Creating long term gridded fields of reference evapotranspiration in Alpine terrain based on a re-calibrated Hargreaves method

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Abstract

A new approach for the construction of high resolution gridded fields of reference evapotranspiration for the Austrian domain on a daily time step is presented. Gridded data of minimum and maximum temperatures are used to estimate reference evapotranspiration based on the formulation of Hargreaves. The calibration constant in the Hargreaves equation is recalibrated to the Penman-Monteith equation in a monthly and station-wise assessment. This ensures on one hand eliminated biases of the Hargreaves approach compared to the formulation of Penman-Monteith and on the other hand also reduced root mean square errors and relative errors on a daily time scale. The resulting new calibration parameters are interpolated over time to a daily temporal resolution for a standard year of 365 days. The overall novelty of the approach is the use of surface elevation as the only predictor to estimate the re-calibrated Hargreaves parameter in space. A third order polynomial is fitted to the re-calibrated parameters against elevation at every station which yields a statistical model for assessing these new parameters in space by using the underlying digital elevation model of the temperature fields. With these newly calibrated parameters for every day of year and every grid point, the Hargreaves method is applied to the temperature fields, yielding reference evapotranspiration for the entire grid and time period from 1961-2013. This approach is opening opportunities to create high resolution reference evapotranspiration fields based only temperature observations, but being closest as possible to the estimates of the Penman-Monteith approach.
1 Introduction

The water balance in its most general form is determined by fluxes of precipitation, change in storage and evapotranspiration (Shelton 2009). Particularly for evapotranspiration, measurement is rather costly, since it requires sophisticated techniques like eddy correlation methods or lysimeters. In hydrology as well as agricultural sciences the actual evapotranspiration as part of the water balance equation is mostly assessed from the potential evapotranspiration (PET). PET refers to the maximum moisture loss from the surface, determined by meteorological conditions and the surface type, assuming unlimited moisture supply (Lhomme 1997). Since surface conditions determine the amount of PET, the concept of reference evapotranspiration (ET0) was introduced (Doorenbos and Pruitt, 1977). ET0 refers to the evapotranspiration from a standardized vegetated surface (grass) under unrestricted water supply, making ET0 independent of soil properties. Numerous methods exist for estimating ET0; differences arise in the complexity and the amount of necessary input data for calculation.

A standard method, recommended by the Food and Agricultural Organisation (FAO; Allen et al. 1998), is the Penman-Monteith (PM) formulation of ET0. There are of course countless other methods as thoroughly described in McMahon et al. (2013), but the PM equation is considered the most reliable estimate and serves as a standard for comparisons with other methods (Allen et al. 1998). PM is fully physically based and requires four meteorological parameters (air temperature, wind speed, relative humidity and net radiation). It utilizes energy balance calculations at the surface to derive ET0 and is therefore considered a radiation based method (Xu and Singh 2000).

On the contrary, much simpler methods which use air temperature as a proxy for radiation (Xu and Singh 2001) are applied as alternatives for regions where the input data is not sufficient to use PM. One of these simpler methods; the method of Hargreaves (HM, Hargreaves et al. 1985), is used in this paper. It requires minimum and maximum air temperature and extra-terrestrial radiation, which can be derived from the geographical location and the day of year. Hence, HM is much broader applicable for many regions, because temperature observations are dense and easily accessible. Nevertheless, like most temperature based methods, HM has been developed for distinct studies and regions representing also distinct climate conditions (Xu and Singh, 2001). To avoid large errors, these temperature-based methods need to undergo a recalibration procedure to make them
applicable in different climatic regions than in those they were originally designed for (Chattopadhyay and Hulme 1997, Xu and Chen 2005).

