

Interactive comment on “Improving hydrological projection performance under contrasting climatic conditions using spatial coherence through a hierarchical Bayesian regression framework” by Zhengke Pan et al.

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This paper analyzes the prediction performance of a lumped hydrological model using different time and spatial dependent parametrizations of one of its parameters. There are several errors in the paper and points that should be explained better and I have a major concern regarding the results. Comment on the results: A1: The value of omega looks strange to me. Assuming that the equation 1 you wrote is correct (and therefore it is a frequency and not a phase) and that the order of magnitude of omega is of hundreds (like shown in figures 8 and 9), this mean that your parameter theta1 oscil-

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lates hundreds of times per time step. This looks unreal to me since the goal of having time-variant parameters is to represent long term (seasonal) oscillations. Therefore, either there is a problem with the unit of omega or your model is not doing what it was meant for. If omega is a phase (meaning $\theta_1 = \alpha + \beta \sin(t + \omega)$) the value of omega makes more sense but θ_1 would still complete an oscillations every 6.28 time steps (the time step is days, right?). Don't you also have a frequency that multiplies "t" and have a small value? Reply: We apologize for our mistakes. Omega represents frequency rather than phase. It will be revised accordingly in the revised manuscript. We have carefully checked the results of regression parameter Omega and found that the Figures 8 and 9 in the manuscript of Omega should be modified as the attachments: See the attachment Figure 8. Posterior distributions of the regression parameters (β and ω) for the production storage capacity (θ_1) for the four modeling scenarios in all the 3 studied catchments. In this figure, parameters were calibrated in the non-dry period while verified in the dry period. The solid horizontal lines within the violin plots denote the 25th and 75th percentiles of the posterior distribution, while the dash line denotes median estimates. See the attachment Figure 9. Posterior distributions of the regression parameters (β and ω) for the production storage capacity (θ_1) for the four model scenarios in all 3 studied catchments. In this figure, parameters were calibrated in the dry period while verified in the non-dry period. The solid horizontal lines within the violin plots denote the 25th and 75th percentiles of the posterior distribution, while the dash line denotes median estimates. For the first four scenarios as shown in Figure 8, the average median estimates of regression parameter ω of the 3 catchments are 0.24, 0.14, 0.15, and 0.18, respectively., and that in Figure 9 are 0.15, 0.26, 0.23, and 0.17 respectively in Figure 9. Thus, the phase of the sine term could be derived based on the regression parameter ω . The mean phase of model parameter Seta1 for each scenario is 26.2, 46.3, 41.9 and 35.2 in Figure 8, respectively. It is 42.9, 24.1, 27.4 and 38.0 in Figure 9, respectively.

Detailed comments: A2: line 102-103: There is not a clear definition of pooling, complete pooling and hierarchical Bayesian. I would explain shortly what do they mean and

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which are the differences since then the paper only writes about hierarchical Bayesian. Reply: Thank you for your comments. The following explanations (in blue) about the pooling, complete pooling and hierarchical Bayesian will be added in the revised manuscript. In general, there are three methods to consider the spatial coherence between different catchments in parameter estimation. The first one is no pooling, which means every catchment is modeled independently, and all parameters are catchment-specific. The second one is complete pooling, which means parameters are considered to be common across all catchments. The third/last one is hierarchical Bayesian (HB) framework, also known as partial pooling, which means some parameters are allowed to vary by catchments and some parameters are assumed to be drawn from a common hyper-distribution across the region that consists of different catchments.

A3: line 152-153: It would be beneficial to explain shortly how the method works even if it was already used in other studies. Reply: Thank you for your comment. Definition of dry period is explained in the following paragraph and will be added in the revised manuscript: Saft et al. (2015) tested several algorithms for dry period delineation, which considered different combinations of dry run length, dry run anomaly and various boundary criteria, and found that the identification results of dry period by one of the algorithms showed marginal dependence on the algorithm and the main results were robust to different algorithms. The detailed processes could be found on Saft et al. (2015) and also are as follows. Firstly, the annual rainfall data were calculated relative to the annual mean, and the anomaly series was divided by the mean annual rainfall and smoothed with a 3 year moving window. Secondly, the first year of the drought remained the start of the first 3 year negative anomaly period. Thirdly, the exact end date of the dry period was determined through analysis of the unsmoothed anomaly data from the last negative 3 year anomaly. The end year was identified as the last year of this 3 year period unless: (i) there was a year with a positive anomaly >15

