regularisation methods is to minimize output variance. To this end, cross-validation (Stone, 1974) was used as explained in (Kong-A-Siou et al., 2012) to empirically select input variables and the number of hidden neurons. Cross validation thus minimizes model complexity and therefore output variance.

Another regularization method is commonly employed: early-stopping (Sjöberg et al., 1995). This method stops training before overtraining occurs. A dedicated set, called a stop-set, is considered separately from the database. In Kong-A-Siou et al. (2012), early-stopping was used with cross validation for input variables and hidden neuron number sizing. In our study, the database is too limited to extract another set from the database (the stop set). Thus, instead of a stop-set, a predefined maximum number of training iterations was selected to avoid overtraining. For this purpose the database, not including the test set, was divided into  $S$  subsets corresponding to flash flood events. Training was performed on  $S - 1$  subsets with 50 different parameters initialisations. The remaining subset was used as a validation-set. Each subset was used in turn as a validation set. For each trial the iteration with the minimum mean quadratic error over the validation set is set aside. The median of these numbers of iterations was calculated for all validation sets and all iterations and selected as the optimal number of training iterations. This maximum number of training iterations is used in all the following without further utilization of stop-set. In this study, parameters are iteratively calculated using the Levenberg-Marquardt algorithm (Hagan and Menhaj, 1994).

It is well known also that model performance depends strongly on the parameters initialisation. To define a reliable simulation independent from the initialisation, Darras et al. (2014b) proposed to establish an ensemble of 50 models trained from different initialisations. The output is calculated at each time step by the median of the 50 outputs.

# HESSD

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[⏴](#)

[⏵](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



## 2.2 Towards knowledge improvement about processes

Even if neural networks generally implement black-box models, several authors have tried to make the model more understandable. For example (Johannet et al., 2008) and (Jain and Kumar, 2009) demonstrated the possibility of observing physically interpretable information at the output of hidden neurons. Another path would be to exploit parameters values. The principal difficulty is the sensitivity of parameters values to their initialisation before training. This dependence can be avoided as proposed by (Kong-A-Siou et al., 2013) using a multistep procedure: (i) proposal of a postulated model that describes the available high-level knowledge about the behaviour of the system to be modelled, (ii) implement a neural model architecture that follows this postulated model, (iii) train an ensemble of identical models that differ by their initialisation, and calculate of the median of the absolute value of each parameter over the ensemble models (noted as median-parameter), (iv) combine median parameters to quantify the importance of each input variable. Kong-A-Siou et al. (2013) applied this method to a karst aquifer to evaluate the contributions from different geographic zones to the discharge at the outlet. This methodology is called: knowledge eXtraction (KnoX). Its accuracy was assessed on a fictitious model before being applied to a real aquifer.

In this study we propose to apply the KnoX method to estimate the contributions of different processes, effective in a heterogeneous aquifer, to flash floods. Regarding the Lez Basin, we thus investigate improvement of knowledge about karst and non-karst (surface) flooding processes.

## 2.3 Performance criteria

Several criteria were used to model selection and performance assessment. The first is the Nash–Sutcliffe efficiency, hereafter referred to as  $R^2$  (Nash and Sutcliffe, 1970).  $R^2$  is used to perform model selection using cross-validation. The second is specifically flood-oriented: the synchronous percentage of peak discharge, or  $S_{PPD}$ . The last,

HESSD

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



a purely temporal aspect, is the delay between measured and simulated flood peak, hereafter referred to as  $P_d$  (Peak delay).

### 2.3.1 Nash–Sutcliffe efficiency

The Nash–Sutcliffe efficiency is the most widely used criterion for evaluating hydrological models. It is equivalent to the  $R^2$  determination coefficient i.e.:

$$R^2 = 1 - \frac{\sum_{k=1}^n (y_p^k - \bar{y}_p)^2}{\sum_{k=1}^n (y_p^k - y_p^k)^2}, \quad (1)$$

where  $k$  is discrete time,  $n$  the number of time steps used to calculate  $R^2$ ,  $y$  the simulated discharge,  $y_p$  the measured discharge, and  $\bar{y}_p$  is the measured mean discharge. The Nash score is not really convenient for assessing flood simulations as it takes into account errors on the whole event and not specifically on the peak. For this reason, other criteria were proposed.