In this paper, the method for constructing a dataset of ET0 is presented on a daily time resolution and a 1 km spatial resolution based on the method of Hargreaves. The HM is calibrated to the PM in a station-wise assessment. Many studies describe re-calibration procedures for ET0 estimations in general (Tegos et al., 2015; Oudin et al. 2005) and for the HM in particular (Pandey et al. 2014; Tabari and Talaee, 2011; Bautista et al., 2009; Gavilán et al. 2006) in order to achieve results comparable to PM. There are also some studies describing methods for creating interpolated ET0 estimates (e. g. Aguila and Polo, 2011; Todorovic et al, 2013). However, two main methodological frameworks emerged for the interpolation of ET0 (McVicar et al., 2007): (i) interpolation of the forcing data and then calculating ET0, or (ii) calculating ET0 at every weather station followed by an interpolation of ET0 onto the grid. Here we follow the first approach and combine it with methods proposed by Tegos et al. (2015) and Mancosu et al. (2014) which use spatially interpolated ET0 model parameters. Gridded data of minimum and maximum temperatures are used as forcing fields for the application of the Hargreaves formulation of ET0. The novelty of this study is the application of elevation as a predictor for the interpolation of the re-calibrated HM calibration parameter. Furthermore, these new calibration parameters are also variable in time, by changing day-by-day for all days of the year. This approach goes a step further than the method of Aguilar and Polo (2011) which derived one new calibration parameter for the dry and one for the wet season of the year. An evaluation of the final gridded product is carried out by assessing different error metrics at grid points next to weather stations where PM ET0 is available, and also by comparing the ET0 fields with those of the operational ET0 estimates based on INCA (Integrated Nowcasting through Comprehensive Analysis, Haiden et al. 2011), the nowcasting system of the Austrian weather service.

The presented dataset aims at using the best of two worlds by (i) using a method for estimating ET0 that is calibrated to the standard algorithm as defined by the FAO and (ii) being applicable to a comprehensive, long-term forcing dataset, on a high temporal and spatial resolution.
2 Forcing Data

The ET0 calculations are based on a high resolution gridded dataset of daily minimum and maximum temperatures calculated for the Austrian domain (SPARTACUS, see Hiebl and Frei 2015), whereas the actual data stretches beyond Austria to entirely cover catchments close to the border. SPARTACUS is an operationally, daily updated dataset starting in 1961. For the ET0 fields, the SPARTACUS temperature forcing is used for the period 1961-2013. The interpolation algorithm is tailored to complex, mountainous terrain with spatially complex temperature distributions. SPARTACUS also aims at ensuring temporal consistency through a fixed station network over the full time period, providing robust trend estimations in space. SPARTACUS uses the SRTM (Shuttle Radar Topography Mission, Farr and Kobrick 2000) version 2 Digital Elevation Model (DEM). The SRTM DEM is also applied in the present study.

SPARTACUS provides the input data for calculating ET0 following the Hargreaves method (HM, Hargreaves and Samani 1982, Hargreaves and Allen 2003). However, a recalibration of HM is necessary to avoid considerable estimation errors. This is carried out in a station wise assessment. Data of 42 meteorological stations (provided by the Austrian weather service ZAMG) are used to calibrate the HM to PM on a monthly basis. Figure 1 shows the location of these stations, which are spread homogeneously over Austria and cover rather different elevations and environmental settings (Table 1). Data of daily global radiation, wind speed, humidity, maximum and minimum temperatures for the period 2004-2013 are used to calculate ET0 simultaneously with HM and PM.

3 Methods

Numerous methods exist for the estimation of ET0, which is defined as the maximum moisture loss from a standardized, vegetated surface, determined by the meteorological forcing (Shelton, 2009). These methods can roughly be classified as temperature based and radiation based estimates (Xu and Singh, 2000, Xu and Singh, 2001, Bormann, 2011). Following the recommendations of the FAO (Allen et al. 1998) the radiation-based Penman-Monteith Method (PM) provides most realistic results and generally outperforms temperature based methods. The overall shortcoming of the PM is the data intense calculation algorithm which requires daily values of net radiation, wind speed, humidity, maximum and minimum
temperatures. Data coverage for these variables is usually rather sparse, particularly if gridded data is required. ET0 following the PM is calculated as displayed in Equation 1:

\[
ET0\_p = \frac{0.408\Delta(R_N - G) + \gamma \frac{900}{T + 273} u_2(e_s - e_a)}{\Delta + \gamma(1 + 0.34u_2)}
\]  

(1)

where \(E\) is the reference evapotranspiration \([\text{mm day}^{-1}]\), \(R_N\) is the net radiation at the crop surface \([\text{MJ m}^{-2} \text{day}^{-1}]\), \(G\) is the soil heat flux density \([\text{MJ m}^{-2} \text{day}^{-1}]\), \(T\) is the mean air temperature at 2 m height \([\text{°C}]\), \(u_2\) is the wind speed at 2 m height \([\text{m s}^{-1}]\), \(e_s\) is the saturation vapour pressure \([\text{kPa}]\), \(e_a\) is the actual vapour pressure \([\text{kPa}]\); giving the vapour pressure deficit by subtracting \(e_a\) from \(e_s\); \(\Delta\) is the slope of the vapour pressure curve \([\text{kPa °C}^{-1}]\) and \(\gamma\) is the psychrometric constant \([\text{kPa °C}^{-1}]\). Given the time resolution of one day the soil heat flux term is set to zero. The calculation of the other individual terms of Equation 1 is described in Allen et al. (1998). It should be mentioned, that the original Penman-Monteith equation contains a “surface resistance” term, expressing the response of different vegetation types, which is set constant for FAO PM, since it uses a standardized vegetated surface.

