

1 **The importance of topography controlled sub-grid process**
2 **heterogeneity and semi-quantitative prior constraints in**
3 **distributed hydrological models**

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1 **Abstract**

2 Heterogeneity of landscape features like terrain, soil, and vegetation properties affect the
3 partitioning of water and energy. However, it remains unclear to which extent an explicit
4 representation of this heterogeneity at the sub-grid scale of distributed hydrological models
5 can improve the hydrological consistency and the robustness of such models. In this study,
6 hydrological process complexity arising from sub-grid topography heterogeneity was
7 incorporated in the distributed mesoscale Hydrologic Model (mHM). Seven study catchments
8 across Europe were used to test whether (1) the incorporation of additional sub-grid
9 variability on the basis of landscape-derived response units improves model internal
10 dynamics; (2) the application of semi-quantitative, expert-knowledge based model constraints
11 reduces model uncertainty; and (3) the combined use of sub-grid response units and model
12 constraints improves the spatial transferability of the model.

13 Unconstrained and constrained versions of both, the original mHM and mHMtopo, which
14 allows for topography-based sub-grid heterogeneity, were calibrated for each catchment
15 individually following a multi-objective calibration strategy. In addition, four of the study
16 catchments were simultaneously calibrated and their feasible parameter sets were transferred
17 to the remaining three receiver catchments. In a post-calibration evaluation procedure the
18 probabilities of model and transferability improvement, when accounting for sub-grid
19 variability and/or applying expert-knowledge based model constraints, were assessed on the
20 basis of a set of hydrological signatures. In terms of the Euclidian distance to the optimal
21 model, used as overall measure for model performance with respect to the individual
22 signatures, the model improvement achieved by introducing sub-grid heterogeneity to mHM
23 in mHMtopo was on average 13%. The addition of semi-quantitative constraints to mHM and
24 mHMtopo resulted in improvements of 13% and 19% respectively, compared to the base case
25 of the unconstrained mHM. Most significant improvements in signature representations were,
26 in particular, achieved for low flow statistics. The application of prior semi-quantitative
27 constraints further improved the partitioning between runoff and evaporative fluxes. Besides,
28 it was shown that suitable semi-quantitative prior constraints in combination with the transfer
29 function based regularization approach of mHM, can be beneficial for spatial model
30 transferability as the Euclidian distances for the signatures improved on average by 2%. The
31 effect of semi-quantitative prior constraints combined with topography-guided sub-grid

1 heterogeneity on transferability showed a more variable picture of improvements and
2 deteriorations, but most improvements were observed for low flow statistics.

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1 1 Introduction

2 A better understanding of the link between landscape heterogeneity and its impact on process
3 dynamics of catchments is urgently required to develop more robust catchment-scale rainfall-
4 runoff models that have the skill to adequately reproduce the observed system response
5 dynamics, even for catchments where no calibration data are available. Besides heterogeneity
6 in the system boundary conditions, including amongst others topography, vegetation or
7 geology (e.g. Knudsen, 1986; Rodríguez-Iturbe, 2006; Tromp-van Meerveld, 2006), climatic
8 variables, i.e. the forcing of models such as precipitation and evaporation, typically exhibit
9 considerable spatial variability (e.g. Obleid, 1994; Singh, 1997; Winsemius et al., 2008;
10 Hrachowitz and Weiler, 2011). Together, these factors lead to the concept of the “uniqueness
11 of place” as termed by Beven (2000). Thus, with increasing catchment size it becomes
12 increasingly problematic to treat catchments as lumped entities in models as these are not
13 suitable to accommodate spatial heterogeneity. In other words, this heterogeneity can in
14 reality result in a variety of parallel processes, characterized by considerably different time
15 scales, being simultaneously active. Therefore, lumped representations of catchments
16 frequently fail to adequately represent the dominant features of the observed hydrological
17 response at the catchment scale (e.g. Euser et al., 2015), such as low and high flows at the
18 basin outlet

19 Experimentally, the importance of intra-catchment process heterogeneity was for example
20 demonstrated by Seibert et al. (2003a). They showed that groundwater table fluctuations can
21 exhibit considerably distinct dynamics between hillslopes and riparian areas near the stream.
22 Similarly, Detty and McGuire (2010) showed that topographically different landscape
23 elements are characterized by different wetting mechanisms, while others, e.g. McGlynn et
24 al. (2004), Jencso et al. (2009) or Spence et al. (2010), systematically documented distinct
25 response patterns in different parts of catchments.

26 Lumped applications of hydrological models, such as HBV (Bergström, 1992) or GR4J
27 (Perrin et al., 2003) proved valuable in the past under a wide range of environmental
28 conditions and across a range of scales as they appear to capture the core emergent processes
29 of many hydrological systems (e.g. Refsgaard and Knudsen, 1996; Booiij, 2005).
30 Nevertheless, in many cases these models may remain serious over-simplifications of the
31 different combinations of the dominant processes underlying the observed response patterns
32 as argued by, among others, Young, (1992), Reichert and Omlin (1997), Perrin et al. (2001),

1 Wagener and Gupta, (2005), Gupta et al. (2012), Zehe et al.,2014, Hrachowitz et al. (2014)
2 and Fovet et al. (2015). In addition, the transferability of these simple models to other
3 (ungauged) basins is limited. In the past, distributed models, such as MIKE-SHE (Refsgaard
4 and Storm, 1995) or DHSVM (Wigmosta et al., 1994), but also (semi-) distributed
5 applications of lumped models were shown to alleviate the issue of over-simplification to a
6 certain extent by accommodating spatial heterogeneity in soil moisture and/or model
7 parameters (e.g. Fenicia et al., 2008; Winsemius et al., 2008; Euser et al., 2015).

8 However, traditional, conceptual distributed model approaches suffer from several limitations.
9 They are defined by the grid size of the available data or the size of the defined
10 subcatchments, which are in the order of several dozen square kilometers in most applications
11 (e.g. Booi, 2005; Lindström, 2010). Furthermore, although different model parameters allow
12 for some flexibility in accounting for spatial differences, in a large number of cases the
13 defined processes remain the same among individual model units, i.e. the same model
14 architecture is used. This denies the potential for the distinction of different dominant
15 processes belonging to the different parts of the study domain. Even though in some cases
16 triggered by different parameterizations, the importance of this distinction of processes
17 became already apparent in several studies, e.g. Merz and Bárdossy (1998), Zehe et al.
18 (2001), Seibert et al. (2003a) , Das et al (2008).

19 Thus, as individual model units are often still represented in a lumped way, sub-grid process
20 heterogeneity in these lumped units is merely just reflected by distribution functions, or
21 constitutive relationships. For example, distribution functions for maximum unsaturated
22 storage capacities, such as defined in the Xinanjiang model (Zhao, 1992) or the VIC model
23 (Liang et al, 1994), are widely used as a measure of spatial variability of storage capacities on
24 the sub-grid scale. As a second example, the closure problem in the Representative
25 Elementary Watershed approach (Reggiani et al. 1998) addresses the definition of
26 relationships between the spatial variability on the elementary watershed scale and states and
27 fluxes to close the mass and momentum balance equations. Several attempts have been
28 reported to formulate closure relations that allow to accommodate the spatial heterogeneity
29 within the elementary watershed to varying degrees (e.g. Reggiani and Rientjes, 2005; Zhang
30 and Savenije, 2005; Zhang et al.,2006; Tian et al., 2006; Mou et al., 2008; Vannamettee et al.,
31 2012), but the search for generally applicable adequate closure relations is still ongoing.

1 The division of the catchment in several functional units (e.g. Knudsen, 1986; Leavesley and
2 Stannard, 1990; Kite and Kouwen, 1992; Kouwen et al., 1993; Flügel, 1995, Reggiani et al.,
3 1998; Winter, 2001; Seibert et al., 2003b; Uhlenbrook et al., 2004, Schmocker-Fackel et al.,
4 2007, Zehe et al., 2014) may offer a way to address these conceptual shortcomings. In spite
5 of the fact that in many cases insufficient data for a detailed delineation of response units are
6 available, it has been recognized (e.g. Beven and Binley, 1979; Knudsen, 1986) that already
7 topographic data can contain important hydrological information. Starting from that premise,
8 Savenije (2010) argued that through the co-evolution of topography, vegetation and
9 hydrology, different landscape features, such as hillslopes, wetlands or plateaus, do have
10 distinct hydrological functions. This implies that topography alone may contain sufficient
11 information to derive dominant hydrological response units. Distinct response units can
12 therefore be identified based on, for example, the height above the nearest drainage, as a
13 proxy for hydraulic head, and local slope (Rennó et al., 2008; Nobre et al, 2011; Gharari et
14 al., 2011). The different dominant processes characterizing these response units can then be
15 combined into a semi-distributed model with landscape elements acting in parallel. This
16 parsimonious approach to account for process heterogeneity at catchment scale proved highly
17 valuable for improving the skill of otherwise lumped models in reproducing observed system
18 response patterns (e.g. Gao et al., 2014; Gharari et al., 2014). They further enhance model
19 transferability without the need for empirical transfer functions (Gao et al., 2015) in widely
20 contrasting environments.

21 Traditional distributed model applications are characterized by a comparably large parameter
22 space. The typical lack of sufficient model constraints makes it problematic to select
23 meaningful feasible parameter sets. This leads to considerable equifinality (Beven, 1993) and
24 associated problems (cf. Gupta et al., 2008). The need for increased hydrological consistency
25 in models and for more realistic internal model dynamics (i.e. “getting the right answer for the
26 right reasons”; Kirchner, 2006) was recently emphasized as a critical point towards the
27 development of models with higher predictive power (Gupta et al., 2012; Euser et al., 2013;
28 Hrachowitz et al., 2014). This can all be placed in the sense of achieving “the least uncertainty
29 for forecasts” (Kumar, 2011) and needs to be done by more rigorous model testing (e.g.
30 Andréassian et al., 2009; Coron et al., 2012) to meaningfully constrain the feasible
31 model/parameter space.

1 An efficient method to constrain the parameter space is model regularization (e.g. Tonkin and
2 Doherty, 2005), for example by the use of transfer functions (e.g. Abdulla and Lettenmaier,
3 1997; Hundecha et al., 2004; Pokhrel et al., 2008). Being mathematically equivalent to the
4 concept of regionalization, it was also shown that this is a valuable method to improve spatial
5 model transferability (e.g. Götzinger and Bárdossy, 2007; Samaniego et al., 2010; Kumar et
6 al. 2013b). However, regularization frequently relies on empirical relationships between
7 catchment characteristics, such as soils, and individual model parameters with little explicit
8 hydrological meaning. In a different approach it was recently shown that semi-quantitative
9 information on catchment functioning based on expert-knowledge, often referred to as “soft
10 data” (Seibert and McDonnell, 2002; Van Emmerik et al., 2015), can be highly efficient in
11 constraining models (Kapangaziwiri, 2012; Hughes, 2013; Seibert and McDonnell, 2013; Gao
12 et al., 2014; Gharari et al., 2014; Hrachowitz et al., 2014).

13 Considering the potential information embedded in landscapes, the need for simplification
14 and regularization in complex models, and the additional value of expert-based semi-
15 quantitative information, there may be an opportunity to improve distributed hydrological
16 models. To test the value of topography-induced sub-grid process heterogeneity, the
17 principles of landscape driven modelling (Savenije, 2010) were introduced in the distributed,
18 regularized mesoscale Hydrologic Model (mHM; Samaniego et al., 2010; Kumar et al.,
19 2013a). It is hypothesized that, (1) the incorporation of additional sub-grid variability on the
20 basis of topography-derived response units improves model internal dynamics and its
21 predictive power, (2) the application of semi-quantitative, expert-knowledge based model
22 constraints allow the identification of unfeasible parameter sets and thereby reduces model
23 uncertainty, and (3) the combined use of response units and model constraints improves the
24 spatial transferability of the model.

25

26 **2 Methodology**

27 **2.1 Study Areas**

28 Seven catchments were selected in order to cover a variety of climatological, geographical
29 and geological conditions. The geographical locations as well as the classification of
30 topography-based hydrological response units (i.e. hillslopes, wetlands and plateaus) in the
31 study catchments are shown in Figure 1. The set of study sites includes catchments with

1 pronounced relief as well as relatively flat and gently sloped catchments. Therefore, some
2 catchments are almost fully dominated by landscapes classified as hillslopes, whereas others
3 contain higher proportions of wetlands. In addition, the climatic variability is considerable, as
4 indicated by the aridity indices ranging from 0.5 to 1.34. Table 1 summarizes the catchment
5 characteristics.

6 The North-German Treene catchment is a tributary of the Eider river. It is a lowland
7 catchment characterized by sedimentary soils and peat. The land cover is mostly grassland
8 and low vegetation while only a small percentage is forested or agriculturally used.

9 The Loisach, Kinzig and Broye catchments are located in mountainous areas, characterized by
10 pronounced relief, steep slopes and the importance of snow. The Loisach and Kinzig
11 catchments are mostly forested, whereas the Broye catchment has mainly open grassland.
12 Sand overlies limestone and other sedimentary bedrock in the Loisach catchment, while the
13 Kinzig catchment is dominated by granite and gneiss series.

14 The French catchments Orge and Briance are relatively flat with gentle slopes and flat upland
15 areas. Agriculture is the dominant land use, but some forests are also present. The Orge
16 catchment is a tributary of the Seine and contains some of the suburbs of Paris. Thus, it has a
17 significant proportion of urbanized areas (10%). In the Orge, sandy loam soils have formed on
18 limestone geology, while the Briance is characterized by gravel on gneiss bedrock.

19 The Alzette catchment in Luxembourg is partly covered by forest (33% of the catchment
20 area). The rest of the catchment is more open with grass and shrublands. Limestone,
21 sandstone and schist are the dominant geologic formations with some clay and loam soil in
22 the upper layers.

23 Daily discharge time series for all study catchments were obtained from the Global Runoff
24 Data Centre (GRDC). The daily meteorological data are the gridded E-OBS precipitation and
25 temperature data from the European Climate Assessment and Dataset (ECA&D). The daily
26 potential evaporation was estimated with the Hargreaves equation (Hargreaves, 1985). A
27 summary of the data sources is given in Table 2.