A4: line 159: Maybe it is more appropriate to use “cross validation” instead. I suggest to avoid making a paragraph with just one sentence and remove paragraphs 2.1.1 and

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2.1.2 putting all together in section 2.1. Reply: Thanks. (1) Follow the Referee’s comment, the phrase “Verification method will be modified as “Cross validation”. (2) Follow the Referee’s suggestion, paragraph 2.1.1 and 2.1.2 will be put together in section 2.1, and the sub-titles of section 2.1.1 and 2.1.2 will be deleted in the revised manuscript.

A5: chapter 2.3: It is not clear to me what do you do with the other parameters of the GR4J model ($\theta_2, \theta_3, \theta_4$). Do you keep them fixed or do you sample them? What is their effect on the final result? Reply: Thank you for your comment. (1) All other model parameters (θ_2, θ_3 and θ_4 , except θ_1) are not fixed, but sampled simultaneously with regression parameters μ_2, σ_2, μ_3 and σ_3 in the SCEM-U algorithm. In actual calculation, the Rubinstein convergence value of 1.2 (Gelman et al., 2013) would be selected as the posterior probability, varying while other model parameters are temporal invariant.

A6: line 199: The equation is different from the ones reported in Table 1. Reply: We apologize for our mistakes. The fault equations in Table 1 have been revised as equation 1 in the revised manuscript.

A7: line 201: You write that ω is the phase while in the equation 1 it is a frequency. Reply: Thank you for pointing out this mistake. The ω represents the frequency rather than the phase (see response to comment A1). The statement in line 201 is wrong and will be modified in the revised manuscript.

A8: line 202: The combination $\alpha = \beta = \omega = 0$ makes θ_1 to be equal to 0, that indeed it is a constant value but probably it is not what you want. Reply: Thanks. According to the definition of the GR4J model (Perrin et al., 2003), θ_1 represents the primary storage of water in the catchment and must be a positive value. Thus 0, the combination of $\alpha = \beta = \omega = 0$ would be excluded first, and other combination that made θ_1 equal to zero would be excluded too.

A9: chapter 2.3.2: What happens to α ? You don’t write about it anymore in the rest of the paper. Do you keep it fixed or do you sample also it? What

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is its effect on the final result? Reply: Thanks. (1) The alpha represents the constant term in equation 1. Changes in alpha lead to consistent changes in θ_1 across the whole time series, which does not result in temporal variations of model parameters μ_2, σ_2, μ_3 and σ_3 , other regression parameters β and ω (if present) in the UA algorithm.

A10: chapter 2.3.2: It is not clear to me if linking the parameters between catchments means sampling them from the same Gaussian distribution or there is another form of linking. Reply: We apologize for the misunderstanding. The link is that regression parameter β (ω) of different catchments is assumed to sample their values in the same Gaussian distribution. This kind of links have been widely used in the field of extreme event analysis, such as Sun et al (2015, 2016), Lima et al (2009) and Bracken et al (2018).

A11: chapter 2.3.2: How do you sample ω and β when they are not linked? Reply: Thanks. The ω is not linked in scenario 1, while β is not linked in scenario 2. In scenario 4, both ω and β are not linked. Spatially irrelevant parameters would be sampled and derived as independent variables. For example, in scenario 4, the ω and β of different catchments are not linked, thus values of ω and β of each catchment are calibrated from corresponding catchment inputs. In scenario 1, regression parameter $\beta(c) = N(\mu_3, \sigma^2)$, which means that β is shared with linked catchments, while independent regression parameters ω_1-2 , and ω_1-3 are used to represent the frequency of model parameter θ_1 in different catchments. The name of all unknown quantities in different scenarios could

A12: line 218: How do you choose the values of μ and σ , the hyper-parameters of your model? Reply: Thanks. The posterior distributions of all unknown quantities, including model parameters θ_2, θ_3 and θ_4 , and regression parameters α, β and γ , and hyper-parameters μ_2, σ_2, μ_3 and σ_3 are derived simultaneously through the SCEM-UA algorithm. In actual calculation process, we would set a large variation interval for each unknown

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Rubin convergence value of 1.2 (Gelman et al., 2013) would be selected as the posterior probability.