### 2.3.2 Synchronous percentage of peak discharge

Synchronous percentage of peak discharge is especially designed for the evaluation of flash flood modelling. It is the ratio of measured and simulated discharges at the time of the observed peak discharge:

$$S_{PPD} = 100 \frac{y_p^{k_p^{\max}}}{y_p^{k_p^{\max}}}, \quad (2)$$

where  $k_p^{\max}$  is the time of the measured peak discharge.



underlies impervious formations in the downstream part. The karst component consists of Cretaceous and Jurassic carbonate rocks. The karst in these formations developed under the current Mediterranean Sea level as a result of the Messinian crisis (Hsü et al., 1973). These formations also crop out widely and form the calcareous plateaus of both the Causse de Hortus and the Causse de Viols-le-Fort. The downstream part of the system is composed of Eocene carbonate and clay formations and Tertiary sandstone and conglomerate formations.

Two major tectonic events have affected the geomorphological structure of the Lez hydrosystem. The first was Pyrenean compression, which occurred during the Eocene. This south–north compression led to the formation of east–west trending faults. The second tectonic event was the opening of the Lion Gulf during the Oligocene. This event led to the formation of northeast–southwest sinistral faults, including the Corconne fault that crosses the Lez Basin.

### 3.3 Meteorological and hydrogeological setting

The study area is subject to a Mediterranean climate. Mediterranean events often occur at the meso-scale and promote intense and localized rainfall. Daily rainfalls can reach 650 mm, such as one event that occurred in September 2002 in south-eastern France. Such high-volume rainfall events are referred to as Mediterranean episodes.

### 3.4 Hydrodynamic circulation

Kong-A-Siou et al. (2013) divided the Lez Basin into four parts (Fig. 2) to better analyse the rainfall–runoff relationship at the Lez Spring at a daily time step. The east–west division is based on the Corconne Fault pathway. On the western side of the basin, the south–north division is based on the Causse de Viols-le-Fort boundary, which is a cropping part of the principal aquifer. On the eastern side of the basin, a south–north division has been drawn based on its geological setting. The Oligocene and Eocene formations define a well-delineated impervious zone in the southeastern part of the

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



basin. The geological composition of each zone is assumed to be “homogeneous”, which means that the geology within a zone is quite similar and that it differs more from the geology of other zones. Using the KnoX method, (Kong-A-Siou et al., 2013) were able to estimate both the water contribution from each “homogeneous” geological zone to the Lez Spring discharge and the mean time-response. The last study, which was conducted at daily time step, shows the important contribution, more than half, of the northeastern zone to the discharge of the Lez Spring. These contributions are presented in Table 5.

### 3.5 Flash Flooding in the Lez Basin

Fed by abundant rainfall on the basin, the Lez receives contributions from surface watershed and also from underground (karst) basin thanks principally to its tributary: the Lirou river. The Lez can exceed a discharge higher than  $500 \text{ m}^3 \text{ s}^{-1}$  at its entrance to Montpellier. This corresponds to a specific discharge greater than  $4 \text{ m}^3 \text{ s}^{-1} \text{ km}^{-2}$ , based on the size of the surface watershed, or  $1.3 \text{ m}^3 \text{ s}^{-1} \text{ km}^{-2}$  considering the whole underground basin. These two simple numbers highlight the need to better understand the origin of the water, and water circulations during flash floods at the Lavalette station at the entrance to Montpellier.

To this end, two different approaches have been proposed in the literature, using event-based modelling. The first uses data assimilation (Kalman filter) to: (i) estimate karst filling at the beginning of the event, (ii) adapt transfer velocity at each time step, and (iii) correct the lack of accuracy of rainfall measurement. Based on these improvements,  $R^2$  of simulation increased from 0.89 to 0.91 for an event in December 2003, and from 0.72 to 0.98 for an event in September 2005 (cf. Table 1). The model is based on the Soil Conservation Service production function coupled with a lag and route transfer function (Coustau et al., 2012). The second approach has operational goals and proposes a graphical method (abacus) to estimate flood peaks from forecast rain features and karst filling (Fleury et al., in press). Using Abacus, authors revised the estimated peak of the September 2005 event down to 460 from  $480 \text{ m}^3 \text{ s}^{-1}$ .