In contrast to the radiation based PM, the HM is based on daily minimum and maximum temperatures \((T_{\text{min}}, T_{\text{max}})\). Hargreaves (1975) stated from regression analysis between meteorological variables and measured ET0 that temperature multiplied by surface global radiation is able to explain 94 % of the variance of ET0 for a five day period (see Hargreaves and Allen 2003). Furthermore, wind and relative humidity explained only 10 and 9 % respectively. Additional investigations by Hargreaves led to an assessment of surface radiation which can be explained by extra-terrestrial radiation at the top of the atmosphere and the diurnal temperature range as an indicator for the percentage of possible sunshine hours. The final form of the Hargreaves equation is given by:

\[
ET0\_h = C(T_{\text{mean}} + 17.78)(T_{\text{max}} - T_{\text{min}})^{0.5} R_a
\]  

(2)

where \(ET0\_h\) is the reference evapotranspiration \([\text{mm day}^{-1}]\), \(T_{\text{mean}}, T_{\text{max}}\) and \(T_{\text{min}}\) are the daily mean, maximum and minimum air temperatures \([\text{°C}]\) respectively and \(R_a\) is the water equivalent of the extra-terrestrial radiation at the top of the atmosphere \([\text{mm day}^{-1}]\). \(C\) is the calibration parameter of the HM and was set to 0.0023 in the original publication of Hargreaves et al. (1985).

Following these formulations the ET0 for all stations is calculated for the period 2004-2013.
In order to achieve a meaningful representation of ET0 by HM, an adjustment of the calibration parameter \( C_{\text{adj}} \) of HM is necessary, with respect to ET0 derived from PM. This is carried out on an average monthly basis for every station by the following equation, as also proposed by Bautista et al. (2009):

\[
C_{\text{adj}} = 0.0023/(E \_H / E\_P)
\] (3)

where \( C_{\text{adj}} \) represents the new calibration parameter of the HM, \( E\_H \) is the original ET0\_h from HM, using a \( C \) of 0.0023 and \( E\_P \) is the ET0\_p from PM. As a result, a new set of \( C \) values for every month and every station is available. An analysis on the behaviour of \( C_{\text{adj}} \) in space revealed rather strong altitude dependence, particularly in the cold season. This feature enables to estimate \( C_{\text{adj}} \) in space for every grid point by using the underlying DEM of the temperature fields as a predictor.

As a first step, the monthly \( C_{\text{adj}} \) values at every station are linearly interpolated to daily values to avoid stepwise changes and therefore abrupt shifts of \( C_{\text{adj}} \) between months. This is carried out for a standard year with length of 365 days. The result is a time series of daily changing values of \( C_{\text{adj}} \) over the course of the year, available for every station, stretching over different altitudes and therefore yielding 42 different annual time series of \( C_{\text{adj}} \).

Subsequently the daily, station-wise values of \( C_{\text{adj}} \) are interpolated in space. The analysis of the \( C_{\text{adj}} \)-altitude relationship indicated non-linear characteristics, so a third order polynomial fit was chosen. Using the underlying DEM of the SPARTACUS dataset it is possible to determine adjusted calibration parameters for every grid point in space by this relationship. The polynomial fit is applied for every day of the daily interpolated station-wise \( C_{\text{adj}} \) values, since these are changing day by day as well. The result is a gridded dataset of \( C_{\text{adj}} \) for the SPARTACUS domain for 365 time steps from January 1\(^{st}\) to December 31\(^{st}\).

Having these gridded \( C_{\text{adj}} \) values the ET0\_h,c is calculated for every grid point and day since 1961 to 2013. In the case of leap years the \( C_{\text{adj}} \) grid of February 28\(^{th}\) is also used for February 29\(^{th}\). The final gridded product is termed ARET (Austrian Reference EvapoTranspiration dataset) throughout the rest of the paper.