A13: chapter 2.4.1: I wouldn't call "likelihood function" what actually is an objective function. Reply: Thanks. As suggested, the "likelihood function" will be modified as "objective function" in the revised manuscript.

A14: line 250: You are mixing an objective function with a prior distribution of the parameters. How do you account for the prior distribution of the parameters when they are not linked? Reply: Thanks. The objective function of Eq.1 will be modified as follows: Please see the supplementary material (Line 31). where $\theta_1, \theta_2, \theta_3$ and θ_4 refer to four model parameters. The objective function of Eq.5 will be modified as follows: Please see the supplementary material (Line 32). where the number of catchments in the region is

A15: chapter 2.4.2: You don't say which settings of the sampling method you use (e.g. how many parameters you sample. . .) Reply: Thanks. The sampling method used in this paper is the SCEM-UA algorithm. The detailed description of the settings of SCEM-UA algorithm will be added in the revised manuscript: Convergence is assessed by evolving three parallel chains with 30000 random samples, while verifying that the posterior distribution of parameters results in a value smaller than a Gelman-Rubin convergence value of 1.2 (Gelman et al., 2013). The number of unknown quantities in different scenarios are as follows: 15 in scenario 1 and scenario 2, 13 in scenario 3 and 18 in scenario 4.

A16: chapter 3.2.1: The dataset that you get is unbalanced, since there are more wet years. Is it taken into account? Does it have an effect on the calibration? Reply: Thank you for pointing out this situation. (1) Generally, calibration data should be longer than 3-6 years for daily hydrological modeling in order to get robust results (Perrin et al., 2003, Coron et al., 2012). Thus, data from both dry period (15 years) and wet period (21 years) were used for model calibration to meet this requirement. (2) Generally, a longer time series may improve the robustness of hydrological predictions. However, we tested the calibration performance with different lengths of records (> 10 years) in

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dry and non-dry periods and found that their results are almost the same. Therefore, we used both the length of 15 years of dry and 10 years non-dry periods into calibration in order to utilize all available data.

A17: chapter 3.2.3: Figures 7 and 8 are actually 8 and 9. Reply: Thanks. Changes will be made as suggested.

A18: Figures 5, 6, 8, 9: Since you want to show a probability distribution I wouldn't use a boxplot but, instead, I suggest to use a violin plot (e.g. https://seaborn.pydata.org/examples/grouped_violinplots.html) Reply : Thankyouforyoursuggestions.Figures8and9willbemodifiedasviolinplotintherevisedmanus PleaseeetheattachmentFigure5(a)PleaseeetheattachmentFigure5(b)Figure5.NSEsqrtf(dryperiod)and(b)theverificationperiod(dryperiod).PleaseeetheattachmentFigure6(a)Plea dryperiod).

A19: Figures 8, 9: Why do you change the colors between beta and omega? This makes the plot more difficult to read. Reply: Thanks. The same color will be used to the same parameter consistently in all figures. Changes will be made as suggested in the revised figures. Please refer to response to comment A1 by Referee 1.

Please also note the supplement to this comment:

<https://www.hydrol-earth-syst-sci-discuss.net/hess-2019-6/hess-2019-6-AC1-supplement.pdf>

Interactive comment on Hydrol. Earth Syst. Sci. Discuss., <https://doi.org/10.5194/hess-2019-6>, 2019.