1 **2.2 Models**

2 **2.2.1 Mesoscale Hydrological Model (mHM)**

3 mHM is a distributed, process-based model that uses the cell-wise model architecture shown
4 in Figure 2 in each grid cell of the modelling domain (Samaniego et al., 2010, Kumar et al.
5 2013a). It contains an interception and snow routine to determine the effective precipitation
6 which enters the soil moisture reservoir. For sealed areas the water is directly routed to a fast
7 reservoir. The water infiltrating into the soil is then partitioned into transpiration and
8 percolation to a fast runoff reservoir, i.e. shallow subsurface flow. In addition, this reservoir
9 recharges a lower reservoir that mimics the base flow component of the runoff. The model has
10 been successfully applied across Germany, Europe and North America (Samaniego et al.
11 2010, 2013, Kumar et al. 2010, 2013a,b, Livneh et al., 2015, Thober et al., 2015, Rakovec et
12 al., 2015).

13

14 **2.2.2 Topography driven mHM (mHMtopo)**

15 To test the value of topography variability-induced process heterogeneity in a distributed
16 model, the concepts of FLEXtopo (Savenije, 2010; Gharari et al., 2011) were applied in
17 mHM. Based on the assumption of distinct hydrological functioning of different landscape
18 elements, sub-grid process heterogeneity was accounted for by a model architecture that
19 allowed an explicit representation of landscape classes identified to be dominant in many
20 central European regions: plateaus, hillslopes and wetlands (Savenije, 2010). The landscape
21 classes were defined by the Height Above the Nearest Drainage (Renno et al., 2008; HAND)
22 and local slope. Following Gharari et al. (2011), areas with a low slope ($<11\%$) and high
23 HAND ($>5\text{m}$) were defined as plateaus, areas with high slope ($>11\%$) as hillslopes and areas
24 with low slope and low HAND ($<5\text{m}$) as wetlands. It is acknowledged that these thresholds
25 remain merely assumptions and may need refinement in other regions. Nevertheless, this
26 refinement is out of the scope of this paper and the used threshold values are assumed to give
27 a reasonable delineation of landscape units in the Central European context. The varying
28 proportions of these individual landscape units in each cell in the modelling domain then
29 allow for considerable sub-grid process heterogeneity in the distributed model, as the total
30 outflow of a cell is then the area-weighted average of the outflows from the individual
31 landscape units. The assumptions behind the conceptualizations of the three landscape classes

1 are in the following briefly summarized. For details the reader is referred to Savenije (2010)
2 and Gharari et al. (2014).

3 The different model structures for these three classes run in parallel, connected by a common
4 groundwater reservoir for each modelling cell, as can be seen in Figure 3. The primary
5 hydrological functions of plateau landscapes are, in the absence of significant topographic
6 gradients, mainly groundwater recharge and evaporation/transpiration, i.e. vertical fluxes. To
7 account for potential agricultural drainage systems a fast reservoir is included in the plateau
8 model structure. Hillslopes are assumed to be the dominant source of storm flow and
9 efficiently contribute to storm runoff through storage excess shallow subsurface flow, e.g.
10 preferential flow, here conceptualized by a fast reservoir. The wetland landscape is assumed
11 to interact stronger with the groundwater. Thus, capillary rise (Cr in Figure 3) is included to
12 interact with the soil moisture reservoir. The wetlands are assumed to have shallow
13 groundwater tables and associated low storage capacities. Therefore, saturation excess
14 overland flow, represented by a fast responding reservoir, and evaporative processes are
15 assumed to be dominant in this landscape unit.

16 Throughout the rest of this paper, the two models will be referred to as mHM and mHMtopo
17 to distinguish between the original mHM and the topography-guided set-up respectively.

18 **2.3 Model regionalization, regularization and prior constraints**

19 Reducing the feasible model parameter space is strongly associated with a reduction in
20 parameter equifinality and model uncertainty, and can be achieved by imposing constraints on
21 the model, for example by regularization. Only parameter sets that can satisfy these
22 constraints will then be retained as feasible, while others will be discarded. A method that
23 uses empirical transfer functions relating parameter values to physical catchment
24 characteristics, is also a powerful tool to regionalize models.

25 **2.3.1 Multiscale parameter regionalization**

26 The multiscale parameter regionalization (MPR) is the key feature of mHM (Samaniego et al.,
27 2010; Kumar et al. 2013a). The global parameters in mHM are, in contrast to typical models,
28 not hydrologic model parameters (e.g. soil porosity). Instead, the global parameters define the
29 functional relationship between the individual hydrologic model parameters and physical
30 catchment characteristics at the spatial resolution of the data of the latter. A set of global

1 parameters is obtained by simultaneously calibrating on multiple catchments. This set of
2 global parameters can then be transferred to other catchments where the same data of physical
3 catchment characteristics are available without the need for further calibration.

4 Thus, the functional relationships are used in a first step to estimate model parameters on the
5 spatial resolution of the input data. As depicted in Figure 4, as an example, the leaf area index
6 is linearly linked through global parameters with the hydrologic model parameter of
7 interception capacity (I_{\max}). Assuming the relationships are adequate, the use of additional
8 data of preferably multiple, distinct catchments may increase the general validity of these
9 relationships and, thus, the global parameters.

10 Figure 5 depicts the application of the MPR technique on gridded data. The obtained
11 hydrologic parameters, determined by the functional relationships, still have a resolution
12 equal to the input data. In most cases, this is not equal to the modelling resolution. Therefore,
13 a second step in the MPR is the upscaling of hydrologic parameters to the modelling
14 resolution (in this study 8 km x 8 km). This upscaling can either be achieved by using the
15 harmonic mean, arithmetic mean or maximum value over the cells within the modelled grid
16 cell. The choice of the upscaling method strongly depends on the parameter under
17 consideration. The reader is referred to Samaniego et al. (2010) and Kumar et al. (2013a) for
18 details about the transfer functions and upscaling methods.

19 The MPR has been adjusted in two ways for use in mHMtopo. The regionalization functions
20 were used for the three individual landscape units, whereby each landscape unit was assigned
21 its own global parameters. In other words, the functional relations between physical
22 catchment characteristics (e.g. soil, slope) and hydrologic parameters were kept the same, but
23 the global parameters of these relations differ between landscape units. For example, the LAI
24 is now individually linked with three global parameters for wetland, hillslopes and plateaus,
25 respectively, to obtain three hydrologic parameters for interception capacity ($I_{\max,plateau}$,
26 $I_{\max,hillslope}$, $I_{\max,wetland}$), see Figure 5.

27 The second change was in the upscaling. Instead of scaling up over all high resolution cells
28 within a modelling unit, the upscaling was carried out for each landscape class within a
29 modelling unit. The upscale operators for mHMtopo were adopted from similar parameters in
30 mHM. For example, the upscaling of the interception capacities was done by the arithmetic
31 mean, similar to that of the upscaling of interception capacities used in the original mHM (see
32 Figure 5).

1 2.3.2 Expert knowledge-based prior constraints

2 In addition to MPR, we tested the value of semi-quantitative, relational prior parameter and
3 process constraints (Gharari et al., 2014; Hrachowitz et al., 2014) for the robustness of
4 process representation and model transferability. In other words, only global parameter sets
5 that satisfied these parameter and process constraints during calibration were accepted as
6 feasible and used in validation and post-calibration evaluation.

7 Specifically, constraints for the long-term mean annual runoff coefficients were formulated to
8 ensure plausible water partitioning between evaporation and runoff. The limits were chosen as
9 the maximum and minimum annual runoff coefficients C_{Rmax} and C_{Rmin} occurring over the
10 calibration time period. The months May – September were defined as high flow period,
11 whereas low flows were assumed to occur over the months October – April. Only for the
12 Loisach catchment these periods were switched as this catchment has high flows starting in
13 spring due to snowmelt. The following three constraints were used: one taking into account
14 the whole time series (C_R) as well as one for the high flow period (C_{Rhigh}) and one for the low
15 flow period (C_{Rlow}) to improve the seasonal variation of the model response behaviors.

16

$$17 \quad C_{Rmin} \quad < \quad C_{Rmodelled} \quad < \quad C_{Rmax} \quad (1)$$

$$18 \quad C_{Rhigh,min} \quad < \quad C_{Rhigh,modelled} \quad < \quad C_{Rhigh,max} \quad (2)$$

$$19 \quad C_{Rlow,min} \quad < \quad C_{Rlow,modelled} \quad < \quad C_{Rlow,max} \quad (3)$$

20

21 The topography driven model mHMtopo is also constrained on soil moisture storage capacity
22 (S_M). On hillslopes and plateaus the groundwater table can be assumed to be deeper than in
23 wetlands and root systems generate a larger dynamic part of the unsaturated zone (cf. Gao et
24 al., 2014b). Therefore, they are conceptualized to have a higher water storage capacity than
25 wetlands, which are typically characterized by a very shallow groundwater table. This
26 reasoning reflects not only the variable contribution area theory of Dunne (1975) and the
27 concept of topographic wetness index (Beven, 1979), but also results from experimental
28 studies, e.g. Seibert et al. (2003a). Thus, two additional constraints were used for mHMtopo:

29

$$30 \quad S_{M,plateau} \quad > \quad S_{M,wetland} \quad (4)$$

$$1 \quad S_{M,\text{hillslope}} > S_{M,\text{wetland}} \quad (5)$$

2

3 **2.4 Experiment set-up**

4 **2.4.1 Calibrated model comparison**

5 The two models, i.e. mHM and mHMtopo, were calibrated for each catchment with a random
6 Monte Carlo sampling approach based on 100,000 realizations and a multi-objective strategy
7 using four objective functions: the Nash-Sutcliffe efficiency of flow ($E_{NS,Q}$), the Nash-
8 Sutcliffe efficiency of the logarithm of flow ($E_{NS,\log Q}$), the volume error of flow ($E_{V,Q}$) and the
9 Nash-Sutcliffe efficiency of the logarithm of the flow duration curve ($E_{NS,FDC}$). The four
10 objective functions were chosen as they characterize different aspects of the flow response.
11 Therefore, these objective functions are expected to provide hydrologically relatively
12 consistent and robust parameter sets.

13 This calibration strategy was preferred over other calibration schemes, such as DDS (Tolson
14 and Shoemaker, 2007) or SCE (Duan et al. 1992), to obtain a set of feasible parameter
15 solutions, instead of one optimal solution. As the mathematically optimal solution may not be
16 the hydrologically most adequate solution (cf. Beven, 2006; Kirchner, 2006; Andreassian et
17 al., 2012), this is necessary to make a robust assessment of the model's abilities. Therefore, all
18 parameter sets that satisfy all model constraints and that are contained in the parameter space
19 spanned by the 4-dimensional Pareto front formed by $E_{NS,Q}$, $E_{NS,\log Q}$, $E_{V,Q}$ and $E_{NS,FDC}$ were
20 considered as feasible solutions and used for post-calibration evaluation. Considering all
21 feasible solutions as equally likely, the model uncertainty intervals are represented by the
22 envelope of all feasible solutions.

23 **2.4.2 Post-calibration model evaluation**

24 The models' skill to reproduce a variety of observed hydrological signatures, i.e. emergent
25 properties of a system (Eder et al., 2003), was evaluated after calibration to test the
26 hydrological consistency of the models. Hydrological signatures allow evaluating the
27 consistency and reliability of hydrologic simulations by taking more features of the
28 hydrological response into account than only the flow time-series. In a nutshell, the more
29 signatures a model can simultaneously reproduce in addition to the hydrograph, the more
30 plausible it is that a model (and its parameters) adequately reflects the underlying dominant

1 system processes (e.g. Euser et al., 2013). All signatures used in this study were selected
 2 based on earlier work (e.g. Sawicz et al., 2011; Euser et al., 2013) and are summarized in
 3 Table 3.

4 Although not fully independent of each other, the signatures, such as the peak flow
 5 distribution, the rising limb density and the autocorrelation function of flow, contain
 6 information on different aspects of the hydrologic response. The Nash-Sutcliffe efficiency S_{NS}
 7 was used as a performance metric to assess the model skill in case of multi-value signatures
 8 such as the peak flow distribution or the autocorrelation function. In contrast, the relative
 9 error S_{RE} was used for single valued signatures, such as the mean annual runoff. The
 10 Euclidian distance D_E to the “perfect model” was used as an overall measure of a model’s
 11 ability to reproduce all signatures under consideration (e.g. Schoups et al., 2005):

12

$$13 \quad D_E = \sqrt{(1 - S_{NS,1})^2 + (1 - S_{NS,2})^2 \dots + (1 - S_{NS,n})^2 + S_{RE,1}^2 + S_{RE,2}^2 \dots + S_{RE,m}^2},$$

14 (5)

15 with $S_{NS,i}$ the performance metric of n multi-valued signatures, and $S_{RE,j}$ for the m single
 16 valued signatures.

17 From calibration, a set of feasible parameter sets was obtained for each tested model, which
 18 inevitably resulted in varying skills to reproduce the system signatures for the individual
 19 parameter sets. The probability that one model outperforms another for a specific signature
 20 was computed to objectively quantify the differences between these distributions and to allow
 21 an overall assessment which of the tested models exhibit a higher capability to reproduce the
 22 individual signatures. As estimates of the empirical performance distributions are available
 23 based on all parameter sets retained as feasible, the probability of improvement $P_{I,S}$ can be
 24 readily obtained from:

$$25 \quad P_{I,S} = P(S_1 > S_2) = \sum_{i=1}^n P(S_1 > S_2 | S_1 = r_i) P(S_1 = r_i)$$

(6)

26 where S_1 and S_2 are the signature performance metrics of the two models, r_i a realization from
 27 the S_1 distribution and n the total number of realizations of the S_1 distribution. Thus, a
 28 probability of 0.5 indicates that in 50% of the cases model 1 and in 50% of the cases model 2

1 performs better, i.e. no preference for a model can be identified. In contrast, for $P_{1,S} > 0.5$ it is
2 more likely that model 1 outperforms model 2 with respect to the signature under
3 consideration, and vice versa for $P_{1,S} < 0.5$.

4 In an additional analysis, the Ranked Probability Score S_{RP} was calculated as a measure for
5 the magnitude of improvement. For details please see the description and Figure S1 in the
6 supplementary material.