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Thus, it appears that improved knowledge of karst/river interactions is critical. For this purpose, in the next section we propose to use the KnoX method to estimate the contribution of each zone of the Lez Basin to flash flood events.

## 3.6 Database presentation and analysis

### 3.6.1 Monitoring network

Hourly rainfall data are available at five rain gauges: Saint-Martin-de-Londres, Prades-le-Lez, Sommières, Vic-le-Fesq and Saint-Hippolyte-du-Fort. The French Weather Forecasting Service (Météo France) manages the first two gauges, and the Flood Forecasting Service of the Grand Delta (SPCGD) manages the last three gauges. Only the Prades-le-Lez rain gauge is inside the Lez system, but as pointed out in introduction, it is essential to make use of spatialized rainfall information. In addition, no data at the considered time step is available further south than the Prades-le-Lez rain gauge. Spatial rainfall variability is thus not correctly described in the southern part of the basin. This will limit the reliability of this study regarding the southern zone of the basin. Discharge data are provided by the Lavalette gauging station managed by an office of the French ministry of ecology and sustainable development (DIREN). Both rainfall and discharge data are available at an hourly time step, which is convenient for flash flood modelling.

The data suffers from high noise and uncertainty. The uncertainties of discharge measurements have been estimated at around  $\pm 20\%$  for flash floods. The uncertainty of rainfall measurements, can be as high as  $\pm 30\%$  (Marchandise, 2007). Rainfall and discharge time series are available from 2002 to 2008. Fifteen flood events whose peak discharges exceed  $80 \text{ m}^3 \text{ s}^{-1}$  were selected (Table 2). Events 7 and 8 were the most intense; contrary to other intense events, events 13 and 8 occurred on dry soils.

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[⏴](#)

[⏵](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



## 4 Application of the KnoX method to flash flooding at Lavalette

### 4.1 From postulated model to neural network model

#### 4.1.1 Postulated model

As presented in Sect. 2.2, it was necessary to prepare a postulated model describing flash flood genesis at Lavalette station. The postulated model is based on the work of (Kong-A-Siou et al., 2013) as the considered basin is the same (surface + underground). The primary difference is that flash floods are considered at hourly time step at the Lavalette station in this study. Using continuous data at daily time step at the Lez Spring, (Kong-A-Siou et al., 2013) showed that the north-eastern and north-western zones are the principal contributors to Lez spring discharge. To estimate the contributions of each zone to flooding at Lavalette, we distinguished the both behaviours: surface (rapid if inside the impervious watershed) and underground (slower if infiltrated into karst outcrops or in faults: faults play the role of a drain in impervious parts of the basin inside and outside of the Lavalette watershed). Schematically, by looking at the map presented in Fig. 2 and following the previous reasoning, one can propose that the north-western zone would make a minor contribution to flash flooding at Lavalette because it is outside the surface (topographic) basin and because its underground time response is great (Table 5). The south-eastern zone would also have a minor impact because its impervious area is mostly outside the Lavalette watershed. Regarding the south-western and north-eastern zones, it is difficult to propose an a priori quantification. It is thus not easy to estimate the principal contributors to flash flooding. Application of the KnoX method would provide this quantification. The postulated model of the basin behaviour is thus composed of four branches, each corresponding to a zone of the basin, involving surface and groundwater, and feeding a complex mixing process. The postulated model is represented in Fig. 3.

The model used to apply the KnoX method is based on the multilayer perceptron; it follows the postulated model represented in Fig. 3 with four zones contributing to

HESSD

12, 3681–3718, 2015

### Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



discharge at Lavalette station. As suggested by the KnoX method, to be able to identify the contribution of each zone to the discharge, a linear hidden neuron is added between the inputs and the layer of sigmoid neurons. These neurons are intended to represent rain that falls on each zone; they facilitate the estimate of the time response of water falling in each zone.

### 4.1.2 Input data

Inputs are mean rainfalls for each zone. These rainfalls are calculated using the Thiessen polygon method. Table 2 shows the weight of each rain gauge for each zone. It highlights the sparse spatial distribution of rainfall information in the south of the basin. Nevertheless, we consider the rainfall information sufficient to carry out this study.