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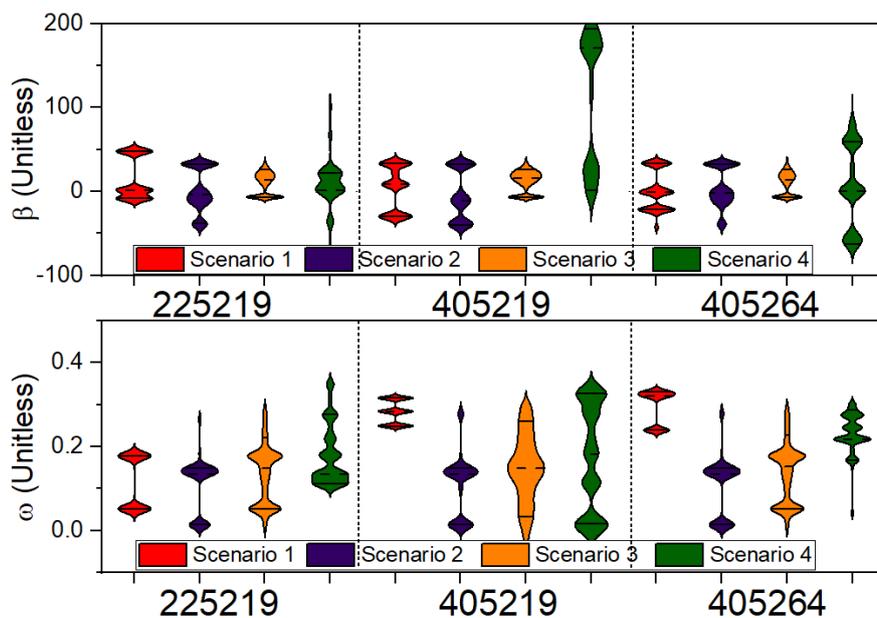


Fig. 1. Figure 8 Posterior distributions of the regression parameters (β and ω) for the production storage capacity (θ_1) for the four modeling scenarios in all the 3 studied catchments. In this figure, param

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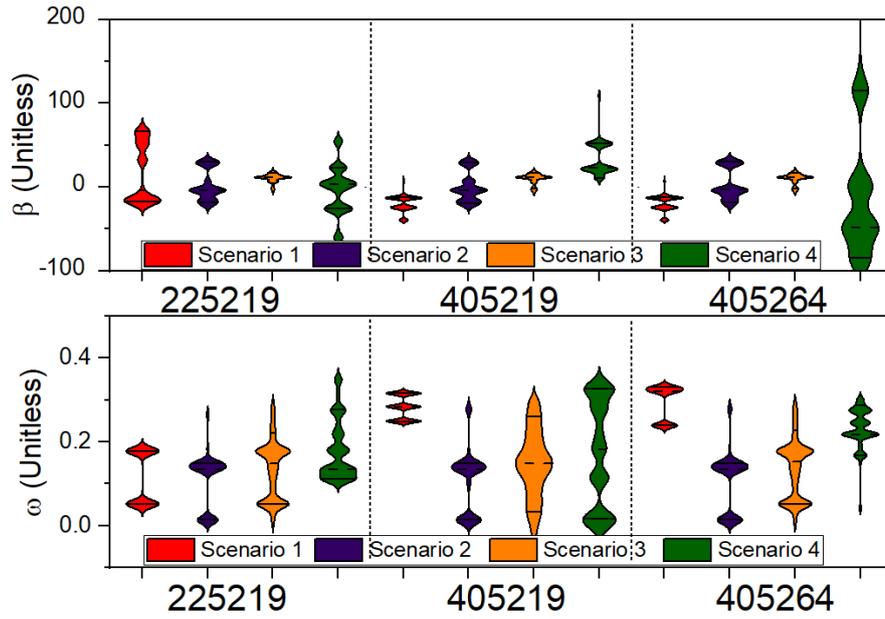


Fig. 2. Figure 9 Posterior distributions of the regression parameters (β and ω) for the production storage capacity (θ_1) for the four model scenarios in all 3 studied catchments. In this figure, parameters we