7 2.4.3 Comparison of model transferability

8 The hydrologic model mHM has been previously shown to have a considerable ability to
9 reproduce the hydrograph when transferring global parameters from calibration catchments to
10 other regions without further recalibration (Samaniego et al., 2010a,b; Kumar et al., 2013a,b;
11 Rakovec et al. 2015). Therefore, it was tested whether the addition of topography-driven sub-
12 grid process heterogeneity and the use of prior constraints in mHM have potential to further
13 improve this transferability. Four catchments were used as donor catchments to obtain one set
14 of global parameters via simultaneous calibration. The Orge, Treene, Broye and Loisach were
15 chosen as donor catchments as they are geographically far from each other, introducing a
16 wide range in climate and catchment characteristics. The receiver catchments are the three
17 remaining catchments of Alzette, Briance and Kinzig.

18 This was carried out with the same calibration strategy as for the individual catchment
19 calibrations. However, the four objective functions $E_{NS,Q}$, $E_{NS,\log Q}$, $E_{V,Q}$ and $E_{NS,FDC}$ were now
20 averaged over the catchments. This lead to global parameters that account for the performance
21 on all donor catchments. These averaged values were then used to determine the pareto space
22 of feasible parameter sets again. The feasible solutions were transferred and used in the three
23 remaining receiver catchments without any further recalibration. We fully acknowledge that
24 this analysis can only give a sense of what is possible and that a full bootstrap procedure and
25 the analysis of more catchments would have allowed a more robust interpretation of the
26 results, but this was unfeasible given the computational demands of the calibration procedure.
27 The calibrations were carried out on the high-performance compute cluster EVE of the UFZ
28 Leipzig which has 84 compute nodes with dual socket Intel Xeon X5650 processors with 64
29 GB RAM as well as 65 compute nodes with dual socket Intel Xeon E5-2670. Nevertheless,
30 the used calibration strategy needed runtimes of about two weeks per catchment on multiple
31 EVE cores, depending on catchment sizes and lengths of time series.

1

2 **3 Results and Discussion**

3 **3.1 Calibrated model comparison**

4 The two different models mHM and mHMtopo, both with and without additional prior
5 constraints, exhibited adequate and similar calibration performances with respect to all four
6 calibration objective functions (see Figure S2 in the supplementary material). For the
7 validation period it was found that performance generally improved by applying prior
8 constraints and by allowing for topography-guided sub-grid process heterogeneity. This can
9 be seen from Figure 6, where mHM with constraints (darkblue) compared with mHM
10 (lightblue) generally has an increased performance. The same is true for mHMtopo with
11 constraints (orange) compared with unconstrained mHMtopo (grey). At the same time, it can
12 be noted from Figure 6 that the addition of topography-guided sub-grid variability leads to a
13 general moderate improvement in performance. Overall, the introduction of constraints to
14 mHM resulted in an average improvement of 13% with regard to the Euclidian distance D_E
15 for the objective function values in validation. In addition, unconstrained and the constrained
16 mHMtopo exhibited an average increase of 8% and 11%, respectively, for the Euclidian
17 distance D_E compared to the original mHM.

18 **3.1.1 Effect of sub-grid heterogeneity**

19 The incorporation of sub-grid process heterogeneity did not show a clear pattern of
20 improvements or deterioration. Some catchments experienced performance increases in terms
21 of the used objective functions during validation, like the Briance catchment. The predictive
22 performance of others, also in terms of the used objective functions, slightly decreased, such
23 as the Orge catchment. These findings support the results of Orth et al. (2015), who also
24 found that added complexity, here in the sense of an increased number of processes and
25 parameters, not necessarily leads to model improvements. However, these findings are not in
26 line with some other previous work (e.g. Gharari et al., 2013; Gao et al., 2014; Euser et al.,
27 2015), who all concluded that parallel model structures increased model performance. It can
28 be argued that for mHM, whose global parameters are to a certain extent already functions of
29 landscape variability, additional sub-grid process heterogeneity is not warranted by the
30 available data and can thus not be resolved by the model when there are relatively little
31 contrasts in the landscape.

1 The Treene catchment benefits most from the addition of topography-guided sub-grid
2 heterogeneity (Figure 6). Here, a large area is classified as wetland, where the soil moisture is
3 fed by groundwater through capillary rise. This process is fully absent in the original mHM
4 structure, but an important process in this relatively flat and humid catchment, dominated by
5 peaty soils. These findings also correspond with conclusions by Schmalz (2008a,b), who
6 applied the SWAT model in the same catchment and noticed that shallow groundwater and
7 soil moisture parameters are very sensitive to low flows. It may also be noted that for
8 mHMtopo the bandwidth of the feasible solutions around the observed hydrograph is
9 considerably reduced as compared to mHM, in particular during low flows. Figure 7 shows
10 that in the months April – July the uncertainty range is significantly larger for mHM than for
11 mHMtopo. In addition, it is interesting to note that the lower bound of flow in mHM is
12 reaching towards 0 mm/d in July, whereas mHMtopo still maintains a flow.

13 In contrast, it can be noticed from Figure 6 that the consideration of sub-grid process
14 heterogeneity causes a decrease in performance compared to the original mHM in the Orge
15 catchment. This catchment has a relatively large urban area of about 10%. In addition, these
16 areas are rather densely populated and the river contains several human made adjustments
17 such as weirs (Le Pape, 2012). Therefore, it is more markedly influenced by anthropogenic
18 disturbances, which are likely not adequately reflected in neither mHM nor mHMtopo. This
19 results in a situation where the more parsimonious mHM is likely to provide a representation
20 of process dynamics that more closely reflects the observed. The higher number of parameters
21 in mHMtopo provides not only more freedom for adequate system representations, but also
22 for misrepresentations. Thus, after an adequate calibration a larger part of the “feasible”
23 mHMtopo parameter sets fails to mimic the observed response patterns in the validation
24 period compared to mHM. In addition, it can also be observed from the hydrographs that the
25 Orge is a fast responding catchment with very spiky flow peaks (Figure 8). The addition of
26 more storage reservoirs in mHMtopo delays the signal more than the simpler model structure,
27 leading to a reduced ability to reproduce this spiky behavior.

28

29 3.1.2 Effect of constraints

30 The applied prior process and parameter constraints, in agreement with Gharari et al. (2014b)
31 and Hrachowitz et al. (2014), helped to increase model performance (Figure 6) and to reduce

1 model uncertainty (Figures 7,8,9) by identifying and discarding a considerable part of model
2 solutions that did not satisfy these constraints. Rather, these discarded solutions violated
3 observed partitioning patterns between runoff and evaporative fluxes and conflicted with our
4 understanding of how the catchments respond. Being merely manifestations of a successful
5 mathematical optimization process, rather than plausible representations of system-internal
6 response dynamics, the discarded solutions underline how deceitful adequate calibration
7 results can be and how a successful identification can result in reduced predictive uncertainty.
8 It must be noted that the effect is strong in the chosen calibration strategy, as a large set
9 containing also less optimal solutions is maintained as feasible, but it has already been shown
10 that other calibration procedures may also benefit from additional constraints (Gharari et al.,
11 2014b). This is true as constraints limit the parameter search space with feasible solutions that
12 the algorithm has to explore. In addition, while traditional calibration procedures may
13 converge to a mathematically optimal fit, additional constraints can test the found solutions
14 for hydrological consistency.

15 More specifically, the Loisach catchment benefits considerably from the applied constraints.
16 This can be explained by the fact that this is one of the few catchments in this study where
17 snowmelt plays an important role. For this catchment, temperature is in phase with the high
18 flows, which causes difficulties in water partitioning in the unconstrained models, resulting in
19 evaporative fluxes being too high and stream flow being too low. A similar observation for
20 the Loisach was found by Muerth et al. (2013). Even though forced by an ensemble of climate
21 models, the winter flows were too high for an ensemble of hydrological models run for this
22 catchment. Hence, the application of runoff constraints for high and low flow periods lead to
23 a considerable improvement of the model internal dynamics. This is supported by visual
24 inspection of the hydrographs (Figure 9): both, the constraints for mHM and mHMtopo, cause
25 a significant reduction in the uncertainty bandwidth of the modelled hydrograph, particularly
26 during high flow periods. The unconstrained models have a relatively low lower boundary
27 during high flows, whereas the boundaries in the constrained cases stay much closer to the
28 observed values. Nevertheless, it must also be noted that both models tend to slightly
29 underestimate the flows in the high flow period.

30 3.1.3 Effect of constraints and sub-grid heterogeneity

31 Comparing the base case of the unconstrained mHM with the most complex constrained
32 mHMtopo (Figure 6) shows that in most cases improvements are observed. As stated before,

1 compared with the unconstrained mHM, the constrained mHMtopo exhibited an average
2 increase of 8% and 11%, respectively, for the Euclidian distance D_E . In most cases, a
3 narrowing of the distribution of objective function values can be observed. For example, the
4 Alzette shows a considerable reduction in the bandwidths of the objective function values.
5 Several catchments also show a substantial shift towards more optimal solutions. The Loisach
6 catchment, as an example, is one of the catchments where this can be observed.

7 The only catchment that does neither show a decrease in bandwidth nor shift upward for any
8 of the four objective function value distributions, is the Orge catchment. Moreover, it shows
9 a strong deterioration in terms of objective functions when constraints and sub-grid
10 heterogeneity are added. The processes included in mHMtopo may not be suitable in this
11 case, as the human influences are strong in this catchment. Thus, as stated before, the more
12 parsimonious mHM better reflects the observed dynamics in this catchment in terms of the
13 objective functions.

14 **3.2 Signature comparison**

15 The two models mHM and mHMtopo, both unconstrained and constrained, were compared
16 for their ability to reproduce a wide range of hydrological signatures (Table 3). This
17 comparison is based on the probabilities of improvement P_{IS} (Figure 10 and Equation 6), but
18 similar results were obtained with the Ranked Probability Score S_{RP} . The results of S_{RP} can be
19 found in the supplementary material in Figures S3 and S4. Overall, the introduction of
20 constraints to mHM lead to an average improvement of 13% in terms of the Euclidian
21 distance D_E . The introduction of topography had a similar effect with an average
22 improvement of 13% for D_E . The constrained mHMtopo case even experienced an average
23 improvement of 19%.

24 **3.2.1 Effect of sub-grid heterogeneity**

25 Similar to the model performance in the validation periods, no clear pattern emerges for the
26 different models' ability to reproduce the system signatures. The Euclidean distance metric,
27 depicted in the last column of Figure 10a, illustrates that the consideration of sub-grid process
28 heterogeneity in mHMtopo leads to a slight overall improvement compared to mHM. Yet, the
29 effect on individual signatures is diverse with some signatures captured to a better degree,
30 while others could be reproduced less well.

1 Figure 10a shows that the Treene, Orge and Loisach benefit the most from the addition of
2 sub-grid heterogeneity. Especially the Treene has a rather large probability of improvement
3 for most of the signatures. This supports the previous findings that the wetland related
4 processes, which are added in mHMtopo, are important to consider in this wet, peaty
5 catchment.

6 It is interesting to note that the Orge and Loisach, which showed a considerable decrease in
7 performance in terms of the four calibration objective functions (Figure 6), now exhibit
8 relatively high probabilities of improvement with respect to the signatures when sub-grid
9 heterogeneity is added (Figure 10a). The signatures with the strongest improvements are
10 related to peaks in the low flow period. Similar to the Treene, the low flow processes are
11 better captured with mHMtopo. The relatively large urban area in the Orge may merely affect
12 the fast, high flow processes, which leads to low performances for $E_{NS,Q}$ in mHMtopo.
13 Nevertheless, a large area of the Orge catchment is still classified as wetland (see also Figure
14 1), adding several processes that only become dominant in the dry periods. Thus, the low
15 flow peaks may be more adequately represented in mHMtopo. Besides, the information of
16 low flow peaks is fully masked when looking at, for example, $E_{NS,Q}$ or $E_{NS,\log Q}$, as the relative
17 importance of peaks in low flows in these metrics is low. First, these metrics consider the
18 whole period of interest, instead of only the low flow period, and, second, the peaks are
19 relatively small compared to the average high flows. Hence, high performances in terms of
20 $E_{NS,Q}$ or $E_{NS,\log Q}$ may be misleading, which is very relevant for automatic calibration schemes
21 that often optimize towards these functions. Improvements in, for example, low flow peaks,
22 may remain unnoticed when calibrating on more general objective functions, such as $E_{NS,Q}$,
23 as they mostly rely on the absolute values of model residuals aggregated over the entire model
24 period. This is the result of the frequent absence of homoscedasticity in the model residuals.
25 Therefore, errors in high flows tend to have a higher weight in the objective function than
26 errors in low flows. For the Loisach, the findings are also in agreement with findings of
27 Velázquez et al. (2013) that in particular the performance of low flows depends on the choice
28 of the hydrological model. Apparently, here the low flow processes are not easy to capture as
29 in most hydrological models.

30 Results for the comparative analysis of the individual signatures instead of catchments
31 indicated a considerable degree of improvement for mHMtopo to represent low flows ($Q_{50,low}$,
32 $Q_{95,low}$, $Q_{5,low}$) and peaks during low flows ($Q_{peak,10}$, $Q_{low,peak,50}$) as can be seen in Figure 10a.

1 A probability distribution of the performance metric of a signature, so S_{RE} or S_{NS} , may
2 indicate whether the feasible space produces many solutions close to optimal. Ideally, a high
3 peak of the distribution function close to one indicates a strong ability of the model to
4 reproduce a certain signature, whereas a flat and widespread distribution or even negative
5 performance values, indicates a more reduced ability to reproduce the signature. Thus, the
6 improved ability of mHMtopo to reproduce low flow signatures becomes more obvious when
7 looking in detail at the probability distributions of, for example, $Q_{50,low}$ in the Treene
8 catchment (Figure 11). The original model of mHM only allows downward percolation and
9 infiltration, which leads to a larger buffer for soil moisture in dry periods. mHMtopo, on the
10 other hand, sustains a shallow groundwater table in wetlands through an upward flux, which
11 leads to a faster response and thus to a better representation of the peaks during dry periods.