## 4.2 Model design

### 4.2.1 Model selection

As presented in Sect. 2.1.2, model selection is done using cross-validation and pre-definite number of training iterations. Ranges of investigation and chosen values of various window-width and hidden neurons numbers are provided in Table 3. One can note that the complexity of the model is moderate (small number of hidden neurons). To make the model assessment more reliable on the most intense events 7 and 8, model selection was done without these events (blind assessment).

### 4.2.2 Model validation

The database presented in Table 4 shows seven rapid events. Because of the small number of events it seemed necessary of estimating modelling quality on all events. We thus decided to train seven models, testing each on one event (training performed on the six following events). The model tested on event  $n$  is noted as  $T_n$ . This is a cross-

# HESSD

12, 3681–3718, 2015

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



test operation. Table 4 shows the performance of the seven models in terms of  $R^2$ , synchronous percentage of peak discharge ( $S_{PPD}$ ), and peak delay ( $P_d$ ). After training, we compared the quality of the models: aside from model  $T_2$ ,  $R^2$  and  $S_{PPD}$  scores of model  $T_{13}$  are the worst, respectively 0.71 and 138 %. The other models show satisfactory  $R^2$  and  $S_{PPD}$  scores:  $R^2$  from 0.79 to 0.96 and  $S_{PPD}$  from 87 to 99 %. Regarding the  $P_d$ , only model  $T_2$  performed badly. The models  $T_4$ ,  $T_7$ ,  $T_8$ , and  $T_{14}$  are efficient regarding the three performance criteria. Model  $T_{13}$  over-estimates the flood peak; note that event 13 is the sole event that occurred on dry soils, except event 8 when extremely intense rainfall was observed.

Looking at hydrographs presented in Fig. 4 for the two most intense events and taking into account the scores presented in Table 4, one can suggest that the models are efficient enough to be used for knowledge extraction. In addition, as will be shown in Sect. 4.3.1, knowledge extraction is independent of outliers as it takes into account all events of the training database.

### 4.3 Contributions and time transfers of spatial rainfall to discharge at the Lavalette station

The KnoX method was used to estimate the contributions of the four previously defined zones to flash flooding at the Lavalette station.

#### 4.3.1 Extraction of information from parameters

After training, the median of absolute values of the parameters for 50 different initializations is calculated. It is noted as  $^M |C_{ij}|$  for the parameter  $C_{ij}$  linking the neuron (or input)  $j$  to the neuron  $i$ . The rainfall contribution of zone  $z$  to output at time step  $k - d$  ( $k$  is the discrete time and  $d$  a delay) is denoted as  $r_z(k - d)$ . It is calculated according to the chain of parameters linking one input:  $r_z(k - d)$ , to the output  $y(k)$ . As it is shown in Fig. 3, we have three layers of parameters between the input  $r_z(k - d)$  and the output  $y_o(k)$ , therefore there is three terms in numerator; denominator corresponds to normal-

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



ization terms in order to estimate the specific contribution of the input  $r_z(k-d)$  relative to the sum of all other parameters of the same layer. There is also three normalisation terms because there is three layers of parameters. Following notations are reported in red in Fig. 3. The contribution is calculated as:

$$P(r_z(k-d)) = \frac{M |C_{H_z r_d}|}{\sum_{d=0}^{w_z} M |C_{H_z r_d}|} \sum_{H_N=1}^{N_c} \left[ \frac{M |C_{H_N H_z}|}{\sum_{H_z=1}^l (M |C_{H_N H_z}|) + \sum_{d=1}^{w_1-1} (M |C_{H_N q_d}|)} \frac{M |C_{o H_N}|}{\sum_{H_N=1}^n (M |C_{o H_N}|)} \right] \quad (4)$$

where  $H_z$  ( $H_z = 1, 4$ ) is the subscript of the first hidden layer of linear neurons,  $H_N$  ( $H_N = 1, N_c$ ) is the subscript of the second hidden layer (of  $N_c$  nonlinear neurons);  $q_d$  is the subscript of the previously measured discharge inputs  $y_q$ , and  $o$  is the subscript of the output layer.