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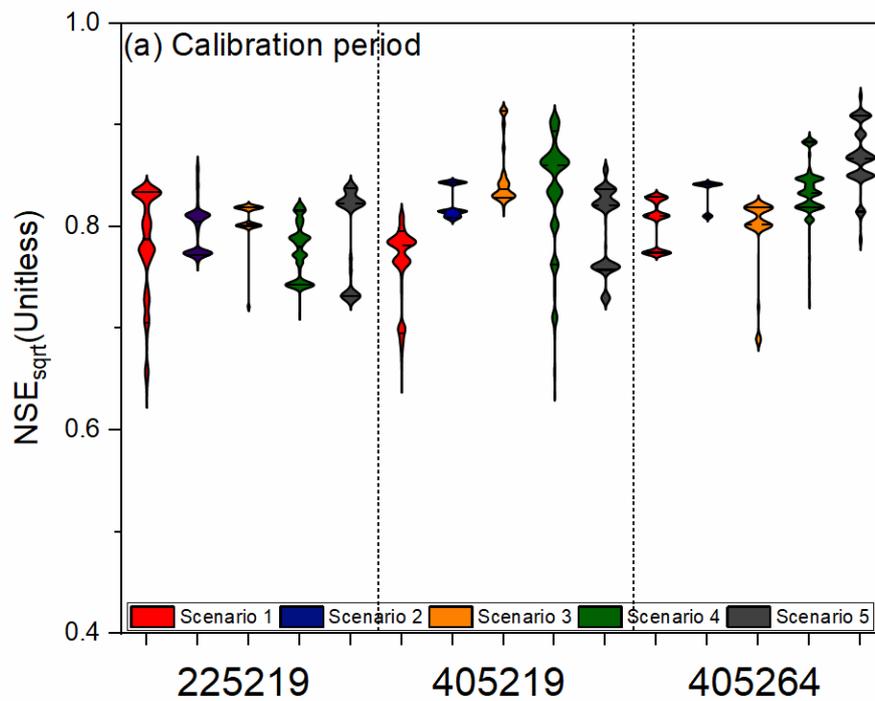


Fig. 3. Figure 5(a) NSE_{sqrt} for each of the five scenarios for each catchment during (a) the calibration period (non-dry period) and (b) the verification period (dry period).

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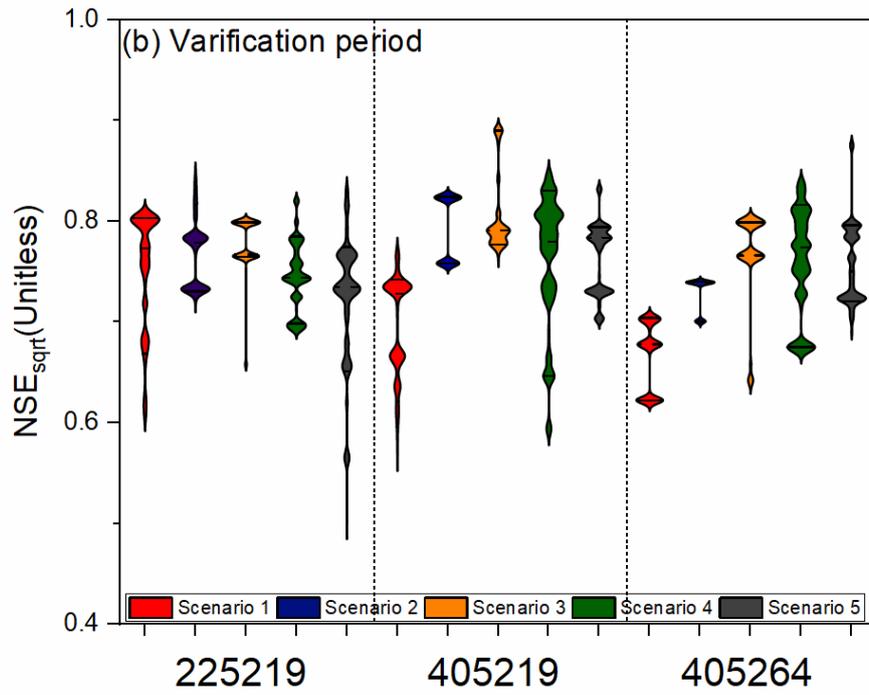


Fig. 4. Figure 5(b) NSEsqrt for each of the five scenarios for each catchment during (a) the calibration period (non-dry period) and (b) the verification period (dry period).