12 In contrast, the 1-day autocorrelations for the total, low flow and high flow periods, are
13 consistently better represented in the original mHM (Figure 10a,b). This indicates that the
14 timing of the flow peaks is better represented in the original model. Likewise, the rising and
15 declining limb densities (RLD and DLD respectively) are also better captured by the original
16 mHM. Similar to the observation that mHM better captures the fast spikey peaks in the Orge
17 catchment, this suggests again that the more simple model structure (mHM) is able to respond
18 faster, while the more complex model structure (mHMtopo) tends to delay the flow of water.
19 A possible explanation for this observation is that the more complex model has more options,
20 in terms of reservoirs, to store the water. As linear reservoirs keep draining, the use of
21 multiple reservoirs can produce a delayed and flattened signal. In addition, as the flood peaks
22 now consist of contributions of the different reservoirs, more solutions exist to reconstruct
23 these flood peaks. These solutions could also contain flatter, delayed peaks, which affect the
24 1-day autocorrelation. More specifically, for fast responding catchments like the Orge and
25 Loisach, it means a poor representation of the 1-day autocorrelation in mHMtopo, which
26 offers more storage possibilities and thus more “memory” in the system. However, a closer
27 look at the distributions in detail shows that these differences are small. As an example,
28 Figure 12 shows the 1-day autocorrelation distributions for the Loisach catchment. Here, it is
29 apparent that the distributions of mHM and mHMtopo are in accordance.

30 The findings presented here are in line with some other comparison studies, such as Reed et
31 al. (2004), Nicolle et al. (2014), Orth et al. (2015) and te Linde (2008) who all found that
32 added complexity can but does not necessarily lead to improvements. However, in contrast

1 with Orth et al. (2015), we found that low flows are better represented by the complex
2 models, whereas they found that low flows were the best represented by a very simple model.
3 Nevertheless, it was stated by Staudinger et al. (2011) that processes in summer low flow
4 periods are more complex due to a stronger interaction between fast storages and evaporation.
5 Therefore, they did not find one particular model structure to represent low flows in summer.
6 In addition, the difficulties to represent low flows have been acknowledged by several
7 authors, such as Smakhtin et al. (2001), Pushpalatha et al. (2011) or Van Esse et al. (2013).

8

9 3.2.2 Effect of constraints

10 Figure 10c shows that the addition of prior constraints to mHM strongly improves the
11 signature representation, in particular for, again, the Treene. Apparently, the seasonal runoff
12 constraints help the model to represent the low flows better, which mHMtopo was able to do
13 through the additional processes included. As the upward flux from the groundwater in
14 mHMtopo is counterbalanced in the constrained mHM by different parameters that most
15 likely influence the fast reservoir coefficient and storage, it remains unclear which of the two
16 conceptualizations, i.e. mHM or mHMtopo, is more adequate in this case. Also the Loisach
17 shows a strong improvement when prior constraints are added to mHM (Figure 10c). The
18 reasoning considering the importance of snow still holds. The seasonal runoff constraints help
19 to identify parameter sets that are better able to reproduce the seasonal flows, which are
20 strongly affected by snowmelt.

21 The additional constraints imposed to mHM do not significantly affect the performance for
22 the Briance and Orge catchment, as can be seen by the nearly white rows in Figure 10c.
23 Notably, the runoff responses in these catchments are not snow dominated, and as evaporation
24 and rainfall are now out of phase, the original model was already able to capture the
25 seasonality reasonably well.

26 It can be clearly observed from Figure 10c,d that the applied prior constraints yield a strong
27 improvement, in particular on mHM, and in only about 29% (mHM) and 38% (mHMtopo) of
28 the cases a mostly weak performance reduction is observed. This indicates that, in spite of
29 being constrained by the transfer functions that link parameters to catchment characteristics,
30 additional prior constraints do still contain significant discriminatory information to identify
31 unfeasible model solutions, which is in agreement with findings of Hrachowitz et al. (2014).

1 The picture is less clear for applying constraints to mHMtopo, but improvements are still
2 observed for the majority of the signatures (Figure 10d; see also the empirical distribution
3 function at the bottom of the figures).

4 Alzette, Loisach and Orge show some deterioration when constraints are added (Figure 10d),
5 indicating that the topography specific constraints (Equations 4 and 5) may not be fully
6 applicable to these catchments. These catchments show a general decrease in the ability to
7 reproduce several signatures when comparing the unconstrained mHMtopo with the
8 constrained case (Figure 10d). This means that the unconstrained mHMtopo and also the
9 constrained mHM, that does not have these topography specific constraints, will outperform
10 the constrained mHMtopo with respect to these signatures. This is also supported by Figure
11 10b, that illustrates that for the Alzette, Loisach and Orge the addition of constraints to
12 mHMtopo leads to a reduced ability to represent most signatures compared to the constrained
13 mHM case (see the red pattern in Figure 10b). The rejection of these constraints implies that
14 for these catchments, soil moisture storage capacity in wetlands may be equal or even larger
15 than soil moisture storage capacity in the hillslope and plateau area. This may be true for the
16 Loisach, especially as Kunstmann et al. (2006) found that the karstic nature in these areas
17 even leads to water flowing from the neighboring Ammer catchment to the Loisach.
18 Considering these groundwater leakages, the model may need extra storage to correct for it in
19 the hydrograph.

20 In Figure 10c,d it may also be noted that the constraints do not add information to mHM and
21 mHMtopo with respect to the autocorrelation functions (AC , AC_{low} , AC_{high}) and rising and
22 declining limb densities (RLD, DLD). This makes sense as the applied constraints here
23 merely affect the seasonal patterns. Therefore, improvements can be observed for signatures
24 addressing low and high flow periods, such as $Q_{low,95}$ and $Q_{high,95}$.

25 Figure 10d shows that none of the signatures consistently improves or deteriorates. This
26 indicates that care must be taken by including more specific expert knowledge constraints.
27 General constraints, like the runoff constraints, can easily be applied to multiple catchments
28 and lead to improvements as Figure 10c shows, but assumptions about internal model
29 behavior should experimentally be well founded. Even though based on several experimental
30 studies, the topography based parameter constraints applied (Eqs. 4 and 5) were not suitable
31 in all cases, and lead to a random pattern of individual signature improvements/deterioration.
32 Thus, it was expected that additional constraints should narrow down the ‘plausible’

1 parameter space and would lead to more pronounced differences in performances.
2 Nevertheless, the results merely support findings of Holländer et al. (2009), where different
3 choices of expert modelers lead to a variety of outcomes.

4 3.2.3 Combined effect of constraints and sub-grid heterogeneity

5 Figure 10b shows the effect of additional sub-grid variability on the constrained models. Most
6 of the catchments show a slight overall improvement, indicated by the relatively blue shades
7 for Euclidian distance. In general, the patterns observed in Figure 10b are relatively similar to
8 the patterns observed in Figure 10a. It seems that the applied constraints generally enhance
9 the effects caused by the model structure. This can be seen from more darker colors of red and
10 blue, but also from the flatter distribution function (bottom of Figure 10b). Thus, when the
11 model has already a relatively large probability of improvement for certain signatures, the
12 constraints help to zoom in on the good solutions. When this is not the case, the model drifts
13 further away.

14 Nevertheless, the Briance and Broye show a more different effect, indicating a positive effect
15 of the constraints for mHMtopo. For the Briance, a red box for the Euclidian distance in
16 Figure 10a turned blue in Figure 10b. The Broye gained higher probabilities of improvement,
17 represented by more dark blue colors in Figure 10b. Apparently, the solutions maintained for
18 the unconstrained mHMtopo case still contained a relatively large number of implausible
19 solutions. Here, the application of constraints helped to narrow the solution space in such a
20 way that mHMtopo showed improvements compared with the original mHM.

21 However, it must be noted that the Alzette, Loisach and Orge show a relative low probability
22 of improvement again. This due to the rejection of the constraints given in Equations 4 and 5,
23 as discussed before in comparison with Figure 10d.

24 Figure 10e shows the combined effect of constraints and sub-grid heterogeneity on the
25 signature representation compared with the original, unconstrained mHM. The Euclidian
26 distance in the last column of Figure 10e, shows again that most catchments profit from the
27 addition of constraints and sub-grid heterogeneity to mHM. It was noted before that
28 mHMtopo has an improved ability to represent the low flow statistics, whereas the original
29 mHM better represented fast flows signatures like rising limb density (RLD) or
30 autocorrelation (AC). In Figure 10e, even a further contrast between the fast flow and low
31 flow domain can be observed. More particular, the Treene shows again the most

1 improvements. The rejection of the topography specific constraints in the Alzette, Loisach
2 and Orge introduce also in Figure 10e a more red pattern. Nevertheless, the overall
3 improvements in the low flow domains still lead to a general improvement in the Euclidian
4 distance D_E for the Alzette and Loisach. Only for the Orge catchment, influenced largely by
5 human disturbances, the Euclidian distance D_E shows a clear deterioration in performance.

6

7 **3.3 Transferability comparison**

8 In a next step, the two models mHM and mHMtopo were calibrated simultaneously on the
9 four catchments Orge, Treene, Broye and Loisach. The parameters were then transferred
10 without further calibration to the three remaining receiver catchments Alzette, Briance and
11 Kinzig. As shown in Figure 13, both models provide a relatively good performance in the
12 validation period with respect to all four calibration objective functions in the receiver
13 catchments as compared to the individual calibration for the same catchments. Compared
14 with the base case of mHM, the Euclidian distances obtained from the calibration objective
15 functions values changed by 2% (mHM with constraints), -4% (mHMtopo) and 1%
16 (mHMtopo with constraints). The Euclidian distances for the signatures improved by 2% for
17 the constrained mHM case. However, mHMtopo had a decrease of 5% and the Euclidian
18 distance almost doubled for the constrained mHMtopo case.

19 **3.3.1 Effect of sub-grid heterogeneity**

20 In general, mHM and mHMtopo showed a considerable ability to reproduce similar objective
21 function values as in the individual calibrations (Figure 13). Both models kept a reasonable
22 performance during validation in terms of the objective function values and did not fail in
23 reproducing the hydrograph with the parameters received from the donor catchments.

24 For the Alzette, the results obtained with mHM (blue in Figure 13) and mHMtopo (red in
25 Figure 13) are almost identical. For the Briance and Kinzig catchments it is noted that the
26 introduction of sub-grid process heterogeneity, i.e. mHMtopo, leads to a less transferable
27 model. In particular $E_{NS,logQ}$ and $E_{NS,FDC}$ experience a strong decrease in performance (Figure
28 13). The results also suggest that, in the unconstrained case, the original mHM is better
29 transferable than mHMtopo with respect to catchment signatures (Figure 14a). Most
30 signatures show a low probability of improvement, only some signatures that consider peaks

1 during the low flow periods have a relatively high (blue pattern in Figure 14a) probability of
2 improvement. This indicates again that the more complex mHMtopo mostly affects the low
3 flows.

4 It should be noted that the transfer functions used in mHMtopo were adopted for similar
5 parameters from the original mHM. However, it may well be that the assumed functional
6 relations are less valid in a more complex setting. The MPR was developed around the simple
7 model structure, and also refined several times (Samaniego et al, 2010; Kumar et al., 2013a).
8 Similar efforts are required for refining the regionalization for a topography driven model in
9 order to make mHMtopo as transferable as the original mHM. In addition, the global
10 parameter ranges, that do not have a real physical meaning, were also derived for the original
11 mHM and may need adjustments for mHMtopo.

12 3.3.2 Effect of constraints

13 Imposing prior constraints in mHMtopo leads to a strong increase in performance again in the
14 Kinzig catchment compared to the unconstrained case (Figure 13). This indicates that the
15 applied constraints are very suitable for this catchment, but less for the Briance catchment,
16 where only a minor improvement is observed. The Kinzig catchment is characterized by a
17 rather large elevation difference and relatively high contribution of snow, similar to the
18 Loisach catchment. Hence, the same reasoning for this catchment holds as for the Loisach
19 catchment that the seasonal runoff constraints help in the seasonal flow patterns. Besides, the
20 role of the input data may likely influence the modelling results for this catchment, since the
21 Kinzig catchment has a large difference in elevation.

22 When comparing the signatures for the constrained mHM and mHMtopo (Figure 14b), it can
23 be observed that the Alzette and Kinzig catchments benefit from additional process
24 heterogeneity and constraints, while the constrained mHM is still better representing the
25 signatures in the Briance catchment. In general, the constraints do not have much influence on
26 the Briance catchment, as indicated by a relatively white row in Figures 14c and 14d. The
27 unconstrained mHM already was better transferable for this catchment compared to
28 mHMtopo (see Figure 14a), this remains the same in the constrained cases. The other two
29 catchments are much more sensitive to the constraints and show now a better transferability,
30 in particular with respect to the low flow signatures.

1 Furthermore, results shown in Figures 14c,d suggest that prior constraints can add
2 transferability to both models in terms of signatures as highlighted by the probability of
3 improvements for most signatures. For the Kinzig catchment the constrained mHMtopo
4 model is clearly better transferable than the unconstrained mHMtopo as well as mHM with
5 constraints. This was already noted before, when looking at the performances (Figure 13), but
6 it is here confirmed for the signatures.

7 In general, it can be stated that the addition of topography-guided sub-grid process
8 heterogeneity *per se* does not necessarily lead to a pronounced difference in model
9 transferability in all parts of flow regimes. Some improvements were noticed in low flow
10 signature measures. Significant improvements can rather be observed when applying
11 constraints, as illustrated in in Figures 14c,d. The addition of constraints to mHMtopo shows
12 high probabilities of improvements over the full range of signatures (Figure 14d), in particular
13 for the Kinzig. Also for mHM (Figure 14c), even though more moderate, most of the
14 signatures show a relatively large probability of improvement when applying constraints. This
15 test of model transferability underlines the considerable potential of prior constraints to
16 improve the representation of hydrological signatures.

17 3.3.3 Effect of constraints and sub-grid heterogeneity

18 In the transferability test, Alzette and Kinzig have an improved signature representation in
19 terms of the Euclidian distance when constraints and sub-grid heterogeneity both are added to
20 mHM, as can be seen in Figure 14e. For these catchments, the biggest improvements ,
21 compared with the base case of the unconstrained mHM, are again observed for the low flow
22 statistics.

23 The Briance catchment shows a general decrease in the ability to represent the signatures. The
24 constraints did not help here (white rows in Figure 14d) and from Figure 14a it was already
25 observed that the unconstrained mHM was more transferable than mHMtopo. Looking back
26 at Figure 10a, it can also be noted that in the individual calibration mHM slightly
27 outperformed mHMtopo for this catchment with respect to the signatures (lightred Euclidian
28 distance). This indicates that the processes in mHMtopo may not adequately represent the
29 processes in this catchment, which is emphasized when the model receives the parameters
30 derived in other catchments. In addition, the derived global relations may not hold for this
31 catchment. Apparently, this catchment, which is gently sloped with agriculture, is

1 significantly different from the other catchments used in calibration. The calibration
2 catchments of Loisach and Broye are more mountainous catchments, whereas the Treene is
3 very flat and wetland dominated. In nature, the Orge catchment should be relatively similar,
4 but this catchment is strongly affected by urbanization.