The contribution of an entire zone can be expressed as the sum of the contributions of the considered zone at different time steps:

$$P_z = \sum_{d=0}^{w_z} P(r_z(k-d)) \quad (5)$$

This contribution calculus is done for each exogenous input: rainfall or measured discharge, and for each designed model ( $T_n$ ,  $n = 1, 7$ ). The contribution of the previous measured discharges used as input to the model ranges from 21 to 30 % (respectively 89 to 70 % for total rainfall) depending on the considered model  $T_n$  ( $n = 1, 7$ ). Nevertheless, only rainfall contribution values are considered (for a total of 100 %) because the measured input of discharge plays the role of state variable (Artigue et al., 2012). Rainfall contribution medians for the seven models are provided in Table 5. Values obtained

## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



by (Kong-A-Siou et al., 2013) are also reported; they show the difference between contributions of the same zones to very different processes (flash flood at Lavalette station for this study, and daily aquifer discharge at the Lez Spring in the 2013 study).

#### 4.4 Time distribution of contributions

Figure 4 shows the time distributions of contributions by the north-western, north-eastern, south-western and south-eastern rainfall inputs. The percentages expressed in this section are the contribution of the inputs to the output.

Figure 5 shows that the major contribution comes from the south-western zone, with two peaks at  $k - 1$  and  $\{k - 4 \text{ to } k - 5\}$ . This means that, on average, for all events and all time steps, water comes principally from the south-western zone via two transfer functions: one associated with rapid surface response ( $k - 1$ ) and the other associated with slower karst response ( $k - 4$ ) to ( $k - 5$ ) (Causse de Viols-le-Fort, cf. Fig. 1 and Eq. 2). The same reasoning can be applied to the north-eastern zone: fast surface response at  $k - 2$  and slower karst water at  $k - 5$  (due to numerous faults in this zone, cf. Fig. 2); nevertheless, contributions from the north-eastern zone are less pronounced than the south-western ones.

### 5 Discussion

#### 5.1 Rainfalls contributions to discharge

The map shown in Fig. 2 and Table 5 can guide the discussion: Fig. 2 presents the transcription of geological properties in infiltration capabilities.

- Regarding the south-western zone (43 to 54 %), it appears that the large extent of karst delayed contribution (24 % for  $\{k - 4 \text{ to } k - 5\}$ ) comes from the Causse de Viols-le-Fort. This property is not observed in daily continuous modelling (Table 5) because the Lirou Spring (outlet of the Causse de Viols-le-Fort, cf. Fig. 1)

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)







the proposed behaviour of the Lez aquifer, several fieldwork projects are currently in progress to assess karst and non-karst contributions at the Lavalette station.

## 6 Conclusion

Mediterranean flash floods and mountain floods are responsible for numerous casualties and major property damage. These floods occur in heterogeneous basins, which are difficult to observe and thus to model. For this reason this paper investigates the ability to obtain information on a complex aquifer through global systemic modelling using neural networks. For this purpose we chose as a case study flash flooding at the entrance to the great city of Montpellier (Southern France) where large potential losses are at stake. After recent trends in flash flooding and karst modelling, this paper focuses on hydrological modelling with neural networks and presents the basics of neural network modelling. It was shown that these statistical models can efficiently model unknown relationships using only databases. Moreover efficient new approaches were demonstrated to extract information from a set of parameters. Among these methods, the KnoX method can identify contributions from various geographic zones to discharge at the basin outlet; it also provides better characterisation of processes linked to karst water and surface water. To investigate this capability, a case study was conducted on a complex hydrosystem, the Lez hydrosystem. The application to this system shows that the KnoX method consistently estimated the water contributions from four “homogenous” geological zones of the hydrosystem to the discharge at its outlet. The main contributor to flash flooding at Lavalette was identified as the Causse de Viols-le-Fort karst plateau. Piezometric information within this plateau would thus be of crucial importance to model flooding at the Lavalette station. On a more interesting note, several time responses were identified and associated with surface circulations or underground contributions. The lag between these two different response times, estimated at three hours, may thus correspond to synchronization difference between surface and under-

## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)



[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



ground flooding. This information may help flood-warning services anticipate the size of a flood in case of a rain event composed of two rain peaks separated by three hours.

This is a generic method that can be applied to any heterogeneous basin as long as a sufficient database is available.