The ARET fields are finally evaluated against station data and another ET0 product. Unfortunately there is no long-term gridded dataset of ET0 for the Austrian domain, so we used the ET0 of the nowcasting system INCA (Integrated Nowcasting through Comprehensive Analysis, Haiden et al., 2011) which yields daily fields of ET0 based on PM
on 1 km grid resolution. INCA uses weather stations, remote sensing data, rainfall radar data as well as DEM information to derive nowcasting fields of several meteorological variables. INCA is operational for several years, but due to constant changes in data input quality and other improvements we chose to use only the 5-year period from 2009-2013.

For the skill assessment of the ARET dataset we calculate mean monthly values of mean bias, Root Mean Squared Error (RMSE) and Relative Error (RE) of those grid points in ARET as well as INCA closest to a station with PM ET0.

4 Results

Figure 2a shows, as an example, the daily time series of ET0 as derived by PM (ET0_p) and HM (ET0_h) in the year 2004 at the station Grossenzersdorf. The differences between those two are obvious as ET0_p shows clearly higher variability, with ET0_h underestimating the upward peaks in the cold season and downward peaks in the warm season. This feature is more noticeable in Figure 2b, which shows the monthly averages over all stations, indicating the spread among all 42 stations. Here, an underestimation of the ET0_h compared to ET0_p from October to April is counteracted by an overestimation between May and September. On the other hand, ET0_p shows higher spread among stations compared to ET0_h except for November to January.

Figure 4 shows the adjusted C values for three exemplary stations. C_adj is generally higher in winter and autumn compared to the original value indicated by the dashed line at 0.0023. It is also obvious that at station Grossenzersdorf the original value is matching rather well to the C_adj from April to October, in the other months the adjusted values are clearly higher. On the contrary, at station Weissensee Gatschach C_adj is lower than 0.0023 except for the months from November to February. At station Rudolfshuette-Alpinzentrum the adjusted values are above the original ones all year round, reaching the highest values in wintertime of about 0.007. These results clearly underpin the necessity for a re-calibration of C in order to receive sound ET0 from temperature observations.

For simplicity for a first assessment the monthly values of C_adj were used for all days of the month, no temporal interpolation was conducted. As a result, the monthly mean bias is reduced to zero at every station. Furthermore, the RMSE has also slightly decreased by 0.1 to 0.2 mm day$^{-1}$, as can be seen in Figure 4a. The Relative Error (RE) has also decreased, from
around 45% to fewer than 35% in January for example (cf. Figure 4b). The improvements regarding RE in summer are lower due to the higher absolute values of ET0 in the warm season.

The complete monthly mean time series from 2004 to 2013 of ET0_p, ET0_h and ET0_h.c for three stations are shown in Figure 5. At station Grossenzersdorf the underestimation of ET0_h in winter is reduced as well as the overall underestimation at station Rudolfshuette-Alpinzentrum. On the other hand, the overestimation in summer at station Weissensee-Gatschach is considerably reduced with ET0_h.c. These features in combination with the information on the altitude of the given stations provide some information on more general characteristics of $C_{adj}$ and the effects of the calibration, which underpins an altitude-dependence of $C_{adj}$, which is displayed in more detail in Figure 6. It shows the monthly average $C_{adj}$ for stations which were binned to distinct classes of altitude ranging from 100 to 2300 m in steps of 100 m. As already seen in Figure 3 as an example for three stations, $C_{adj}$ is clearly higher in winter than the unadjusted value. From April to September $C_{adj}$ is lower than 0.0023 up to altitudes of 1500 m.a.s.l., lowest values are visible in May to August between altitudes of 400 to 1000 m.a.s.l. Figure 7 displays the adjusted calibration parameters plotted against altitude for the monthly means of $C_{adj}$. From this Figure it comes clear that this relationship is not linear. $C_{adj}$ is decreasing from the very low situated stations until altitudes between 500 and 1000 m.a.s.l. Going further up $C_{adj}$ increases and one could say it might be a linear increase, particularly in winter. On the other hand, looking at the summer months the station with the highest elevation (Sonnblick, 3106 m.a.s.l.) shows somewhat lower or at least equal values of $C_{adj}$ compared to the cluster of stations between 2000 and 2400 m.a.s.l. This feature indicates that the relationship above 1000 m.a.s.l. might not be linear. Taking all this characteristics into account, a higher order polynomial fit was chosen to describe the $C_{adj}$-altitude relation.