5 **3.4 General limitations and outlook**

6 It should be noted that the input data may have a big influence on the experiment. For
7 example, the input resolution of the E-OBS forcing data is 24km by 24km, while the
8 catchments are relatively small. In a few cases, the catchments are just covered by a couple of
9 E-OBS data-cells. In addition, as the E-OBS data is a product derived from the interpolation
10 of station data, peaks in rainfall may have been averaged out. In such cases, the detailed
11 process representation in mHMtopo may thus not be warranted. Due to pronounced
12 topography-induced precipitation heterogeneity (e.g. Hrachowitz and Weiler, 2011) this will
13 be more problematic for catchments with marked relief than for catchments that are
14 characterized by a more subdued topography. For example, the Treene benefits most from
15 mHMtopo and is very flat, whereas the steep Loisach needs additional constraints.

16 In addition to this, one may wonder what the effect of a different spatial model resolution
17 would be. In the extreme case where one modeling cell could be classified as a certain
18 landscape as a whole, the relative importance of the different processes in mHMtopo will
19 increase. Thus, when the assumed processes in the cell are adequate, the performance will
20 increase. Nevertheless, incorrect functional relations may also become more apparent on finer
21 modelling scales as less upscaling is required.

22 The assumptions made in the applied functional relationships may also affect the outcomes of
23 this experiment. In future work, these relationship may need refinement for mHMtopo.
24 Besides this, the threshold values to delineate the landscape units were originally derived for
25 one specific catchment. The general validity of these thresholds needs to be tested in future
26 research.

27 **4 Conclusions**

28 In this study the value of incorporating topography-controlled sub-grid process heterogeneity
29 together with semi-quantitative model constraints to increase hydrological consistency and
30 spatial transferability of the distributed, conceptual model mHM was tested. Both, the

1 unconstrained and constrained applications of the original mHM and the topography-based
2 mHMtopo were applied to seven distinct catchments across Europe.

3 On balance, the addition of topography-based sub-grid process heterogeneity moderately
4 improved mHM. Different hydrological signatures indicated that in particular the
5 representation of low flows improved by allowing for increased sub-grid process
6 heterogeneity. This could be contributed mostly to additional processes which were missing
7 in the original mHM. Especially in catchments where the process of capillary rise is likely to
8 be more important, it became clear that low flows signatures were better represented.
9 Nevertheless, the timing of flow peaks was better captured by the original mHM model. In
10 summary, the addition of topography based sub-grid process heterogeneity in the model
11 structure of a distributed model regionalized through soil and land use, was to a moderate
12 degree able to improve the general model performance in the study catchments while more
13 adequately reflecting internal processes.

14 The use of prior, semi-quantitative constraints proved highly effective in the study catchments
15 as it forces the model to reproduce plausible patterns of partitioning between runoff and
16 evaporative fluxes. Especially in cases where runoff and evaporation are out of phase, the
17 constraints were shown to be valuable. These conclusions were largely drawn from the
18 models' varying ability to reproduce observed catchment signatures.

19 In addition, it was shown that such an improved hydrological consistency at the sub-grid scale
20 combined with the use of suitable model constraints and functional relationships, can be
21 beneficial for transferring models and predicting flows without further calibration in other
22 catchments.

23 Concluding, the addition of topography-based sub-grid process heterogeneity and the use of
24 prior semi- quantitative constraints were shown to be promising and lead to moderate
25 improvements in terms of process representation and transferability.

26

1 **Acknowledgements**

2 We would like to acknowledge the European Commission FP7 funded research project
3 “Sharing Water-related Information to Tackle Changes in the Hydrosphere– for Operational
4 Needs” (SWITCH-ON, grant agreement number 603587), as this study was conducted within
5 the context of SWITCH-ON.

6 We acknowledge the E-OBS dataset from the EU-FP6 project ENSEMBLES
7 (<http://ensembles-eu.metoffice.com>) and the data providers in the ECA&D project
8 (<http://www.ecad.eu>)

9 We acknowledge The Global Runoff Data Centre, D -56002 Koblenz, Germany for providing
10 discharge data.

11

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19

1 Table 1. Overview of the catchments .

Catchment	Country	Area (km ²)	Elevation (mMSL)	Runoff (mm/y)	Aridity Index (EP/P) (-)	Calibration period	Validation period
Alzette	Luxembourg	1172	194-545	286	0.90	01-01-1978 31-12-1980	01-01-1983 31-12-1987
Briance	France	604	211-719	377	0.88	01-01-1982 01-07-1993	02-07-1993 31-12-2004
Broye	Switzerland	396	391-1494	648	0.71	01-01-1995 02-07-1987	03-07-1987 31-12-2009
Kinzig	Germany	955	172-1084	759	0.67	01-01-1951 31-12-1971	01-01-1971 31-12-1990
Loisach	Germany	243	716-2783	960	0.50	01-01-1976 31-12-1988	01-01-1989 31-12-2001
Orge	France	965	38-196	130	1.34	01-01-1968 01-07-1986	02-07-1986 31-12-2004
Treene	Germany	481	-1-80	428	0.75	01-01-1974 01-07-1989	02-07-1989 31-12-2004

2

3

1 Table 2. Overview of the used data.

Data type	Product	Source	Reference
Soil	HWSD	http://webarchive.iiasa.ac.at/Research/LUC/External-World-soil-database/HTML/index.html?sb=1	FAO/IIASA/ISRIC/ISSCAS/JRC (2012)
Topography	SRTM	http://hydrosheds.cr.usgs.gov/index.php	Lehner et al. (2008)
Discharge	GRDC	http://www.bafg.de/GRDC/EN/01_GRDC/13_dtbse/database_node.html	The Global Runoff Data Centre, D -56002 Koblenz, Germany
Precipitation	E-OBS	http://eca.knmi.nl/download/ensembles/ensembles.php	Haylock et al. (2008)
Landcover	Globcover	http://due.esrin.esa.int/page_globcover.php	Arino et al. (2009)

2

3

1 Table 3. Overview of the used signatures.

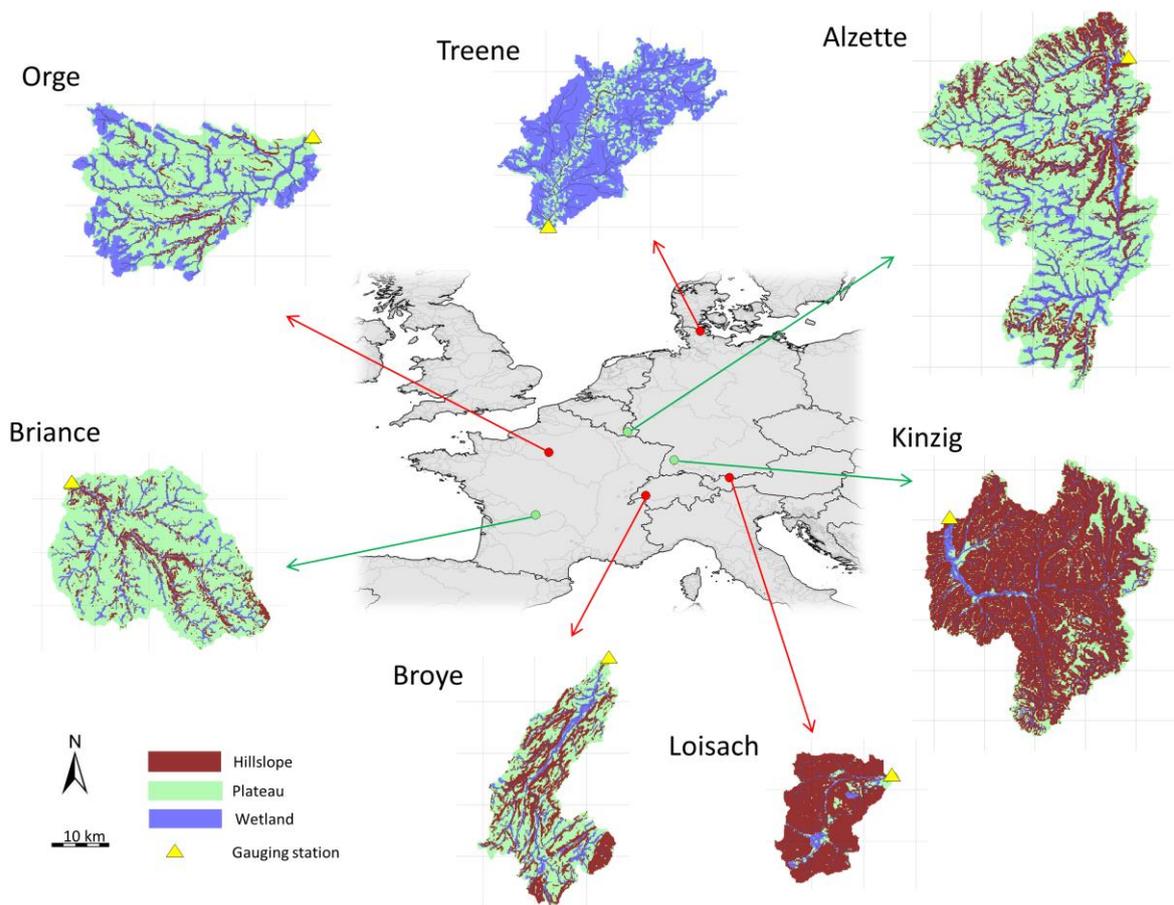
Signature	Description	Reference
Q_{MA}	Mean annual runoff	
AC	One day autocorrelation coefficient	Montanari and Toth (2007)
AC_{low}	One day autocorrelation low flow period	Euser et al. (2013)
AC_{high}	One day autocorrelation high flow period	Euser et al. (2013)
RLD	Rising limb density	Shamir et al. (2005)
DLD	Declining limb density	Shamir et al. (2005)
Q_5	Flow exceeded in 5% of the time	Jothityangkoon et al. (2001)
Q_{50}	Flow exceeded in 50% of the time	Jothityangkoon et al. (2001)
Q_{95}	Flow exceeded in 95% of the time	Jothityangkoon et al. (2001)
$Q_{5,low}$	Flow exceeded in 5% of the low flow time	Yilmaz et al. (2008)
$Q_{50,low}$	Flow exceeded in 50% of the low flow time	Yilmaz et al. (2008)
$Q_{95,low}$	Flow exceeded in 95% of the low flow time	Yilmaz et al. (2008)
$Q_{5,high}$	Flow exceeded in 5% of the high flow time	Yilmaz et al. (2008)
$Q_{50,high}$	Flow exceeded in 50% of the high flow time	Yilmaz et al. (2008)
$Q_{95,high}$	Flow exceeded in 95% of the high flow time	Yilmaz et al. (2008)
Peaks	Peak distribution	Euser et al. (2013)
$Peaks_{low}$	Peak distribution low flow period	Euser et al. (2013)
$Peaks_{high}$	Peak distribution high flow period	Euser et al. (2013)
$Q_{peak,10}$	Flow exceeded in 10% of the peaks	
$Q_{peak,50}$	Flow exceeded in 50% of the peaks	
$Q_{low,peak,10}$	Flow exceeded in 10% of the low flow peaks	
$Q_{low,peak,50}$	Flow exceeded in 10% of the low flow peaks	
$Q_{high,peak,10}$	Flow exceeded in 10% of the high flow peaks	

$Q_{\text{high,peak},50}$ Flow exceeded in 50% of the high flow peaks

AC_{serie} Autocorrelation series (200 days lag time) Montanari and Toth (2007)