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10 *Author contributions.* Darras T., Kong-A-Siou L. and Johannet A. designed the experiments and Darras T. conducted them. Borrell Estupina V., Vayssade B. and Pistre S. provided hydrological and meteorological data and their expertise. Darras T. prepared the manuscript with contributions from all co-authors. Johannet A. contributed to the RNF Pro software used to simulate neural networks and extract parameters.

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## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)



[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



**Spatial and temporal contributions of rainfalls**

T. Darras et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

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T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



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## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



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## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



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## Spatial and temporal contributions of rainfalls

T. Darras et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



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## Spatial and temporal contributions of rainfalls

T. Darras et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



**Table 1.** Dates, peak discharges, and mean cumulative rainfalls of flood events contained in the database. Intense events are highlighted by a star. Mean cumulative rainfall is calculated using a weighted average of the five rain gauges with the Thiessen polygon method.

Events	Dates	Peak discharge ( $\text{m}^3 \text{s}^{-1}$ )	Mean cumulative rainfalls (mm)
1	24–27 Aug 2002	7	128
2*	08–09 Sep 2002	112	171
3	08–13 Oct 2002	45	118
4*	09–13 Dec 2002	384	245
5	15–18 Nov 2003	68	86
6*	23–25 Nov 2003	95	51
7*	01–05 Dec 2003	438	234
8*	05–07 Sep 2005	480	144
9	27–31 Jan 2006	53	117
10	13–15 Sep 2006	25	147
11	23–26 Sep 2006	23	85
12	02–07 May 2007	9	88
13*	20–21 Oct 2008	114	123
14*	21–22 Oct 2008	104	72
15	01–08 Nov 2008	31	127





## Spatial and temporal contributions of rainfalls

T. Darras et al.

**Table 4.** Performances of models  $T_2$ ,  $T_4$ ,  $T_6$ ,  $T_7$ ,  $T_8$ ,  $T_{13}$  and  $T_{14}$ : Nash criterion ( $R^2$ ), the synchronous percentage of the peak discharge ( $S_{PPD}$ ) and the peak delay ( $P_d$ ).  $T_7$  and  $T_8$  are models tested on the two most intense events.

Models	$R^2$	$S_{PPD}$ (%)	$P_d$
$T_2$	-0.75	22	-5
$T_4$	0.96	87	-1
$T_6$	0.84	122–89	0–0
$T_7$	0.96	99	0
$T_8$	0.93	97	0
$T_{13}$	0.71	138	0
$T_{14}$	0.79	94	1

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



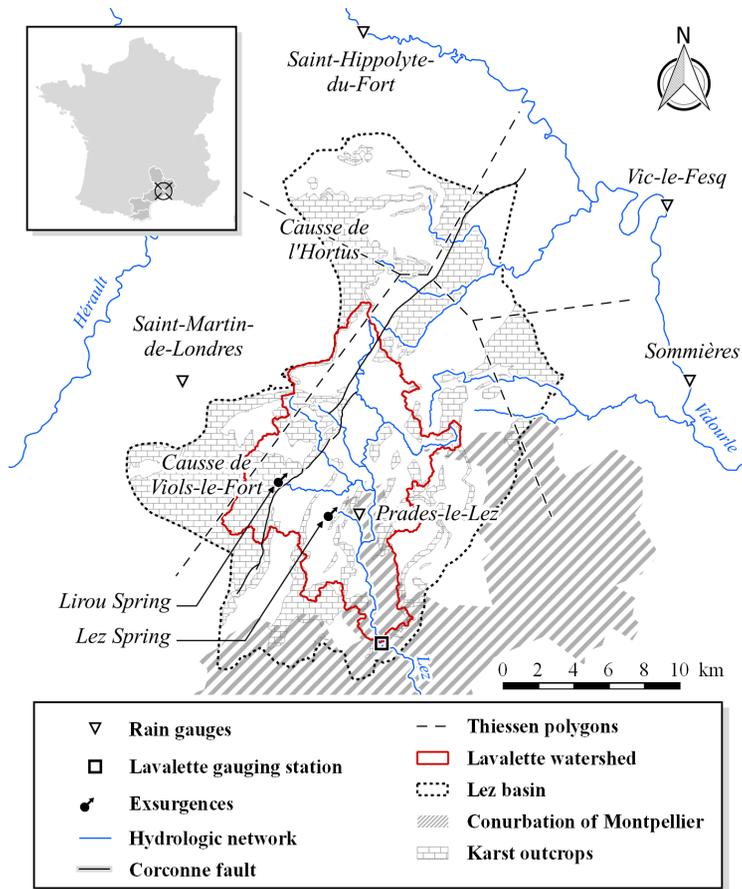
## Spatial and temporal contributions of rainfalls