The results of the spatial interpolation of $C_{adj}$ are displayed in Figure 8, where two examples of $C_{adj}$ distribution in space are displayed; on January 1st (a) and July 1st (b). Particularly in January the altitude dependence of the calibration parameter is clearly standing out, showing rather high values of $C_{adj}$ in the mountainous areas. In contrast to winter the spatial variations in summer are smaller, only some central Alpine areas between 1000 and 3000 m.a.s.l. are appearing in somewhat different shading than the surrounding low lands.
The climatological mean (1961-2013) of the final ARET fields is displayed in Figure 9a. Lowest daily mean values of below 1.5 mm day\(^{-1}\) are apparent on the highest mountain ridges of the main Alpine crest. Highest values of 2.4 mm day\(^{-1}\) and above are found in the eastern and southern low lands. Other spatial features are visible as well, for example higher ET0 in the valleys in the far western part of Austria. This higher ET0 is driven by the longer sunshine hours in these areas, which are also known as “inner alpine dry valleys”, because rainfall approaching from the west is often screened by the mountain chains in the northwest. In the ET0 estimate this feature of less cloud cover and therefore longer sunshine durations is reflected in the higher Diurnal Temperature Range (DTR), yielding larger values in that particular area. A similar characteristic is apparent in the very south of Austria. Here ET0 is higher as well, compared to topographically similar regions on the northern rim of the Alps. This is also connected to the longer sunshine hours which enhance indirectly ET0 through higher DTR values.

Figure 9b shows the ET0 field of August 8\(^{th}\) 2013. For the first time on that particular day, temperatures reached above 40 °C in Austria at some stations in the east and south. Values of ET0 are particularly high, reaching up to 7 mm day\(^{-1}\) in some areas in the southeast. That day was also characterized by an approaching cold front, which brought rain, dropping temperatures and overcast conditions from the west. These conditions were featured as well in the ET0 field, showing a considerable gradient from west to east, with almost zero ET0 at the headwaters of the Inn River in the far southwest of the domain. Furthermore, the implications of overcast conditions in the west with lower altitudinal gradients of ET0 compared to the east with sunny conditions and distinct gradients along elevation are visible.

July, the month with the highest absolute values of ET0 shows considerable variations in the last 53 years. As an example, the mean anomaly of ET0 in July of 1983 with respect to the July mean of 1961-2013 is displayed in Figure 10a. This month was characterized by a considerable heat wave and mean temperature anomalies of +3.5 °C which also affected ET0. The absolute anomaly of ET0 reaches above 1 mm day\(^{-1}\) with respect to the climatological mean in some areas. The relative anomaly is in a range between 10 to 30 % (Figure 10c). July of 1979 was rather cool instead with temperatures 1.5 °C below the climatological mean and accompanied by a strong negative anomaly in sunshine duration, particularly in the areas north of the main Alpine crest. These characteristics implicated a distinctly negative anomaly of ET0 in this particular month (Figure 10b). The absolute anomaly stretches between 0 and
more than -1 mm day\(^{-1}\), which is equivalent to a relative anomaly of 0 to -30 % (Figure 10d). The negative signal is stronger in the areas north of the Alpine crest, zero anomalies are found in some areas in the south.

In Figure 11 the overall benefits of the re-calibration of the HM are revealed. It shows the mean ET0 in July 2012, a month accompanied by a considerable heat wave at the beginning and an overall temperature anomaly of around +2 °C. In Figure 11b the ET0 field of the original HM formulation without calibration is shown, and Figure 11a displays the results with re-calibration as described in this study. Overall, the gradient along elevation of ET0 is larger in the non-calibrated field. Particularly in this time of the year with large absolute values, the re-calibration has a considerable impact, although \(C_{adj}\) in July is relatively small compared to winter. As shown before (cf. Figure 3), the ET0 estimation using the original \(C\) is good for July in the very lowlands, since biases tend to be rather small. However, going to higher elevations, the overestimation of the original HM is rather pronounced. Mean biases reach +1 mm day\(^{-1}\) or +30 % over large parts of the domain. This signal switches to negative biases of -0.5 mm day\(^{-1}\) (-25 %) above 1500 m.a.s.l.

The overall performance of ARET compared to the station wise PM estimates is displayed in Figure 12. 12a shows the monthly bias of the original HM ET0 and the calibrated ET0 of the nearest grid point. The bias is clearly reduced in nearly all months. However, in April, as the only exception, the bias of the calibrated grid point values is larger than the bias of the original estimation. The biases concerning different levels of altitude are reduced as well, as can be seen in Figure 12b which shows the biases in July and Figure 12c displaying the biases in January.