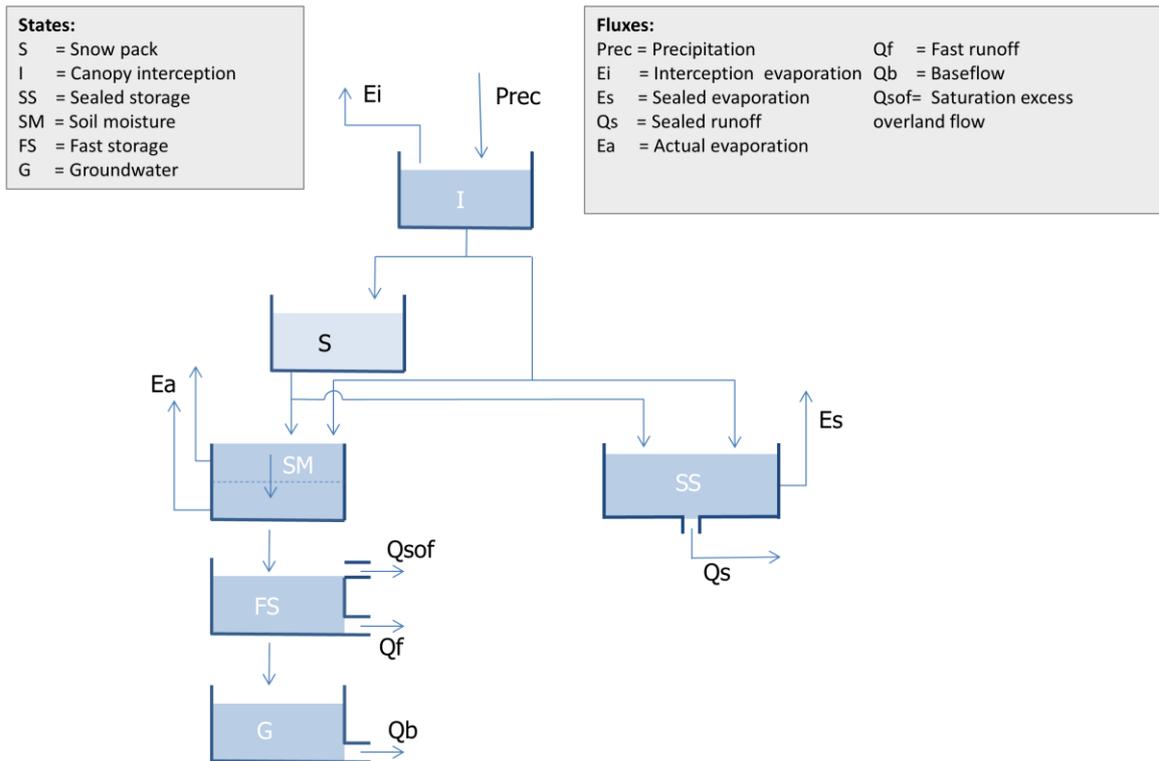
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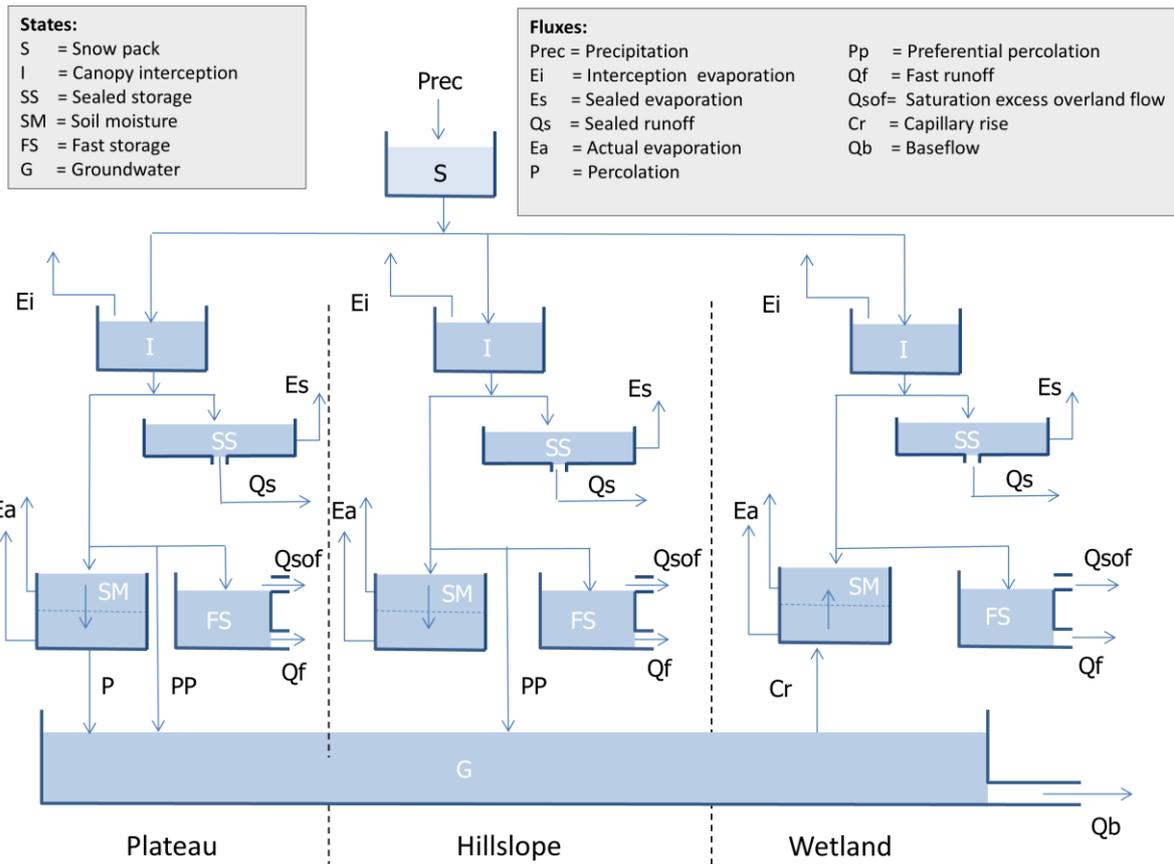


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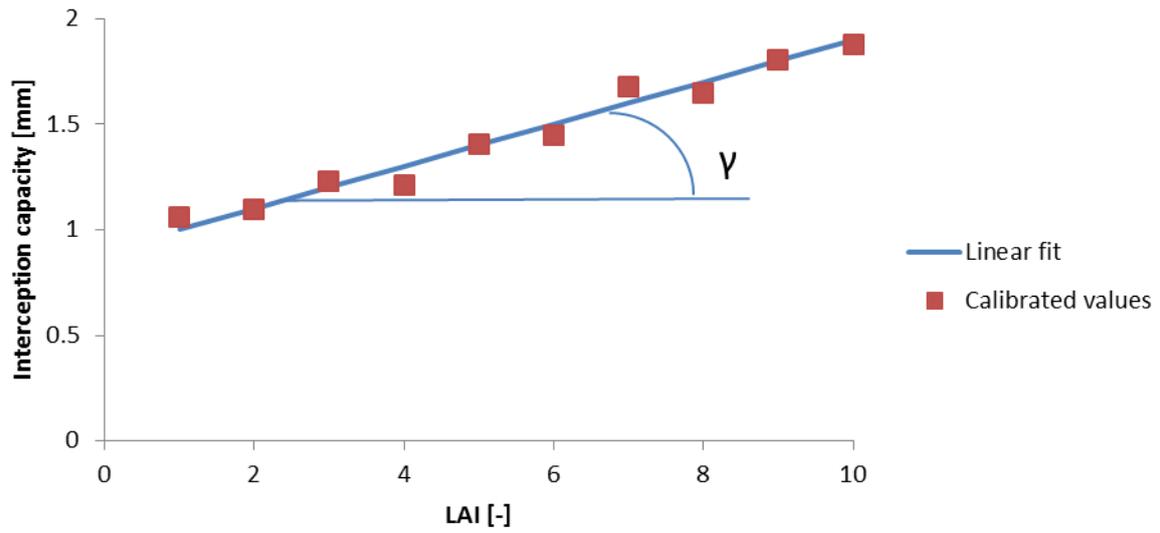
Figure 1. The location of the seven study catchments and their respective landscape classes according to HAND and local slope. Catchments represented by red and green symbols in the context map indicate donor and receiver catchments, respectively, for the transferability analysis. Displayed grids correspond to the modelling grids used in mHM(topo).



1
 2 Figure 2. The original mHM model structure. The effective precipitation is determined by an
 3 interception (I) and snow routine (S). Afterwards, the effective precipitation enters a soil
 4 moisture reservoir (SM) or is directly routed to a fast reservoir that accounts for sealed areas
 5 (SS). The water in the soil moisture reservoir either transpires or percolates further down to a
 6 fast runoff reservoir (FS), i.e. shallow subsurface flow. Eventually, the base flow component
 7 of the runoff is obtained from a slow groundwater reservoir (G).



1
2 Figure 3. The mHMtopo model structure with different configurations of states and fluxes for
3 the landscape classes plateau, hillslope, and wetland, which are based on topography. First, a
4 shared snow module (S) divides the effective precipitation over the landscape classes. The
5 three classes all have an interception module (I), fast reservoir accounting for sealed areas
6 (SS), soil moisture routine (SM) and fast reservoir (FS). The plateau landscapes are assumed
7 to feed the groundwater through percolation (P) from the soil moisture and preferential
8 percolation (PP). The steeper hillslope areas are assumed to merely feed the groundwater
9 through preferential percolation (PP), whereas the wetlands receive water through capillary
10 rise (Cr). The base flow is determined by a shared groundwater reservoir.
11

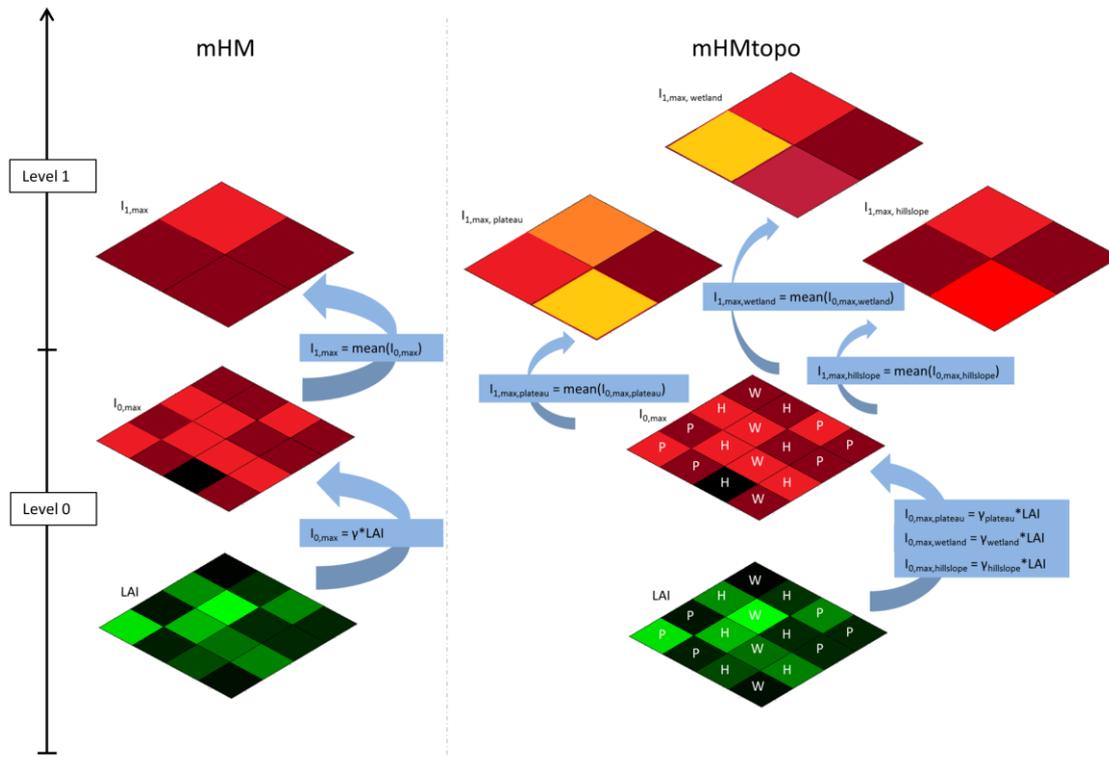


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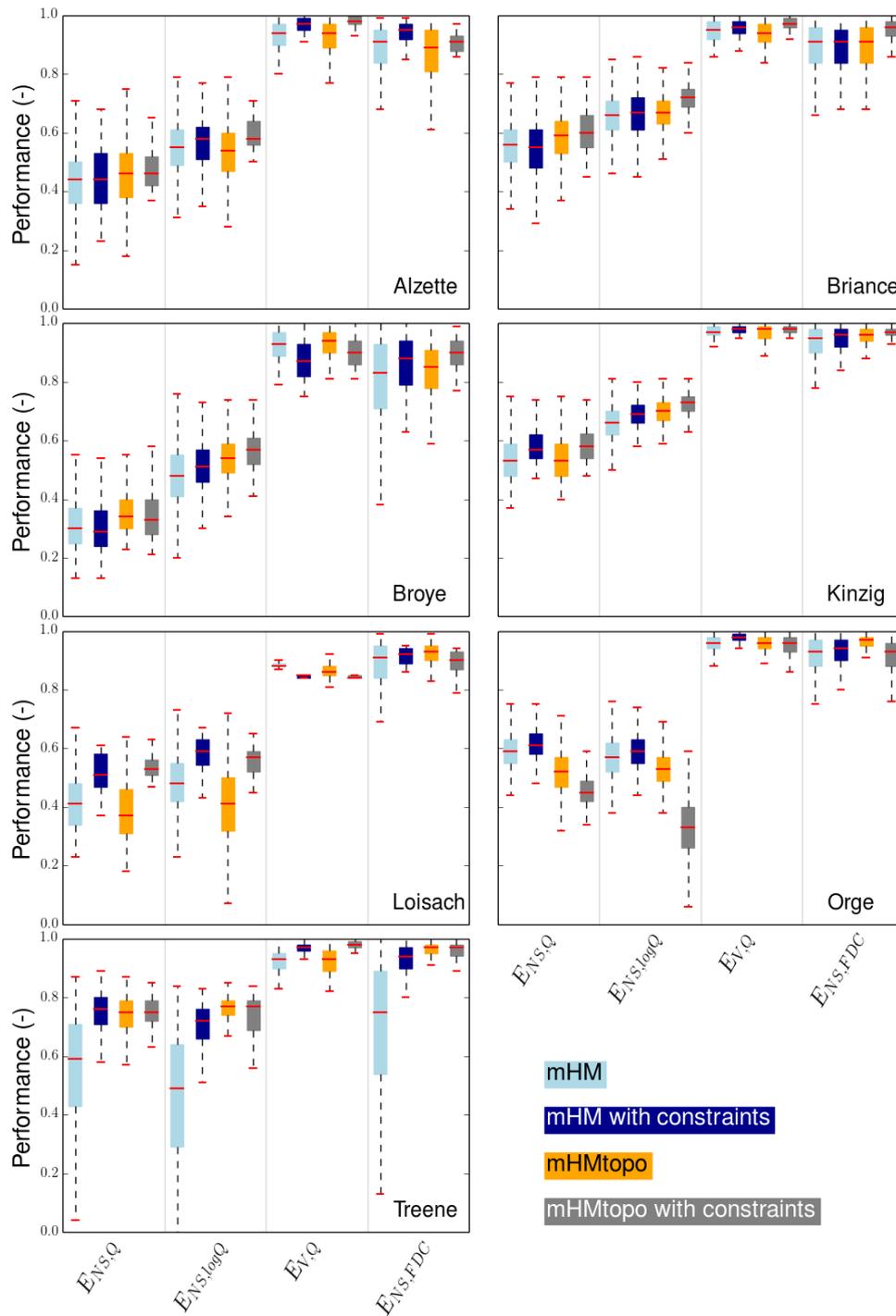
2 Figure 4. Function relationship between leaf area index (LAI) and the hydrologic parameter
 3 interception capacity ($I_{0,max}$) defined by the global parameter γ , based on fictional data for
 4 illustration.