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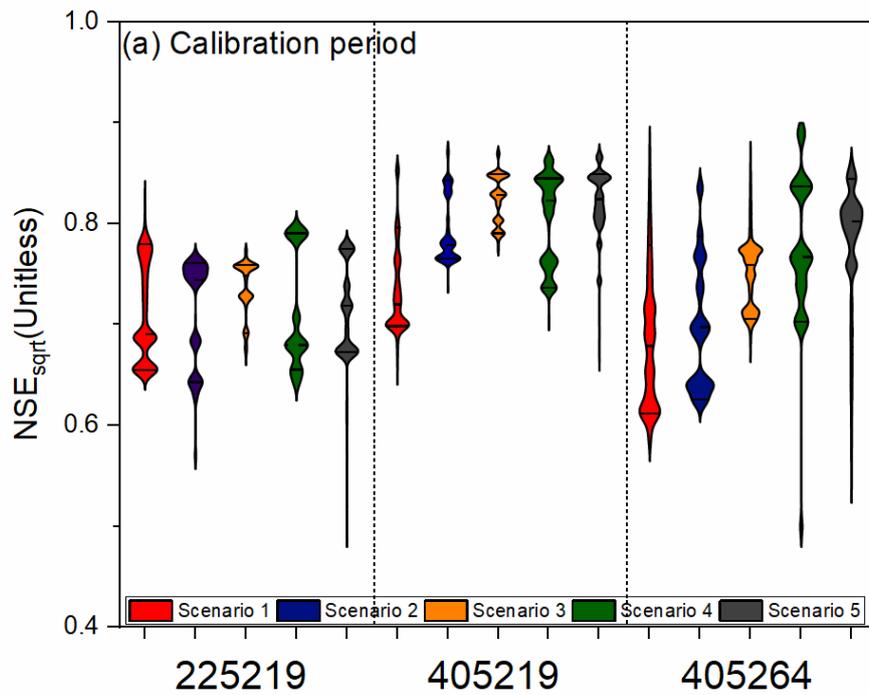


Fig. 5. Figure 6(a) NSEsqrt for each of the five scenarios for each catchment during (a) the calibration period (dry period) and (b) the verification period (non-dry period).

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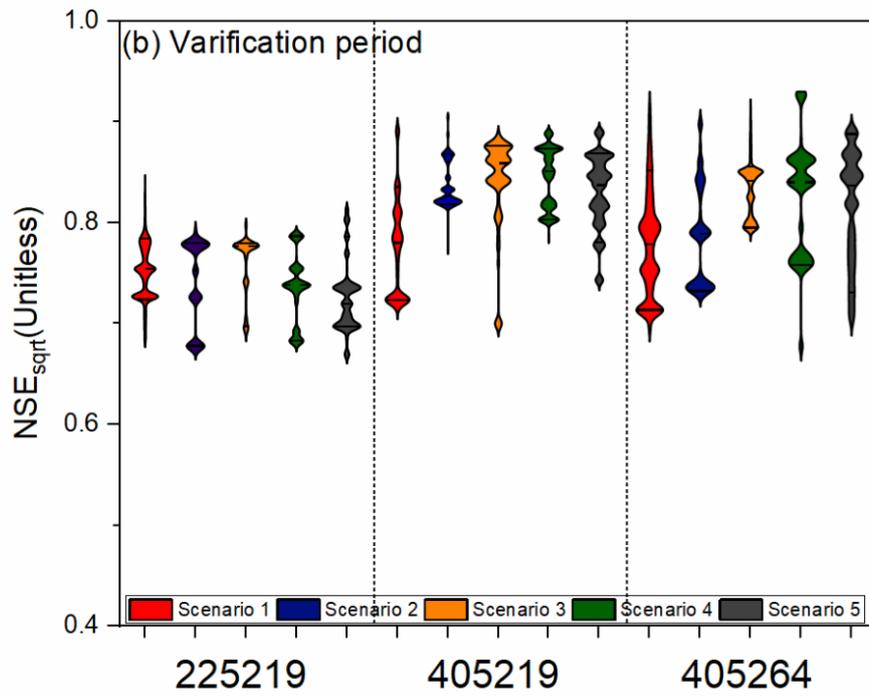


Fig. 6. Figure 6(b) NSE_{sqrt} for each of the five scenarios for each catchment during (a) the calibration period (dry period) and (b) the verification period (non-dry period).