A comparison between ARET and INCA ET0 and station based PM ET0 is given in Figure 13, showing ET0 on two different days in summer 2013. The first example (Figures 13a and 13b) is June the 4\(^{th}\) 2013, a day with mostly overcast conditions, lower than average temperatures of between 7 to 12 °C and high relative humidity, it was the time after a big flood event in northern Austria. ARET is clearly overestimating ET0 by a median difference of +1 mm day\(^{-1}\) across all stations as shown by the boxplot in Figure 13c. INCA has a median difference of nearly zero, although the spread is larger than in ARET. Another example is July 23\(^{rd}\) 2013 (Figure 13d and 13e) which characterized by temperatures ranging between 20 °C in the West and 29 °C in the east, accompanied by some rainfall in the West and South. ET0 in both ARET and INCA range between 3 and 6 mm day\(^{-1}\), although INCA shows a
general overestimation with a median difference around +0.5 mm day\(^{-1}\) (Figure 13f). On the other hand median differences of ARET compared to stations are around zero.

However, comparing error characteristics in ARET and INCA against station data (Table 2) for the period 2009-2013 reveals only minor differences. The mean bias all year round is lower in INCA (0.03 mm day\(^{-1}\)) compared to ARET (0.12 mm day\(^{-1}\)). Considering monthly mean values the spread is rather similar spanning -0.30 to 0.66 mm day\(^{-1}\) in INCA and -0.17 to 0.80 mm day\(^{-1}\) in ARET. The highest monthly mean values are in both dataset found in April (ARET: 0.80 mm day\(^{-1}\), INCA: 0.66 mm day\(^{-1}\)) and May (ARET: 0.79 mm day\(^{-1}\), INCA: 0.51 mm day\(^{-1}\)). The RMSE is slightly lower in ARET reaching maximum values in June of 1.42 mm day\(^{-1}\) compared to INCA with 1.80 mm day\(^{-1}\). The overall mean RMSE is 0.89 mm day\(^{-1}\) in ARET and 1.05 mm day\(^{-1}\) in INCA. Concerning the RE the characteristics are similar to the bias and the RMSE, with only minor differences between ARET and INCA. The RE in ARET ranges between +35 % (April) and -15 % (November) and in INCA these are rather similar spanning +25 % (February) and -18 % (November).

5 Discussion

By comparing the characteristics of ET0 based on HM and PM on a daily time step it came clear that a re-calibration of C within the formulation of Hargreaves follows distinct patterns. The values of C\(_{adj}\) show markedly variations in space and time (over the course of the year). It turned out, that a monthly re-calibration of C reveals an annual cycle of C\(_{adj}\), with C\(_{adj}\) being close to the original value of 0.0023 in the warm season (April-October) and low elevations. Going to higher elevations, C\(_{adj}\) decreases until roughly 1000 m.a.s.l. Reaching altitudes above 1700 m.a.s.l., C\(_{adj}\) has generally a higher value than Hargreaves’ original value, particularly during the cold season (November-March). This altitude dependency of the calibration parameter in HM is mentioned in Samani (2000), but the authors also claimed that this relationship may be affected by different latitudes. Aguila and Polo (2011) also found that the original HM using a C of 0.0023 underestimates ET0 at higher elevations and defined a value of 0.0038 at an elevation of 2500 m.a.s.l. However, this altitude dependency of C turned out to be more complex, as we are able to display, showing a distinct variation throughout the year along with elevation.

To reveal the sources of this altitude dependence of C some additional analysis was done. In general, the HM utilizes the Diurnal Temperature Range (DTR, T\(_{max}\) minus T\(_{min}\)) to mimic the
amount of global radiation at the land surface. Clear sky conditions are usually associated
with higher DTR. There is more heating during daytime due to large proportions of direct
solar radiation, whereas at night time temperatures drop further down since the outgoing long-
wave radiation is not reflected by clouds. Numerous studies investigating the relationship
between DTR and radiation (Pan et al., 2013; Makowski et al., 2009; Bindi and Miglietta,
1991; Bristow and Campbell, 1984) , which show considerable correlations. For example
Makowski et al. 2009 reported a correlation coefficient of 0.87 of the annual means of DTR
and solar radiation averaged over 31 stations across Europe.