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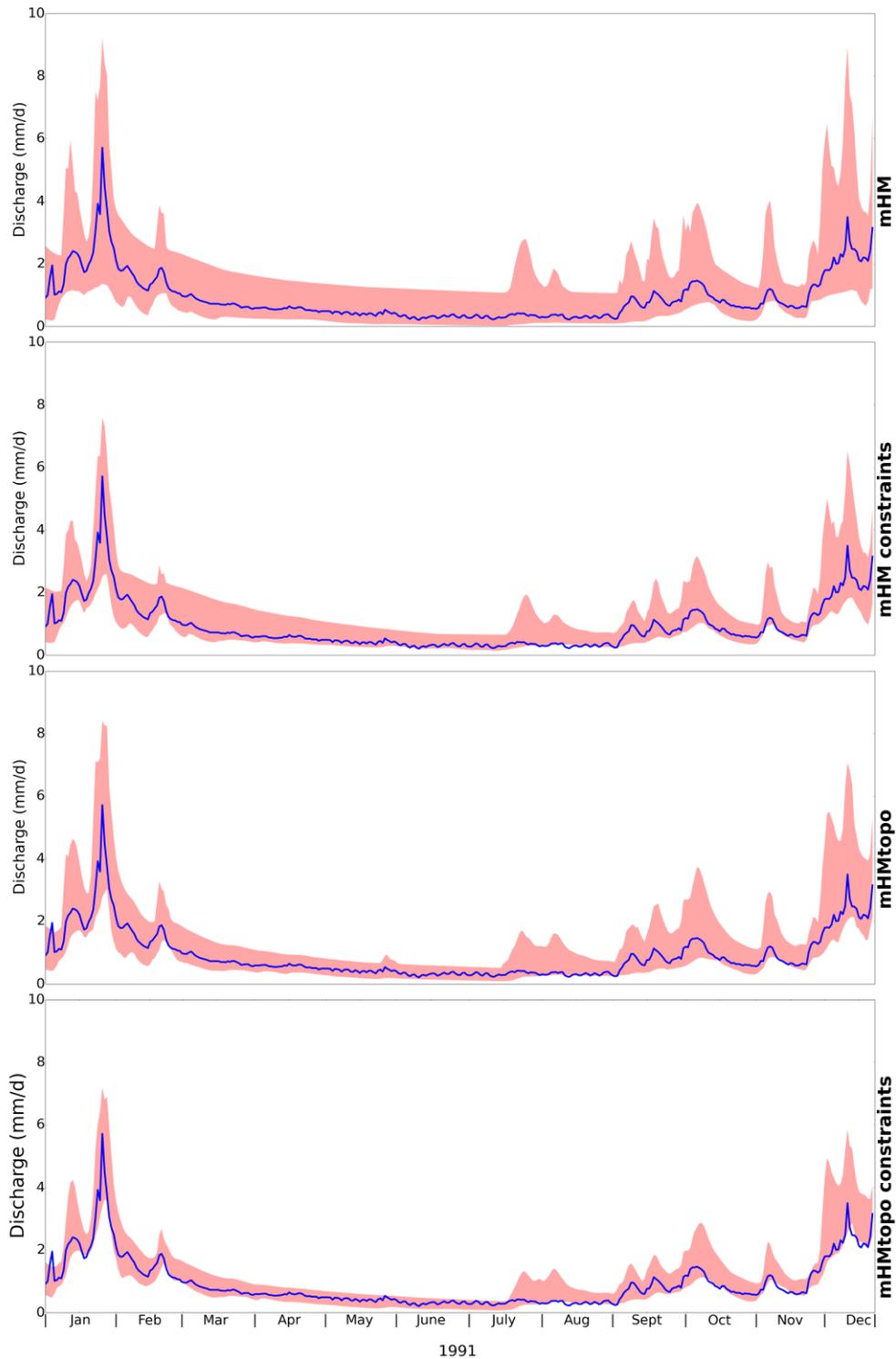
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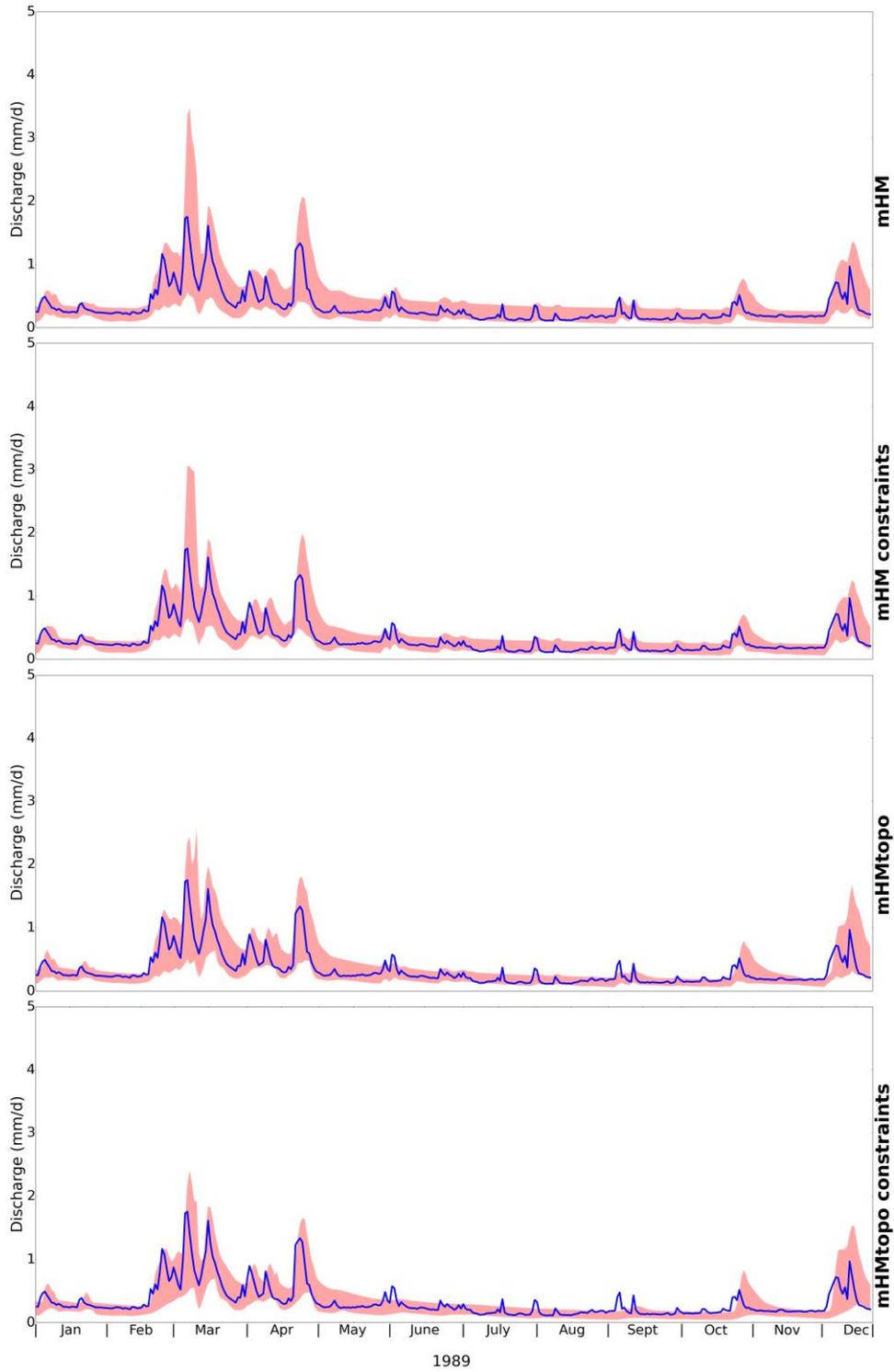
1
 2 Figure 5. Schematic representation of the original MPR (left) and the adjusted MPR (right)
 3 for the maximum interception capacity ($I_{1,max}$). On the input level 0, the leaf area index (LAI)
 4 is linked through the global, generally valid, parameter γ with $I_{0,max}$. In a last step, the mean is
 5 used for upscaling, yielding $I_{1,max}$ at the modelling resolution. For mHMtopo, the functional
 6 relations are the same, but plateau (P), hillslope (H) and wetland (W) have their own global
 7 parameters γ . The upscaling is subsequently carried out over each landscape class within each
 8 grid cell. This leads to the interception capacities of plateau, hillslope and wetland ($I_{1,max,plateau}$,
 9 $I_{1,max,hillslope}$ and $I_{1,max,wetland}$).
 10



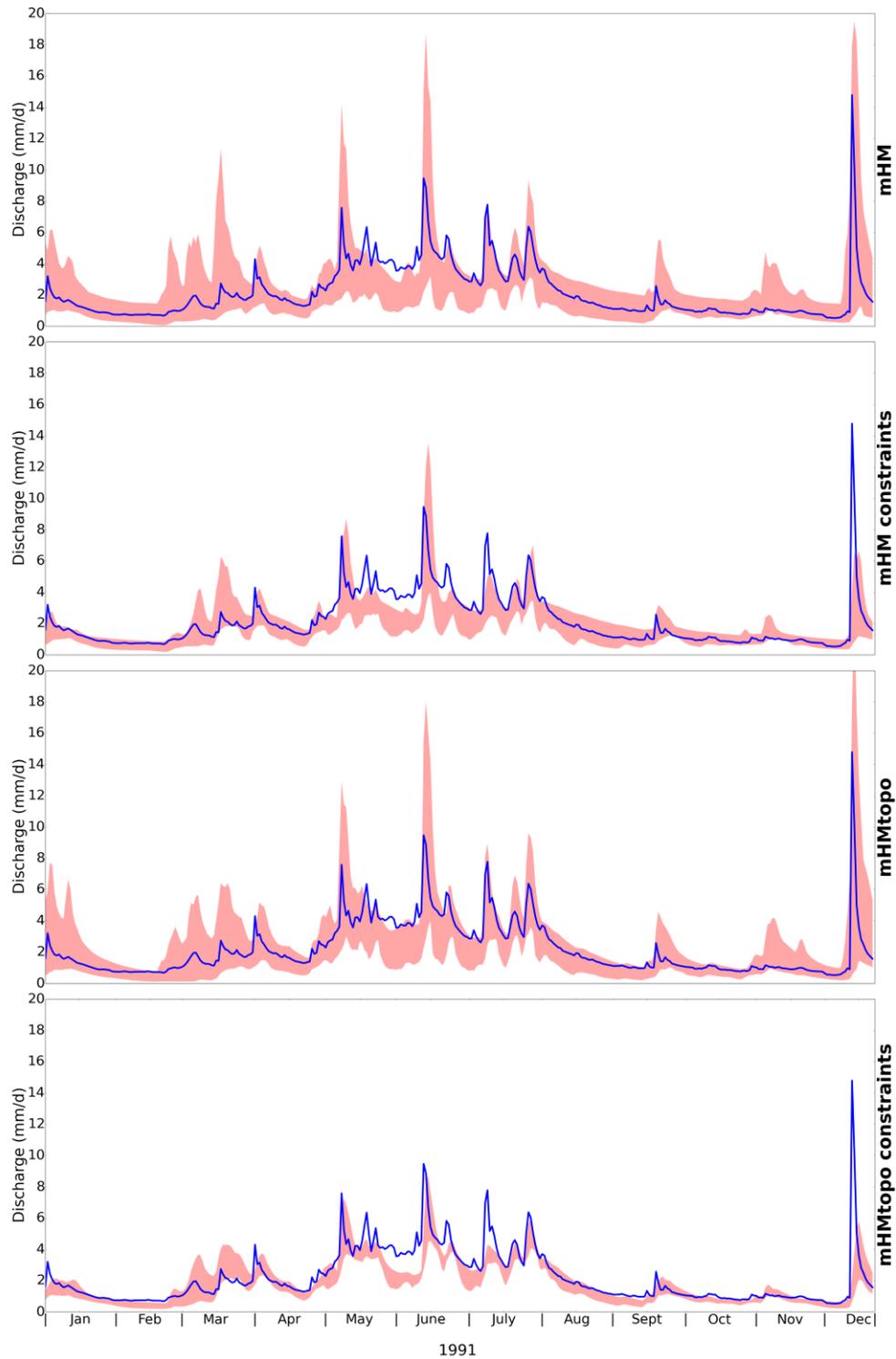
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 2 Figure 6. Nash-Sutcliffe efficiency ($E_{NS,Q}$), log Nash-Sutcliffe efficiency ($E_{NS,\log Q}$), volume
 3 error ($E_{V,Q}$) and log Nash-Sutcliffe efficiency of the flow duration curve ($E_{NS,FDC}$) for the
 4 seven catchments in the validation periods. The optimal value for all four criteria is 1,
 5 whereas 0 is regarded to have a low performance. The boxplots are formed by the Pareto
 6 space spanned by the four objective functions.



1
 2 Figure 7. Hydrographs for the Treene catchment, with respectively the hydrographs for mHM,
 3 mHM with constraints, mHMtopo and mHMtopo with constraints. The red shaded areas
 4 represent the envelope spanned by all feasible solutions, whereas the blue line corresponds to
 5 observed values.



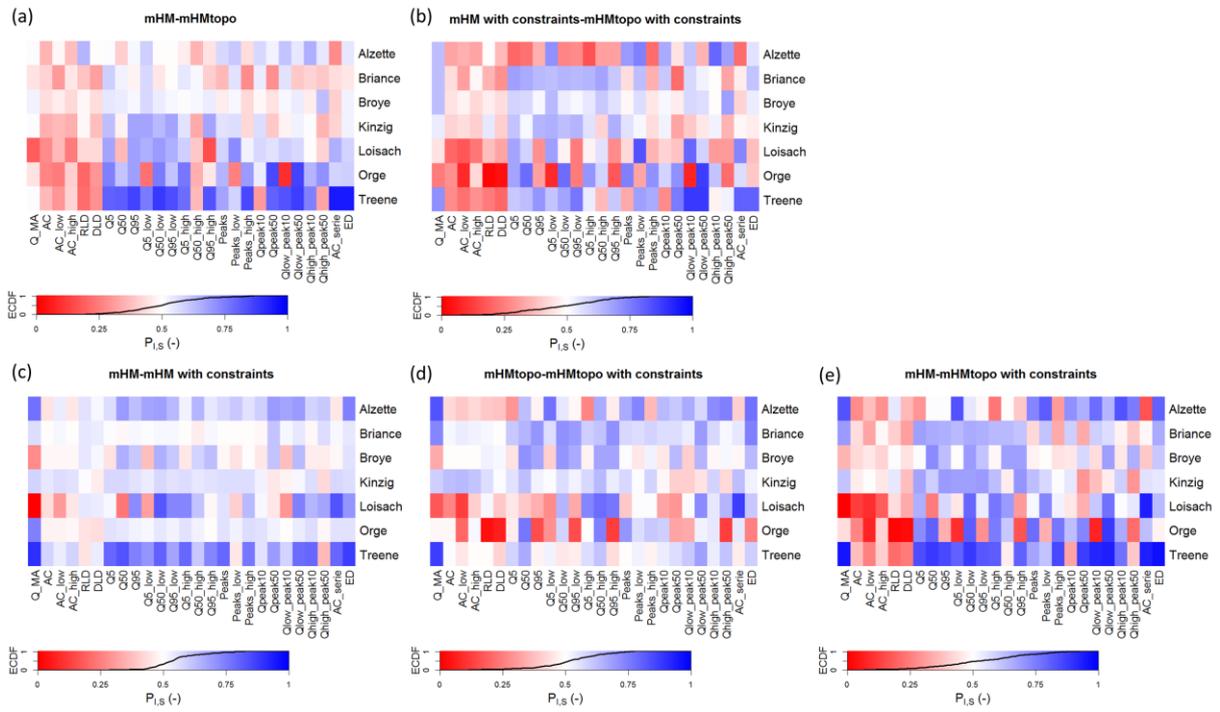
1
 2 Figure 8. Hydrographs for the Orge catchment, with respectively the hydrographs for mHM,
 3 mHM with constraints, mHMtopo and mHMtopo with constraints. The red shaded areas
 4 represent the envelope spanned by all feasible solutions, whereas the blue line corresponds to
 5 observed values.