T. Darras et al.

**Table 5.** Contributions of different zones to discharge. Flash-flood contribution is the median of contributions of rainfall inputs to the output of the seven models  $T_2$ ,  $T_4$ ,  $T_6$ ,  $T_7$ ,  $T_8$ ,  $T_{13}$  and  $T_{14}$ . Maximum and minimum values come from the set of 7 models in this study and from 10 experiments of 50 initialisations in (Kong-A-Siou et al., 2013).

	North-western zone	North-eastern zone	South-western zone	South-eastern zone
Part of the surface watershed at Lavalette	10 %	45 %	20 %	25 %
Rainfalls contribution to flash-flooding at Lavalette (min–max)	<b>9 %</b> (8–11 %)	<b>26 %</b> (18–30 %)	<b>47 %</b> (43–54 %)	<b>18 %</b> (12–24 %)
Time delay of principal contributions	–	–2 h; –5 h	–1 h; –4 to –5 h	0 h
Part of the underground basin at Lez Spring from Kong-A-Siou et al. (2013)	22 %	36 %	18 %	24 %
Rainfalls contribution to daily discharge at Lez Spring from Kong-A-Siou et al. (2013) (min–max)	<b>29 %</b> (28–31 %)	<b>52 %</b> (50–54 %)	<b>13 %</b> (10–15 %)	<b>6 %</b> (4–7 %)
Time delay of principal contributions	–1 to –3 days	–1 day	–1 day	0 day

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)

**Figure 1.** Map of the Lez hydrosystem with location of karst outcrops, rain gauges, gauging stations, springs, causes de Viols-le-Fort and de l'Hortus and of Corconne fault. Boundaries of surface watershed and underground basin, and the conurbation of Montpellier are also shown.

**Spatial and temporal contributions of rainfalls**

T. Darras et al.

Title Page

Abstract Introduction

Conclusions References

Tables Figures

◀ ▶

◀ ▶

Back Close

Full Screen / Esc

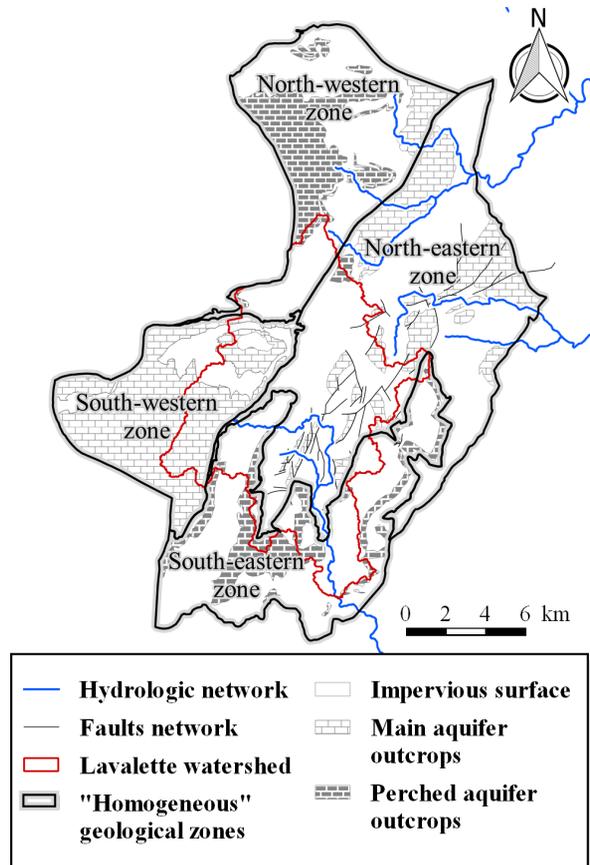
Printer-friendly Version

Interactive Discussion



## Spatial and temporal contributions of rainfalls

T. Darras et al.



**Figure 2.** Map of the Lez Basin: zone boundaries and topographic watershed; impervious and non-impervious formations; faults intensifying infiltration.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)