Figure 14 shows the linear regression coefficients of the square root of DTR and Global Top-
Of-Atmosphere (TOA) radiation ratio on a daily time scale at the 42 stations used in this
study. The idea is to get a better understanding of the parameterization embedded in HM,
which tries to assess the amount of global radiation via the DTR and the TOA radiation. The
coefficients show a distinct altitudinal dependency, particularly in winter. In January the
coefficients are generally high at altitudes between 300 and 1100 m.a.s.l. At higher elevations
they are dropping considerably, getting slightly negative above 3000 m.a.s.l. at station
Sonnblick. This altitude dependency is also apparent in the transitional season (c.f. Figure 14;
April and October) although not as pronounced as in winter. In July the coefficients are
generally higher, roughly ranging between 0.15 and 0.30, with no change along altitude.

The reasons for the patterns in Figure 14 seem to be rooted in the lower atmospheric mixing
ratios at the lowest stations, some of them located in, or nearby cities, which might dampen
the DTR, although clear sky conditions are apparent. At moderate altitudes between 400 and
1500 m.a.s.l. the daily temperature amplitude is more dominantly driven by surface energy
balance processes which reflects higher regression coefficients. Going further up, the
proportion of the DTR which is determined by large scale air mass changes rises, as the
station locations reach up above the planetary boundary layer into the free atmosphere. So for
any given value of cloudiness, DTR is much smaller in winter and high elevations than in low
elevation environments where boundary layer processes are dominant. This means for
yielding realistic values of global radiation relative to TOA radiation, a much higher \( C_{adj} \)
value is needed to compensate for this.

Although these circumstances seem to be a drawback of the methodology, the overall effect is
only minor. Figure 15 shows the HM ET0 in dependence of the DTR and the daily mean
temperature. At low daily mean temperatures, between -10 and +10 °C, the contour lines
determining the value of ET0 are rather steep. This implies that a change in DTR has only
minor effects on the ET0 outcome, whereas a change in daily mean temperature is more
important.

However, the procedure of altering the coefficient C has also implications on the variability of
ET0 on a daily time scale. As was visible in Figure 2a the variability of ET0 based on HM is
lower than using PM. The presented re-calibration has only little effect on the enhancement of
variability. By scaling C, variability is slightly enhanced in those areas and time of the year
where \( C_{adj} \) is higher than 0.0023. This is the case for most of the time and widespread areas,
but there are regions or altitudinal levels where the opposite is taking place. As is visible in
Figure 6 areas up to 1500 m.a.s.l. show lower than original values of \( C_{adj} \) in the summer
months. There are particular areas in June between altitudes of 500 to 1000 m.a.s.l. that show
the largest deviation from the original value. In these areas variability is lower in the re-
calibrated version. On the other hand the benefit of an ET0 formulation being unbiased
compared to the reference of PM may overcome these shortcomings.

Evaluating both the ARET and INCA gridded ET0 estimates against station based ET0
revealed only minor differences in Bias, RMSE and RE, which underpins the strength of the
proposed calibration method. However, there are situations where the deviations compared to
station based ET0 are particularly large in both the ARET and the INCA dataset. As an
example for overcast conditions after a considerable amount of rainfall for a couple of days
we compared ARET to INCA ET0 (cf. Figure 13) and found that ARET clearly overestimates
ET0. Under the given circumstances ARET cannot compete with INCA, which considers,
through using PM, information on relative humidity, which might has a strong forcing on ET0
on that particular day, information that is not available in the ARET estimate. On the other
hand on a typical sunny summer day INCA overestimates ET0, where ARET is rather close to
the station estimates. There might be some biases in the radiation analysis in INCA causing
this deviation from the station data. Global Radiation is calculated based on sunshine duration
estimates (blended remote sensing and station data) driving a simple radiation model (Haiden
et al. 2011).

As shown in the evaluation of the ARET fields against INCA the error characteristics are
rather similar, although in INCA ET0 is calculated using PM. The calibration of HM, though
very simple, yields very satisfying results of the final product. Particularly when considering
Austrian topography it comes clear that using a method like HM without calibration has major
impacts on the result. Using non-calibrated HM ET0 data for rainfall-runoff modelling for example would introduce large errors and uncertainties. Given the fact that gridded data of ET0 based on PM are only available for a rather short time period from the INCA system, the ARET dataset provides a sound alternative for ET0 estimates on a high spatial resolution covering the last 53 years.