1

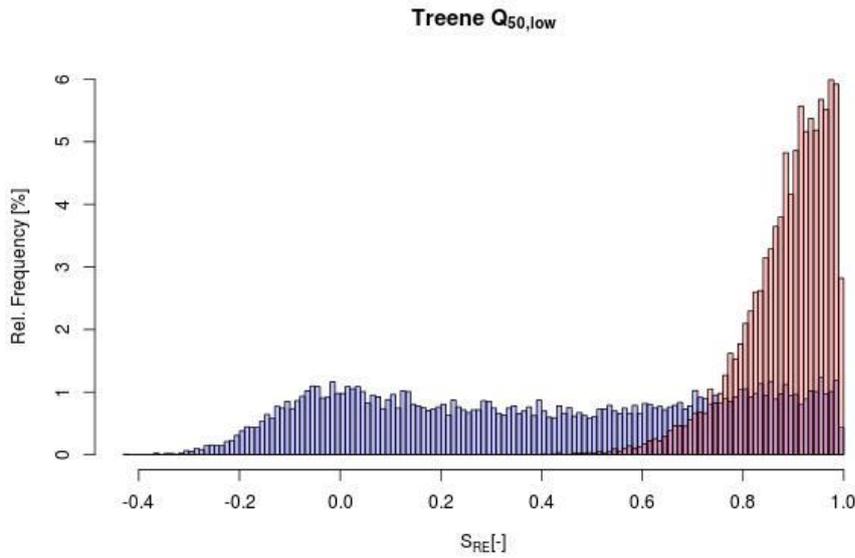
2 Figure 9. Hydrographs for the Loisach catchment, with respectively the hydrographs for
 3 mHM, mHM with constraints, mHMtopo and mHMtopo with constraints. The red shaded
 4 areas represent the envelope spanned by all feasible solutions, whereas the blue line
 5 corresponds to observed values.

6

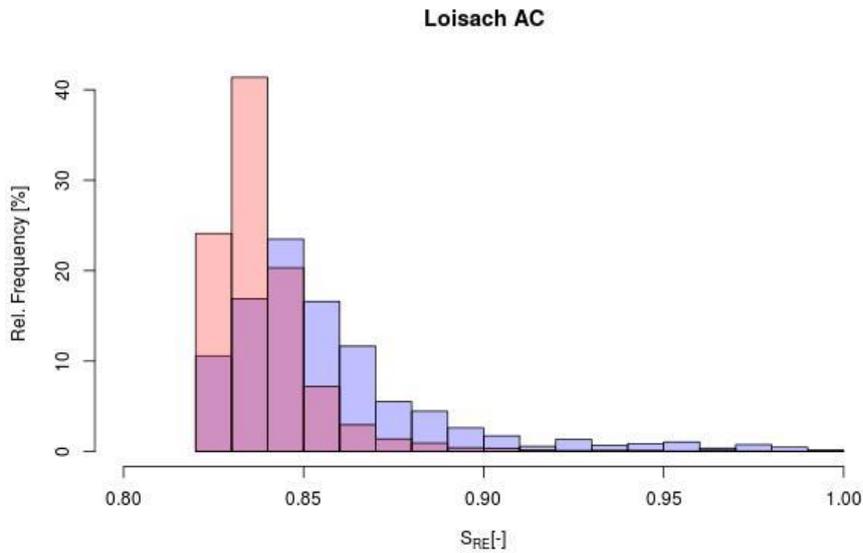


1
2 Figure 10. Probabilities of improvements $P_{I,S}$ between (a) mHM and mHMtopo without
3 constraints and (b) with constraints, (c) mHM with and without constraints, (d) mHMtopo
4 with and without constraints and (e) the base case mHM with the constrained mHMtopo case.
5 The colours are linearly related to probability of improvement between 0 (dark red; e.g.
6 probability of mHMtopo outperforming mHM is 0), 0.5 (white; i.e. models are statistically
7 equivalent) and 1 (dark blue; e.g. probability of mHMtopo outperforming mHM is 1). An
8 empirical cumulative distribution function (ECDF) based on all probabilities of improvement
9 has been added to assess the distribution of these probabilities.

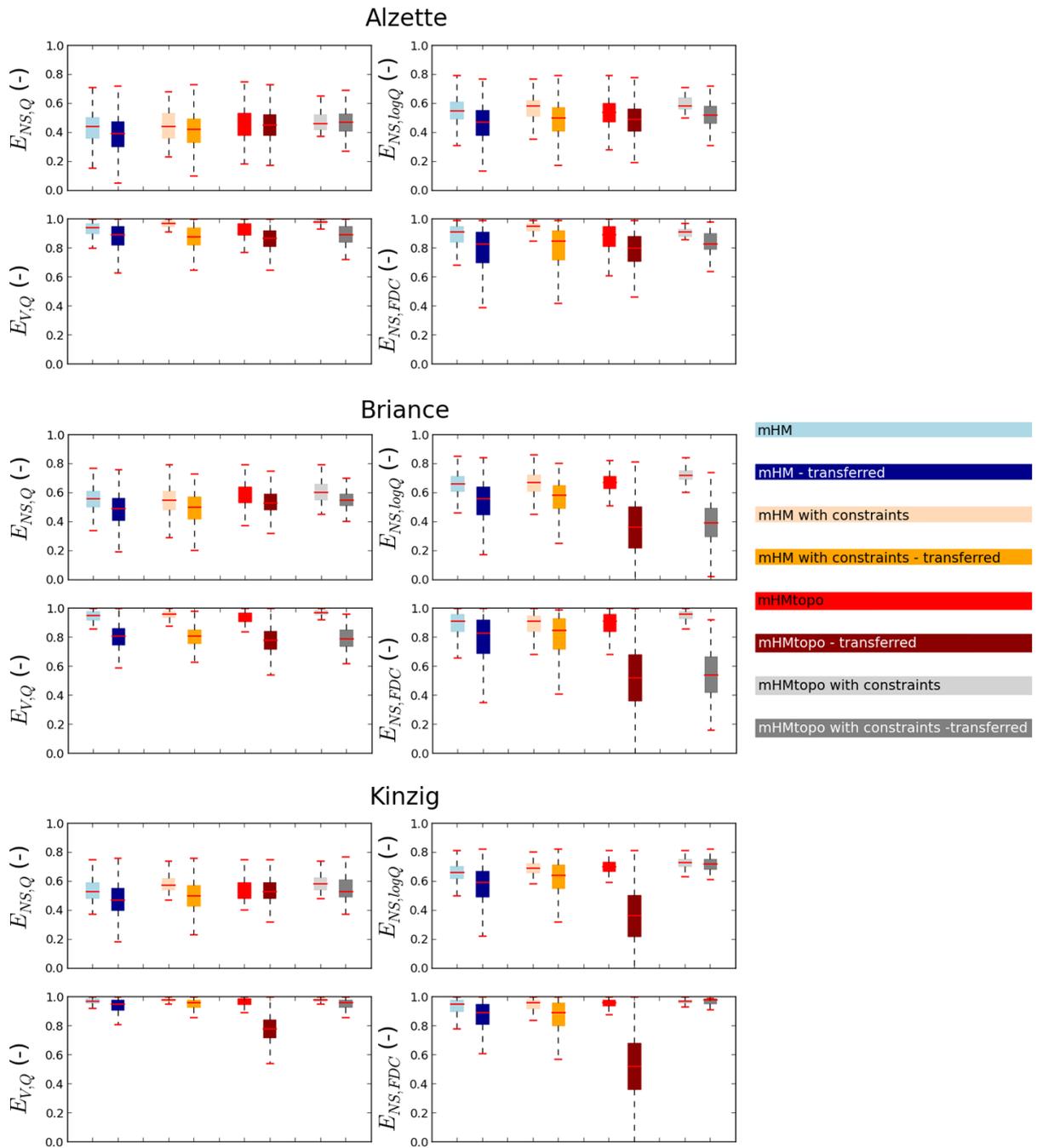
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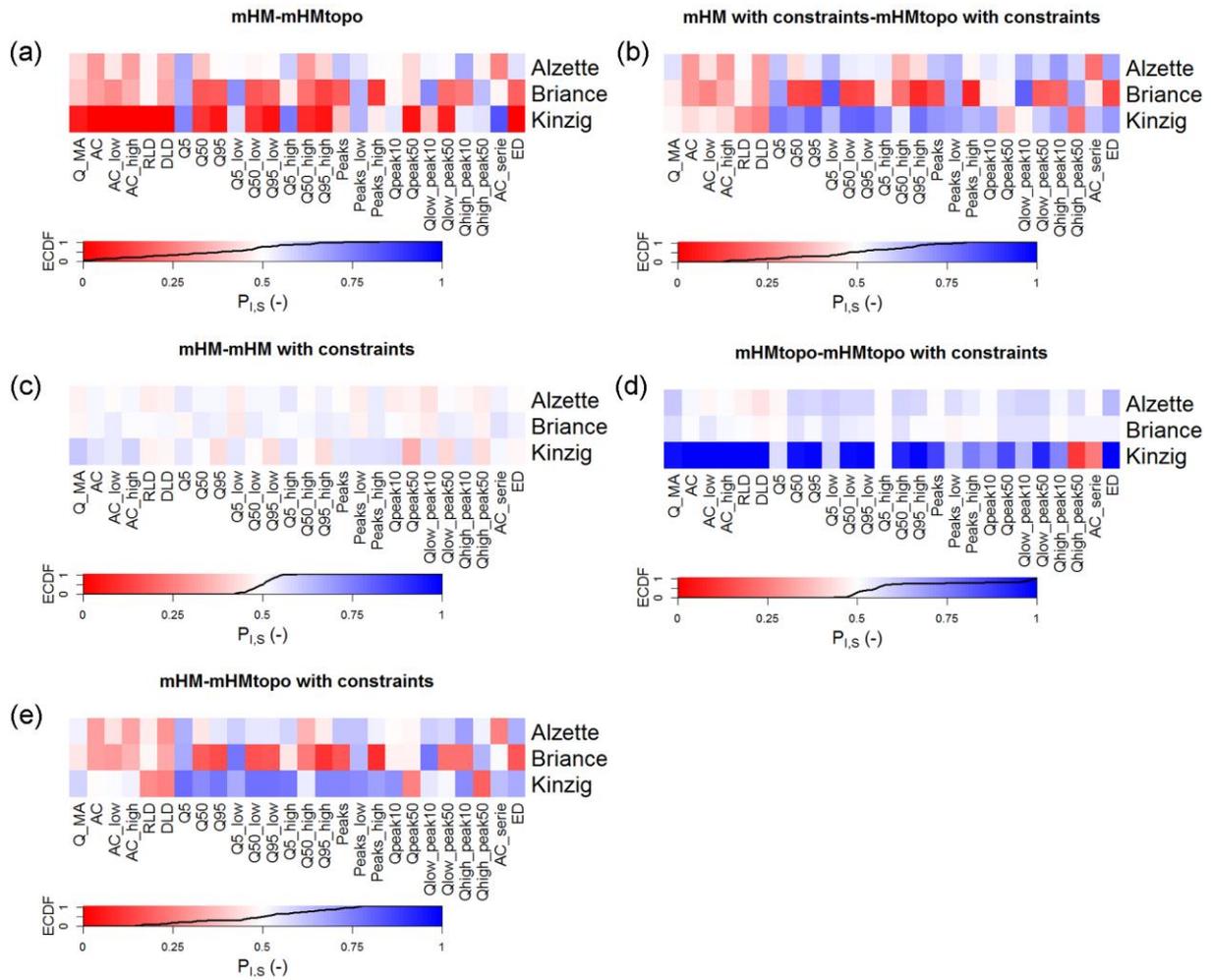
1
 2 Figure 11. Histograms of the performance distributions for the median of the low flows
 3 $Q_{50,low}$ for the Treene catchment on basis of all feasible parameter sets of mHM (blue) and
 4 mHMtopo (red). The performance S_{RE} is defined as 1 minus the relative error, leading to an
 5 optimal value of 1.



6
 7 Figure 12. Histograms of the performance distributions for the 1-day autocorrelation of flows
 8 for the Loisach catchment on basis of all feasible parameter sets of mHM (blue) and
 9 mHMtopo (red). The performance E_{RE} is defined as 1 minus the relative error, leading to an
 10 optimal value of 1.
 11



1
 2 Figure 13. Objective function values of the (a) Alzette, (b) Briance and (c) Kinzig catchments
 3 in the validation period for individual calibration (light colours) and when using parameters
 4 transferred from the remaining four donor catchments in the multibasin calibration (darker
 5 colours).
 6



1
 2 Figure 14. Probabilities of improvements $P_{I,S}$ between (a) mHM and mHMtopo without
 3 constraints and (b) with constraints, (c) mHM with and without constraints, (d) mHMtopo
 4 with and without constraints and (e) the base case mHM with the constrained mHMtopo case,
 5 all after the transfer of global parameters to the three catchments. The colours are linearly
 6 related to probability of improvement between 0 (dark red; e.g. probability of mHMtopo
 7 outperforming mHM is 0), 0.5 (white; i.e. models are statistically equivalent) and 1 (dark
 8 blue; e.g. probability of mHMtopo outperforming mHM is 1). An empirical cumulative
 9 distribution function (ECDF) based on all probabilities of improvement has been added to
 10 assess the distribution of these probabilities.

11
 12