[Back](#)

[Close](#)

[Full Screen / Esc](#)

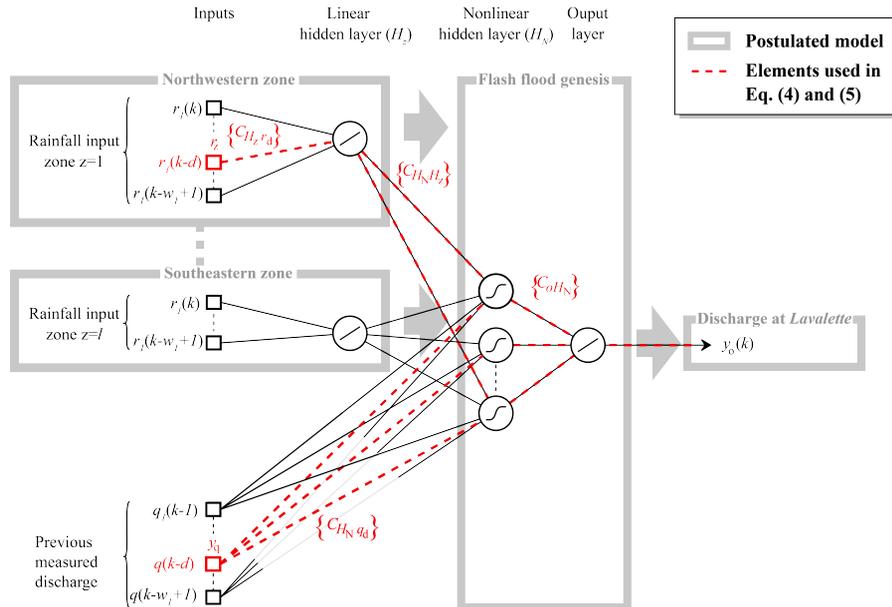
[Printer-friendly Version](#)

[Interactive Discussion](#)



## Spatial and temporal contributions of rainfalls

T. Darras et al.



**Figure 3.** Postulated model: grey block-diagram. Three layers multilayer perceptron with linear hidden layer between rainfall inputs and nonlinear layer. Parameters used in Eq. (4) are denoted in red.

Title Page

Abstract Introduction

Conclusions References

Tables Figures

◀ ▶

◀ ▶

Back Close

Full Screen / Esc

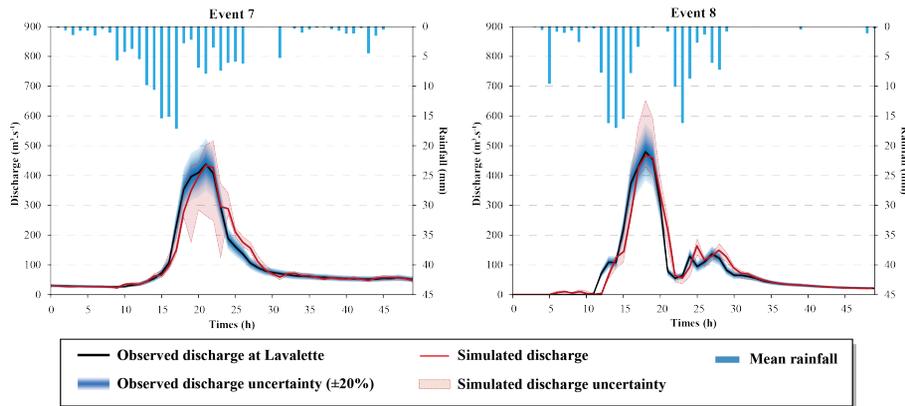
Printer-friendly Version

Interactive Discussion



## Spatial and temporal contributions of rainfalls

T. Darras et al.



**Figure 4.** Hydrographs of major events in the database: events 7 and 8. Simulated discharge is the median of outputs coming from the 50 run models (differing by their initialization parameters). Uncertainty on the observed value is the measurement  $\pm 20\%$ . Uncertainty on the simulated value is represented by simulations coming from the 50 run models (differing by their parameters initialization).

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