6 Conclusion

In this paper a gridded dataset of ET0 for the Austrian domain from 1961-2013 on daily time step is presented. The forcing fields for estimating ET0 are daily minimum and maximum temperatures from the SPARTACUS dataset (Hiebl and Frei 2015). These fields are used to calculate ET0 by the formulation of Hargreaves et al. (1985). The HM is calibrated to the Penman-Monteith equation, which is the recommended method by the FAO (Allen et al. 1998). This is done using a set of 42 meteorological stations from 2004-2013, which have full data availability for calculating ET0 by PM. The adjusted monthly calibration parameters $C_{adj}$ are interpolated in time (resulting in daily $C_{adj}$ for a standard year) and space (resulting in $C_{adj}$ for every grid point of SPARTACUS and day of year). With these gridded $C_{adj}$ the daily fields of reference evapotranspiration are calculated for the time period from 1961-2013. This dataset is highly valuable for users in the field of hydrology, agriculture, ecology etc. as it provides ET0 in a high spatial resolution and a long time period. Data for calculating ET0 by recommended PM is usually not available for such long time spans and/or with this spatial and temporal resolution. However, the method presented in this study combined both strengths of long time series, high spatial and temporal resolution provided by the temperature based HM and the physical more realistic radiation based PM by adjusting HM.

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would also like to thank two anonymous reviewers for the valuable comments which improved the manuscript substantially.
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Table 1. Location, altitude and setting of the 42 meteorological stations used for calibration.

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Table 2. Error Characteristics of ARET and INCA against station data

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Figure 1. Location of the meteorological stations used for calibration; coloured circles around points indicate stations that are exemplary displayed in other plots: Grossenzersdorf (blue), Weissensee Gatschach (green) and Rudolfshuette-Alpinzentrum (red).
Figure 2. Daily time series of ET0 in 2004 for ET0 based on PM (ET0_p) and HM (ET0_h) at the station Grossenzersdorf (a); Monthly mean ET0 from 2004 to 2013 averaged over all stations, error bars denote the spread among all stations (b).
Figure 3. Monthly values of $C_{adj}$ at three different stations, the dashed black lines indicates the original C value of 0.0023 from Hargreaves et al. (1985).
Figure 4. Monthly Root Mean Square Error (a) and monthly Relative Error (b) between daily ET0_p and ET0_h (black) and ET0_p and ET0_h.c (red).
Figure 5. Monthly ET0 sums derived from ET0_p, ET0_h and ET0_h.c for three stations located at different altitudes.
Figure 6. Monthly variations of $C_{adj}$ with respect to altitude; the black contour line defines the original Hargreaves Calibration Parameter C value of 0.0023; stations are binned to classes of altitude from 100 to 2300 m every 100 m; white areas denote classes of altitude with no station available.
Figure 7. Station-wise monthly third-order polynomial fit of the Hargreaves Calibration Parameter $C_{adj}$ against altitude; the blue dotted line indicates the original C value of 0.0023.
Figure 8. Spatially interpolated $C_{adj}$ values for January 1$^{st}$ (a) and July 1$^{st}$ (b).
Figure 9. Climatological daily mean ET0 from 1961-2013 (a); example of a daily field of ET0 on August 8th 2013 (b).
Figure 10. Upper panel: absolute anomalies of ET0 sum in July 1983 (a) and July 1979 (b) with respect to the climatological mean in July from 1961-2013; lower panel: corresponding relative anomaly (c, d).
Figure 11. July 2012 monthly mean ET0 based on $C_{adj}$ values – ET0_h.c (a), using the original C of 0.0023 for the whole grid ET0_h (b) and the corresponding absolute (c) and relative bias (d); the dots in (a) and (b) denote for the PM ET0 at the stations.
Figure 12. Boxplots of monthly mean bias of the station-wise original Hargreaves ET0 (grey) and the ARET, re-calibrated ET0 (red) against Penman-Monteith ET0 (a); stratified by different classes of altitude in July (b) and January (c).
Figure 13. ET0 fields of ARET (a, d) and INCA (b, e) and station wise PM ET0 on June 4th 2013 (cool and overcast conditions) and July 23rd 2013 (warm and mostly sunny conditions) and corresponding differences at grid points closest to a station with PM ET0 of both datasets displayed as boxplots (c, f).
Figure 14. Station-wise linear regression coefficient of the TOA radiation - Global Radiation ratio against the square root of the Diurnal Temperature Range ($T_{\text{max}} - T_{\text{min}}$) against altitude represented by black dots in January, April, July and October.
Figure 15. ET0 response to varying Daily Mean Temperature and Diurnal Temperature Range; ET0 values are calculated with 1st of April Top of the Atmosphere Radiation and the original C value of 0.0023.